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A neural network model of normal and abnormal learning and memory consolidation

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Dissertation

**A NEURAL NETWORK MODEL OF NORMAL AND ABNORMAL LEARNING
AND MEMORY CONSOLIDATION**

by

DANIEL JON FRANKLIN

B.A., Williams College, 1974
M.T.S., Harvard University, 1978
M.B.A., Boston University, 1992

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Approved by

First Reader

Stephen Grossberg, PhD
Wang Professor of Cognitive and Neural Systems, Professor of
Mathematics, Psychology, and Biomedical Engineering

Second Reader

Gail Carpenter, PhD
Professor of Cognitive and Neural Systems, and Mathematics

Third Reader

Arash Yazdanbakhsh, MD, PhD
Research Assistant Professor, Center for Computational
Neuroscience and Neural Technology and Department of
Psychological & Brain Sciences

In the blink of an eye—

Life, death, learning, and love!

DEDICATION

To my wife, Andrea,
who always supported the ladder,
and children, Virginia & Lisa,
who motivated me to climb it.

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This work would not have been possible without the sustained encouragement, guidance, and support provided to me by my mentor, and friend, Steve Grossberg. Through the many starts and stops of this project, Steve continued to have faith in me and work with me to extend and refine my thinking and communication skills. Though I did not always agree with his advice at first, I always trusted it. I thank Steve for his patience. Yes, it is time to celebrate!

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DANIEL JON FRANKLIN

Boston University Graduate School of Arts and Sciences, 2016

Major Professor: Stephen Grossberg, Wang Professor of Cognitive and Neural Systems,
Professor of Mathematics, Psychology, and Biomedical Engineering

ABSTRACT

The amygdala and hippocampus interact with thalamocortical systems to regulate cognitive-emotional learning, and lesions of amygdala, hippocampus, thalamus, and cortex have different effects depending on the phase of learning when they occur. In examining eyeblink conditioning data, several questions arise: Why is the hippocampus needed for trace conditioning where there is a temporal gap between the conditioned stimulus offset and the onset of the unconditioned stimulus, but not needed for delay conditioning where stimuli temporally overlap and co-terminate? Why do amygdala lesions made before or immediately after training decelerate conditioning while those made later have no impact on conditioned behavior? Why do thalamic lesions degrade trace conditioning more than delay conditioning? Why do hippocampal lesions degrade recent learning but not temporally remote learning? Why do cortical lesions degrade temporally remote learning, and cause amnesia, but not recent or post-lesion learning? How is temporally graded amnesia caused by ablation of medial prefrontal cortex? How are mechanisms of motivated attention and the emergent state of consciousness linked

during conditioning? How do neurotrophins, notably Brain Derived Neurotrophic Factor (BDNF), influence memory formation and consolidation?

A neural model, called *neurotrophic START*, or nSTART, proposes answers to these questions. The nSTART model synthesizes and extends key principles, mechanisms, and properties of three previously published brain models of normal behavior. These three models describe aspects of how the brain can learn to categorize objects and events in the world; how the brain can learn the emotional meanings of such events, notably rewarding and punishing events, through cognitive-emotional interactions; and how the brain can learn to adaptively time attention paid to motivationally important events, and when to respond to these events, in a context-appropriate manner. The model clarifies how hippocampal adaptive timing mechanisms and BDNF may bridge the gap between stimuli during trace conditioning and thereby allow thalamocortical and corticocortical learning to take place and be consolidated. The simulated data arise as emergent properties of several brain regions interacting together. The model overcomes problems of alternative memory models, notably models wherein memories that are initially stored in hippocampus move to the neocortex during consolidation.

PREFACE

Models of memory consolidation have been used for decades to explain challenging data about learning, memory, and consciousness. Experimental methods and analysis techniques supported by technological advances have resulted in three main models of memory consolidation: the standard unitary trace model, the multiple traces model, and the schemas model, a model that uses schemas, or mental models, to unite psychological constructs with neurobiology and thus account for accelerated top-down learning based on prior associations. The present work reinforces and expands the multiple traces and schema theories of memory consolidation by explaining and simulating a mechanistic model of conditioning that links learning and memory to resonant states of mind that occur during the experience of stimuli as well as during times with no external input.

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LIST OF ABBREVIATIONS

ART.....	Adaptive Resonance Theory
BDNF.....	Brain Derived Neurotrophic Factor
CogEM.....	C ognitive- E motional and M otor Learning model
CR.....	Conditioned Response
CS.....	Conditioned Stimulus
dART.....	Distributed ART
LTD.....	Long-Term Depression
LTM.....	Long-Term Memory
LTP.....	Long-Term Potentiation
MOTIVATOR.....	M atching O bjects T o I nternal V alues T riggers O ption R evaluations Model
NMR.....	Nictitating Membrane Response
nSTART.....	Neurotrophic START
START.....	Spectrally Timed Adaptive Resonance Theory
STM.....	Short-Term Memory
US.....	Unconditioned Stimulus
WTA.....	Winner-Take-All

CHAPTER 1. Introduction

1.1. Amygdala, Hippocampus, Cortex, and Thalamus in Delay and Trace Conditioning

The roles and interactions of amygdala, hippocampus, thalamus, and neocortex in cognitive and cognitive-emotional learning, memory, and consciousness have been extensively investigated through experimental and clinical studies (Berger & Thompson, 1978; Buchel, Clark, Manns, & Squire, 2001; Dolan, Armony, & Friston, 1999; Frankland & Bontempi, 2005; Kim, Clark, & Thompson, 1995; Lee & Kim, 2004; Mauk & Thompson 1987; Moustafa et al., 2013; Port, Romano, Steinmetz, Mikhail, & Patterson, 1986; Powell & Churchwell, 2002; Smith, 1968; Takehara, Kawahara, & Krino, 2003). This thesis develops a neural model aimed at providing a unified explanation of challenging data about how these brain regions interact during normal learning, and how lesions may cause specific learning and behavioral deficits, including amnesia. The model also proposes testable predictions to further test its explanations. The most relevant experiments use the paradigm of classical conditioning, notably delay conditioning and trace conditioning during the eyeblink conditioning task that is often used to explicate basic properties of associative learning. Earlier versions of this work were briefly presented in Franklin & Grossberg (2005, 2008).

Eyeblink conditioning has been extensively studied because it has disclosed behavioral, neurophysiological, and anatomical information about the learning and memory processes related to adaptively timed, conditioned responses to aversive stimuli, as measured by eyelid movements in mice (Chen et al., 1995), rats (Clark, Broadbent,

Zola, & Squire, 2002; Neufeld & Mintz, 2001; Schmajuk, Lam, & Christiansen, 1994), monkeys (Clark & Zola, 1998), and humans (Clark Manns, & Squire, 2001; Solomon, et al, 1990), and by the timing and amplitude of the nictitating membrane reflex (NMR) which involves a nictitating membrane that covers the eye like an eyelid in cats (Norman et al., 1974), rabbits (Berger & Thompson, 1978; Christian & Thompson, 1999; McLaughlin, Skaggs, Churchwell, & Powell, 2002; Port, Mikhail, & Patterson, 1985; Port et al., 1986; Powell & Churchill 2002; Powell, Skaggs, Churchwell, & McLaughlin, 2001; Solomon, et al, 1990), and other animals. Eyeblick/NMR conditioning data will herein be used to help formulate and answer basic questions about associative learning, adaptive timing, and memory consolidation.

Classical conditioning involves learning associations between objects or events. Eyeblick conditioning associates a neutral event, such as a tone or a light, called the *conditioned stimulus* (CS), with an emotionally-charged, reflex-inducing event, such as a puff of air to the eye or a shock to the periorbital area, called the *unconditioned stimulus* (US). *Delay conditioning* occurs when the stimulus events temporally overlap so that the subject learns to make a conditioned response (CR) in anticipation of the US (Figure 1). *Trace conditioning* involves a temporal gap between CS offset and US onset such that a CS-activated memory trace is required during the inter-stimulus interval (ISI) in order to establish an adaptively timed association between CS and US that leads to a successful CR (Pavlov, 1927).

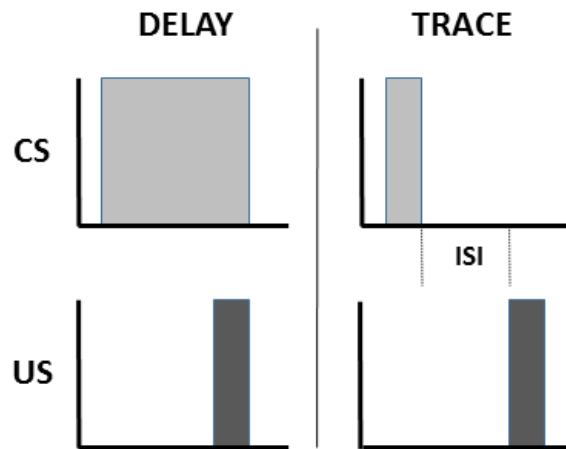


Figure 1. Delay and trace conditioning paradigms. Eyeblink conditioning associates a neutral event, called the conditioned stimulus (CS), with an emotionally-charged, reflex-inducing event, called the unconditioned stimulus (US). Delay conditioning occurs when the stimulus events temporally overlap. Trace conditioning involves a temporal gap between CS offset and US onset such that a CS-activated memory trace is required during the inter-stimulus interval (ISI) in order to establish an association between CS and US. After either normal delay and trace conditioning, with a range of stimulus durations and ISIs a conditioned response (CR) is performed in anticipation of the US.

Multiple brain areas are involved in eyeblink conditioning. Many of these regions, and their interactions, are simulated in the current neural model (Figure 2). Sensory input comes into the cortex, and the model, by way of the thalamus. Since the US is an aversive stimulus, the amygdala is involved (Buchel, Dolan, Armony, & Friston, 1999; Lee & Kim, 2004). The hippocampus plays a role in new learning, in general (Frankland & Bontempi, 2005; Kim, Clark, & Thompson, 1995; Takehara et al., 2003) and in adaptively timed learning, in particular (Buchel et al., 1999; Green & Woodruff-Pak, 2000; Kaneko & Thompson, 1997; Port et al., 1986; Smith, 1968). Prefrontal cortex plays an essential role in the consolidation of long-term memory (Frankland & Bontempi, 2005; Takehara, Kawahara, & Krino, 2003; Winocur, Moscovitch, & Bontempi, 2010). Lesions of amygdala, hippocampus, thalamus, and neocortex have different effects

depending on the phase of learning when they occur. In particular, the model clarifies why the hippocampus is needed for trace conditioning, but not delay conditioning (Buchel et al., 1999; Frankland & Bontempi, 2005; Green & Woodruff-Pak, 2000; Kaneko & Thompson, 1997; Kim, Clark, & Thompson, 1995; Port et al., 1986; Takehara, Kawahara, & Krino, 2003); why thalamic lesions retard the acquisition of trace conditioning (Powell & Churchwell, 2002), but have less of a statistically significant effect on delay conditioning (Buchanan & Thompson, 1990); why early but not late amygdala lesions degrade both delay conditioning (Lee & Kim, 2004) and trace conditioning (Buchel et al., 1999); why hippocampal lesions degrade recent but not temporally remote trace conditioning (Kim et al., 1995; Takehara et al., 2003); why in delay conditioning, such lesions typically have no negative impact on CR performance but this finding may vary with experimental preparation and CR success criteria (Berger, 1984; Chen et al., 1995; Lee & Kim, 2004; Port, 1985; Shors, 1992; Moustafa, et al., 2013); why cortical lesions degrade temporally remote but not recent trace conditioning, but have no impact on the acquisition of delay conditioning (Frankland & Bontempi, 2005; Kronforst-Collins & Disterhoft, 1998; McLaughlin et al., 2002; Takehara et al., 2003; see also, Oakley & Steele Russell, 1972; Yeo, Hardiman, Moore, & Steele Russell, 1984); how temporally graded amnesia may be caused by ablation of medial prefrontal cortex after memory consolidation (Simon, Knuckley, Churchwell, & Powell, 2005; Takehara et al., 2003; Weible, McEchron, & Disterhoft, 2000); how attention and consciousness are linked during delay and trace conditioning (Clark, Manns, & Squire, 2002; Clark & Squire, 1998); and how neurotrophins, notably Brain Derived

Neurotrophic Factor (BDNF), influence memory formation and consolidation (Tyler et al., 2002).

The thesis does not attempt to explain all aspects of memory consolidation, although its proposed explanations may help to do so in future studies. One reason for this is that the prefrontal cortex and hippocampus, which figure prominently in model explanations, carry out multiple functions (see Section 5.4). The model only attempts to explain how an interacting subset of these mechanisms contribute to conditioning and memory consolidation. Not considered, for example, are sequence-dependent learning, which depends on prefrontal working memories and list chunking dynamics (cf. compatible models for such processes in Grossberg & Kazerounian, 2016; Grossberg & Pearson, 2008; and Silver et al., 2011), or spatial navigation, which depends upon entorhinal grid cells and hippocampal place cells (cf. compatible models in Grossberg & Pilly, 2014; Pilly & Grossberg, 2012). In addition, the model does not attempt to simulate properties such as hippocampal replay, which require an analysis of sequence-dependent learning, including spatial navigation, for their consideration, or finer neurophysiological properties such as the role of sleep, sharp wave ripples, and spindles in memory consolidation (see Albouy, King, Maquet, & Doyon, 2013, for a review).

Data about brain activity during sleep provide further evidence about learning processes that support memory consolidation. These processes begin with awake experience and may continue during sleep where there are no external stimuli that support learning (Kali & Dayan, 2004; Wilson, 2002). The activity generated during waking in hippocampus is reproduced in sequence during rapid eye movement (REM)

sleep with the same time scale as the original experiences, lasting tens of seconds to minutes (Louie & Wilson, 2001), or is compressed during slow-wave sleep (Nádasdy et al. 1999). During sleep, slow waves appear to be initiated in hippocampal CA3 (Siapis & Wilson, 1998; Wilson & McNaughton, 1994), and hippocampal place cells tend to fire as though neuronal states were being played back in their previously experienced sequence as part of the memory consolidation process (Ji & Wilson, 2007; Qin, McNaughton, Skaggs, & Barnes, 1997; Skaggs & McNaughton, 1996; Steriade, 1999; Wilson & McNaughton, 1994). Relevant to the nSTART analysis are the facts that, during sleep, the interaction of hippocampal cells with cortex leads to neurotrophic expression (Hobson & Pace-Schott, 2002; Montaggio, et al, 2404), and that similar sequential, self-organizing ensembles that are based on experience may also exist in various areas of neocortex (Ji & Wilson, 2007; Maquet et al., 2000; cf. Deadwyler, West, & Robinson, 1981; Schoenbaum & Eichenbaum, 1995). With the nSTART analyses of neurotrophically-modulated memory consolidation as a function, these sleep- and sequence-dependent processes, which require substantial additional model development, can be more easily understood.

1.2. Unifying three basic competences.

The model reconciles three basic behavioral competences. Its explanatory power is illustrated by the fact that these basic competences are self-evident, but the above data properties are not. All three competences involve the brain's ability to *adaptively time* its learning processes in a task-appropriate manner.

First, the brain needs to pay attention quickly to salient events, both positive and negative. However, such a rapid attention shift to focus on a salient event creates the risk of prematurely responding to that event, or of prematurely resetting and shifting the attentional focus to a different event before the response to that event could be fully executed. As explained below, this fast motivated attention pathway includes the amygdala. These potential problems of a fast motivated attention shift are alleviated by the second and third competences.

Second, the brain needs to be able to adaptively time and maintain motivated attention on a salient event until an appropriate response is executed. The ability to maintain motivated attention for an adaptively timed interval on the salient event involves the hippocampus, notably its dentate-CA3 region (Berger, Clark & Thompson, 1980). Recent data have further developed this theme through the discovery of hippocampal "time cells" (Kraus et al., 2013; MacDonald et al., 2011).

Third, the brain needs to be able to adaptively time and execute an appropriate response to the salient event. The ability to execute an adaptively timed behavioral response always involves the cerebellum (Christian & Thompson, 2003; Fiala, Grossberg, & Bullock, 1996; Green & Woodruff-Pak, 2000; Ito, 1984). When the timing contingencies involve a relatively long trace conditioning ISI, or the onset of the US in delay conditioning is sufficiently delayed, then the hippocampus may also be required due to higher cognitive demand (Beylin, Gandhi, Wood, Talk, Matzel, & Shors, 2001).

How the brain may realize these three competences, along with data supporting these hypotheses, has been described in articles about the Spectrally Timed Adaptive

Resonance Theory (START) model of Grossberg & Merrill (1992, 1996). A variation of the START model in which several of its mechanisms are out of balance is called the Imbalanced START, or iSTART, model that has been used to describe possible neural mechanisms of autism (Grossberg & Seidman, 2006). START mechanisms have also been used to offer mechanistic explanations of various symptoms of schizophrenia (Grossberg, 2000b). The current *neurotrophic START*, or nSTART, model builds upon this foundation. The nSTART model further develops the START model to refine the anatomical interactions that are described in START, to clarify how adaptively timed learning and memory consolidation depend upon neurotrophins acting within several of these anatomical interactions, and to explain using this expanded model how various brain lesions to areas involved in eyeblink conditioning may cause abnormal learning and memory.

1.3. nSTART model of adaptively timed eyeblink conditioning.

Neural pathways that support the conditioned eye-blink response involve various hierarchical and parallel circuits (Thompson, 1988; Woodruff-Pak & Steinmetz, 2000a, 2000b). The nSTART macrocircuit (Figure 2) simulates key processes that exist within the wider network that supports the eyeblink response *in vivo* and highlights circuitry required for adaptively timed trace conditioning. Thalamus and sensory cortex are lumped into one sensory cortical representation for representational simplicity. However, the exposition of the model and its output pathways will require discussion of independent thalamocortical and corticocortical pathways. Different experimental manipulations affect brain regions like thalamus, cortex, amygdala, and hippocampus in

different ways. The nSTART model computer simulations illustrate these differences. In addition, it is important to explain how these several individual responses of different brain regions contribute to a final common path whose activity covaries with observed conditioned responses. Outputs from these brain regions meet directly or indirectly at the pontine nucleus, the final common bridge to the cerebellum which generates the CR (Freeman & Muckler, 2003; Kalmbach et al, 2009; Siegel et al., 2012; Woodruff-Pak & Disterhoft, 2007). Simulations of how the model pontine nucleus responds to the aggregate effect of all the other brain regions are thus also provided. The internal dynamics of the cerebellum are not, however, simulated in the nSTART model, but see Fiala, Grossberg, & Bullock (1996) for a detailed cerebellar learning model that simulates how Ca^{++} can modulate mGluR dynamics to adaptively time responses across long ISIs.

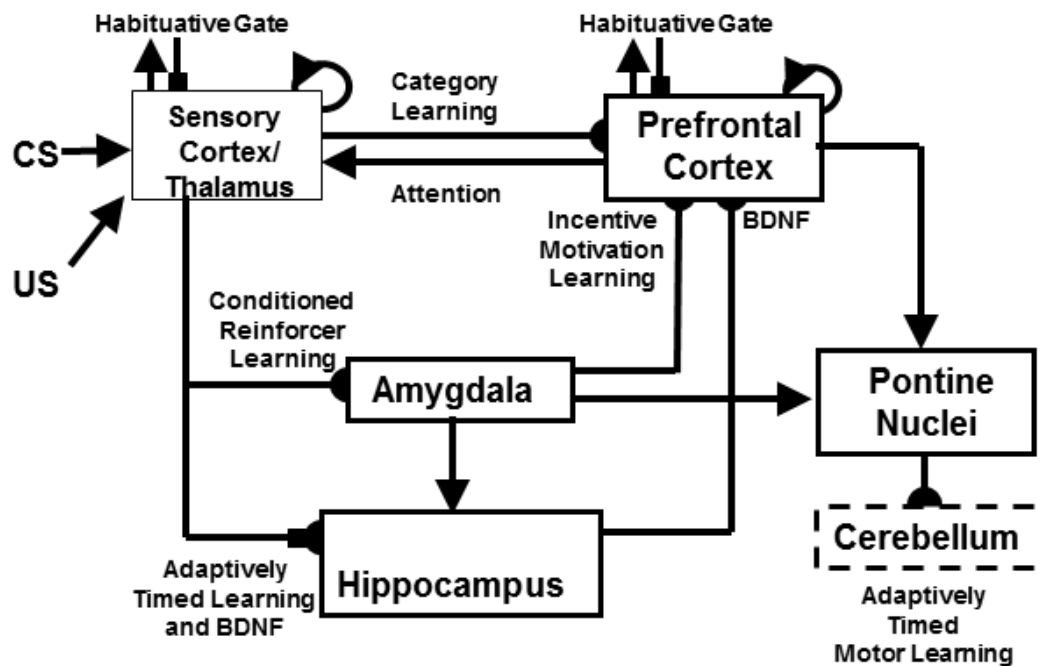


Figure 2. The neurotrophic START macrocircuit. The neurotrophic START, or nSTART, macrocircuit is formed from parallel and interconnected networks that support both delay and trace conditioning.

Connectivity between thalamus and sensory cortex includes pathways from the amygdala and hippocampus, as does connectivity between sensory cortex and prefrontal cortex, specifically orbitofrontal cortex. These circuits are homologous. Hence the current model lumps the thalamus and sensory cortex together and simulates only sensory cortical dynamics. Multiple types of learning and neurotrophic mechanisms of memory consolidation cooperate in these circuits to generate adaptively timed responses. Connections from sensory cortex to orbitofrontal cortex support category learning. Reciprocal connections from orbitofrontal cortex to sensory cortex support attention. Habituated transmitter gates modulate excitatory conductances at all processing stages. Connections from sensory cortex to amygdala connections support conditioned reinforcer learning. Connections from amygdala to orbitofrontal cortex support incentive motivation learning. Hippocampal adaptive timing and BDNF bridge temporal delays between CS offset and US onset during trace conditioning acquisition. BDNF also supports long-term memory consolidation within sensory cortex to hippocampal pathways and from hippocampal to orbitofrontal pathways. The pontine nuclei serve as a final common pathway for reading-out conditioned responses. Cerebellar dynamics are not simulated in nSTART. Key: arrowhead = excitatory synapse; hemidisc = adaptive weight; square = habituated transmitter gate; square followed by a hemidisc = habituated transmitter gate followed by an adaptive weight.

1.4. Normal and amnesic delay conditioning and trace conditioning.

The ability to associatively learn what subset of earlier events predicts, or causes, later consequences, and what event combinations are not predictive, is a critical survival competence in normal adaptive behavior. In this section, data are highlighted that describe the differences between the normal and abnormal acquisition and retention of associative learning relative to the specific role of interactions among the processing areas in nSTART's functional anatomy; notably, interactions between sensory cortex and thalamus, prefrontal cortex, amygdala, and hippocampus. See the Methods, Section 2, for an exposition of design principles and heuristic modeling concepts that go into the nSTART model; the Model Description, Section 3, for a non-technical exposition of the model processes and their interactions; the Results, Section 4, for model simulations of data; the Discussion, Section 5, for a general summary; and the Mathematical Equations and Parameters, Appendix A, for a complete summary of the model mechanisms.

Lesion data show that delay conditioning requires the cerebellum but does not need hippocampus to acquire an adaptively timed conditioned response. Studies of

hippocampal lesions in rats, rabbits and humans reveal that, if a lesion occurs before delay conditioning (Daum, Channon & Canavar, 1989; Ivkovich & Stanton, 2001; Schmaltz & Theios, 1972; Solomon & Moore, 1975; Weiskrantz & Warrington, 1979;), or any time after delay conditioning (Akase, Alkon & Disterhoft, 1989; Orr & Berger, 1985; Port et al., 1986), the subject can still acquire or retain a CR. Depending on the performance criteria, sometimes the acquisition is reported as facilitated (Berger, 1984; Chen, 1995; Lee & Kim, 2004; Port, 1985; Shors, 1992).

Lee & Kim (2004) presented EMG data showing that amygdala lesions in rats decelerated delay conditioning if made prior to training, but not if made post-training, while hippocampal lesions accelerated delay conditioning if made prior to training. They found a time-limited role of the amygdala similar to the time-limited role of the hippocampus: the amygdala is more active during early acquisition than later. In addition, they found that the amygdala without the hippocampus is not sufficient for trace conditioning. During fMRI studies of human trace conditioning, Buchel et al. (1999) also found decreases of amygdala responses over time. They cited other fMRI studies that found robust hippocampal activity in trace conditioning, but not delay conditioning, to underscore their hypothesis that, while amygdala may contribute to trace conditioning, the hippocampus is required. Chau & Galvez (2012) discussed the likelihood of the same time-limited involvement of amygdala in trace eyeblink conditioning.

Holland and Gallagher (1999) reviewed literature describing the role of the amygdala as either modulatory or required, depending on specific connections with other brain systems, for normal “functions often characterized as attention, reinforcement and

representation” (p. 66). Aggleton and Saunders (2000) described the amygdala in terms of four functional systems (accessory olfactory, main olfactory, autonomic, and frontotemporal). In the macaque monkey, 10 interconnected cytotoxic areas were defined within the amygdala, with 15 types of cortical inputs and 17 types of cortical projections, and 22 types of subcortical inputs from the amygdala and 15 types of subcortical projections to the amygdala (their Figures 1.2-1.7, pp. 4-9). Given this complexity, the data are mixed about whether amygdala is required for acquisition, or retention after consolidation, depending on the cause (cytotoxin, acid or electronic burning, cutting), target area, and degree of lesion, as well as the strength of the US, learning paradigm, and specific task (Blair, Sotres-Bayon, Moiya, & LeDoux, 2005; Cahill & McGaugh, 1990; Everitt, Cardinal, Hall, Parkinson, & Robbins, 2000; Kapp, Wilson, Pascoe, Supple, & Whalen, 1990; Killcross, Everitt, & Robbins, 1997; Lehmann, Treit, & Parent, 2000; Medina, Repa, Mauk & LeDoux, 2002; Neufeld & Mintz, 2001; Oswald. Maddox, Tisdale, & Powell, 2010; Vazdarjanova & McGaugh, 1998). In fact, "...aversive eyeblink conditioning...survives lesions of either the central or basolateral parts of the amygdala" (Lavond, 1993). Additionally, such lesions have been found not to prevent Pavlovian appetitive conditioning or other types of appetitively based learning (McGaugh, 2002, p.456).

These inconsistencies among the data may exist due to the contributions from multiple pathways that support emotion. For example, within the MOTIVATOR model extension of the CogEM model (see Section 2.3), hypothalamic and related internal homeostatic and drive circuits may function without amygdala (Draniak et al., 2008). The

nSTART model only incorporates an afferent cortical connection from the amygdala to represent incentive motivational learning signals. Within the cortex, however, the excitatory inputs from both amygdala and hippocampus are modulated by the strength of thalamocortical signals.

A clear pattern emerges from comparing various data that disclose essential functions of hippocampus, functions that are qualitatively simulated in nSTART. Hippocampus has been studied with regard to the acquisition of trace eye blink conditioning, and the adaptive timing of conditioned responses (Berger, Laham, & Thompson, 1980; Mauk & Ruiz, 1992; Schmaltz & Theios, 1972; Sears & Steinmetz, 1990; Woodruff-Pak, 1993; Woodruff-Pak & Disterhoft, 2007). If a hippocampal lesion or other system disruption occurs before trace conditioning acquisition (Ivkovich & Stanton, 2001; Kaneko & Thompson, 1997; Weiss & Thompson, 1991b; Woodruff-Pak, 2001), or shortly thereafter (Kim et al., 1995; Moyer, Deyo, & Disterhoft, 1990; Takehara et al., 2003), the CR is not obtained or retained. Trace conditioning is impaired by pre-acquisition hippocampal lesions created during laboratory experimentation on animals (Anagnostaras, Maren, & Fanselow, 1999; Berry & Thompson, 1979; Garrud et al., 1984; James, Hardiman, & Yeo, 1987; Kim et al., 1995; Orr & Berger, 1985; Schmajuk, Lam, & Christiansen, 1994; Schmaltz & Theios, 1972; Solomon & Moore, 1975), and in humans with amnesia (Clark & Squire, 1998; Gabrieli et al., 1995; McGlinchey-Berroth, Carrillo, Gabrieli, Brawn, & Disterhoft, 1997), Alzheimer's disease, or age-related deficits (Little, Lipsitt, & Rovee-Collier, 1984; Solomon et al., 1990; Weiss & Thompson, 1991a; Woodruff-Pak, 2001).

The data show that, during trace conditioning, there is successful post-acquisition performance of the CR only if the hippocampal lesion occurs after a critical period of hippocampal support of memory consolidation within neocortex (Kim et al., 1995; Takashima, et al., 2009; Takehara, et al., 2003). Data from *in vitro* cell preparations also support the time-limited role of hippocampus in new learning that is simulated in nSTART: activity in hippocampal CA1 and CA3 pyramidal neurons peaked 24 hours after conditioning was completed and decayed back to baseline within 14 days (Thompson, Moyer, & Disterhoft, 1996). The effect of early versus late hippocampal lesions is challenging to explain since no overt training occurs after conditioning during the period before hippocampal ablation.

After consolidation due to hippocampal involvement is accomplished, thalamocortical signals in conjunction with the cerebellum determine the timed execution of the CR during performance (Gabreil, Sparenborg, & Stolar, 1987; Sosina, 1992). Indeed, "...there are two memory circuitries for trace conditioning. One involves the hippocampus and the cerebellum and mediates recently acquired memory; the other involves the mPFC and the cerebellum and mediates remotely acquired memory" (Takehara, et al., 2003, p. 9904; see also Berger, Weikart, Basset & Orr, 1986; O'Reilly, et al., 2010). nSTART qualitatively models these data as follows: after the consolidation of memory, when there is no need for hippocampus, nSTART models the cortical connections to the pontine nuclei that serve to elicit conditioned responses by way of the cerebellum (Kalmbach, Chitwood, & Mauk, 2012; Woodruff-Pak & Disterhoft, 2007).

Based on the extent and timing of hippocampal damage, learning impairments range from needing more training trials than normal in order to learn successfully, through persistent response-timing difficulties, to the inability to learn and form new memories. The nSTART model explains the need for the hippocampus during trace conditioning in terms of how the hippocampus supports strengthening of partially conditioned thalamocortical and corticocortical connections during memory consolidation (see Figure 2). The hippocampus has this ability because it includes circuits that can bridge the temporal gaps between CS and US during trace conditioning, unlike the amygdala, and can learn to adaptively time these temporal gaps in its responses, as originally simulated in the START model (Grossberg & Merrill, 1992, 1996; Grossberg & Schmajuk, 1989). The current nSTART model extends this analysis using mechanisms of endogenous hippocampal activation and BDNF modulation (see Section 1.6) to explain the time-limited role of the hippocampus in terms of its support of the consolidation of new learning into long-term memories. This hypothesis is elaborated and contrasted with alternative models of memory consolidation in Section 5.2.

1.5. Conditioning and consciousness.

Several studies of humans have described a link between consciousness and conditioning. Early work interpreted conscious awareness as another class of conditioned responses (Grant, 1973; Hilgard, Campbell, & Sears, 1937; Kimble, 1962; McAllister & McAllister, 1958). More recently, it was found that, while amnesic patients with hippocampal damage acquired delay conditioning at a normal rate, they failed to acquire trace conditioning (Clark & Squire, 1998). These experimenters postulated that normal

humans acquire trace conditioning because they have intact declarative or episodic memory and, therefore, can demonstrate conscious knowledge of a temporal relationship between CS and US: “trace conditioning requires the acquisition and retention of conscious knowledge” (p. 79). They did not, however, discuss mechanisms underlying this ability, save mentioning that the neocortex probably represents temporal relationships between stimuli and “would require the hippocampus and related structures to work conjointly with the neocortex” (p.79).

Other studies have also demonstrated a link between consciousness and conditioning (Gabrieli et al., 1995; McGlinchey-Berroth, Brawn, & Disterhoft, 1999; McGlinchey-Berroth et al., 1997) and described an essential role for awareness in declarative learning, but no necessary role in non-declarative or procedural learning, as illustrated by experimental findings related to trace and delay conditioning, respectively (Manns, Clark, & Squire, 2000; Papka, Ivry, & Woodruff-Pak, 1997). For example, trace conditioning is facilitated by conscious awareness in normal control subjects while delay conditioning is not, whereas amnesics with bilateral hippocampal lesions perform at a success rate similar to unaware controls for both delay and trace conditioning (Clark, Manns, & Squire, 2001). Amnesics were found to be unaware of experimental contingencies, and poor performers on trace conditioning (Clark & Squire, 1998). Thus, the link between adaptive timing, attention, awareness, and consciousness has been experimentally established within the trace conditioning paradigm. The nSTART model traces the link between consciousness and conditioning to the role of hippocampus in supporting a sustained cognitive-emotional resonance that underlies motivated attention,

consolidation of long-term memory, core consciousness, and "the feeling of what happens" (Damasio, 1999).

1.6. BDNF in memory formation and consolidation.

Memory consolidation, a process that supports an enduring memory of new learning, has been extensively studied: (McGaugh, 2000, 2002; Mehta, 2007; Nadel & Bohbot, 2001; Takehara, Kawahara, & Krino, 2003; Squire & Alvez, 1995; Takashima, 2009; Thompson, Moyer, & Disterhoft, 1996; Tse et al., 2007; Tyler, et al. 2002). These data show time-limited involvement of the limbic system, and long-term involvement of neocortex. The question of what sort of process occurs during the period that actively strengthens memory, even when there is no explicit practice, has been linked to the action of neurotrophins (Zang, et al., 2007), especially Brain Derived Neurotrophic Factor, or BDNF, a complex class of proteins that have important effects on learning and memory (Heldt, Stanek, Chhatwal, & Ressler, 2007; Hu & Russek, 2008; Monteggia et al., 2004; Purves, 1988; Rattiner, Davis, & Ressler, 2005; Schuman, 1999; Thoenen, 1995; Tyler, Alonso, Bramham, & Pozzo-Miller, 2002). Postsynaptically, neurotrophins enhance responsiveness of target synapses (Kang & Schuman, 1995; Kohara, Kitamura, Morishima, & Tsumoto, 2001) and allow for quicker processing (Knipper et al., 1993; Lessman, 1998). Presynaptically, they act as retrograde messengers (Davis & Murphy, 1994; Ganguly, Koss, & Poo, 2000) coming from a target cell population back to excitatory source cells and increasing the flow of transmitter from the source cell population to generate a positive feedback loop between the source and the target cells (Schinder, Berninger, & Poo, 2000), as also occurs in some neural models of learning and

memory search; e.g., Carpenter & Grossberg (1990). BDNF has also been interpreted as an essential component of long-term potentiation (LTP) in normal cell processing (Chen, Kolbeck, Barde, Bonhoeffer, & Kossel, 1999; Korte et al., 1995; Phillips et al., 1990). The functional involvement of existing BDNF receptors is critical in early LTP (up to 1 hour) during the acquisition phase of learning the CR, whereas continued activation of the slowly decaying late phase LTP signal (3+ hours) requires new protein synthesis and gene expression. Rossato et al. (2009) have shown that hippocampal dopamine and the ventral tegmental area provide a temporally sensitive trigger for the expression of BDNF that is essential for long-term consolidation of memory related to reinforcement learning.

The BDNF response to a particular stimulus event may vary from microseconds (initial acquisition) to several days or weeks (long-term memory consolidation); thus, neurotrophins have a role whether the phase of learning is one of initial synaptic enhancement or long-term memory consolidation (Kang, Welcher, Shelton, & Schuman, 1997; Schuman, 1999; Singer, 1999). Furthermore, BDNF blockade shows that BDNF is essential for memory development at different phases of memory formation (Kang et al., 1997), and during all ages of an individual (Cabelli, Hohn, & Shatz, 1995; Tokuka, Saito, Yorifugi, Kishimoto, & Hisanaga, 2000). As nSTART qualitatively simulates, neurotrophins are thus required for both the initial acquisition of a memory, as well as for its ongoing maintenance as memory consolidates.

BDNF is heavily expressed in the hippocampus as well as in the neocortex, where neurotrophins figure largely in activity-dependent development and plasticity, not only to build new bridges as needed, but also to inhibit and dismantle old synaptic bridges. A

process of competition among axons during the development of nerve connections (Bonhoffer, 1996; Tucker, Meyer, & Barde, 2001; van Ooyen & Willshaw, 1999; see review in Tyler et al., 2002), exists both in young and mature animals (Phillips, Hains, Laramée, Rosenthal, & Winslow, 1990). BDNF also maintains cortical circuitry for long-term memory that may be shaped by various BDNF-independent factors during and after consolidation (Gorski, Zeiler, Tamowski, & Jones, 2003).

The nSTART model hypothesizes how BDNF may amplify and temporally extend activity-based signals within the hippocampus and the neocortex that facilitate endogenous strengthening of memory without further explicit learning. In particular, memory consolidation may be mechanistically achieved by means of a sustained cascade of BDNF expression beginning in the hippocampus and spreading to the cortex (Buzsáki & Chrobak, 2005; Cousens & Otto, 1998; Hobson & Pace-Schott, 2002; Monteggia, et al., 2004; Nádasdy, Hirase, Czurkó, Csicsvari, & Buzsáki, 1999; Smythe, Colom, & Bland, 1992; Staubli & Lynch, 1987; Vertes, Hoover, & Di Prisco, 2004), which is modeled in nSTART by the maintained activity level of hippocampal and cortical BDNF after conditioning trials end (see Figure 2).

Hippocampal bursting activity is not the only bursting activity that drives consolidation. Long-term activity-dependent consolidation of new learning is also supported by the synchronization of thalamocortical interactions in response to thalamic or cortical inputs (Llinas, Ribary, Joliot, & Wang, 1994; Steriade, 1999). Thalamic bursting neurons may lead to synaptic modifications in cortex, and cortex can in turn influence thalamic oscillations (Sherman & Guillery, 2003; Steriade, 1999).

Thalamocortical resonance has been described as a basis for temporal binding and consciousness in increasingly specific models over the years. These models simulate how specific and nonspecific thalamic nuclei interact with the reticular nucleus and multiple stages of laminar cortical circuitry (Buzsáki, Llinás, Singer, Berthoz, & Christen, 1994; Engel, Fries, & Singer, 2001; Grossberg, 1980, 2003, 2007; Grossberg & Versace, 2008; Pollen, 1999). nSTART qualitatively explains consolidation without including bursting phenomena, although oscillatory dynamics of this kind arise naturally in finer spiking versions of rate-based models such as nSTART (Grossberg & Versace, 2008; Palma, Grossberg, & Versace, 2012a, 2012b).

The nSTART model focuses on amygdala and hippocampal interactions with thalamus and neocortex during conditioning (Figure 2). The model proposes that the hippocampus supports thalamo-cortical and cortico-cortical category learning that becomes well established during memory consolidation through its endogenous (bursting) activity (Siapas, Lubenov, & Wilson, 2005; Sosina, 1993) that is supported by neurotrophin mediators (Destexhe, Contreras & Steriade, 1998). nSTART proposes that thalamo-cortical sustained activity is maintained through the combination of two mechanisms: the level of cortical BDNF activity, and the strength of the learned thalamo-cortical adaptive weights, or long-term memory (LTM) traces that were strengthened by the memory consolidation process. This proposal is consistent with trace conditioning data showing that, after consolidation, when the hippocampus is no longer required for performance of CRs, the medial prefrontal cortex takes on a critical role for performance of the CR in reaction to the associated thalamic sensory input. Here, the etiology of

retrograde amnesia is understood as a failure to retain memory, rather than by a failure of adaptive timing (Takehara et al., 2003)

CHAPTER 2. Methods

2.1. From CogEM to nSTART.

The nSTART model synthesizes and extends key principles, mechanisms, and properties of three previously published brain models of conditioning and behavior.

These three models describe aspects of:

(1) how the brain learns to categorize objects and events in the world (Carpenter & Grossberg, 1987, 1991, 1993; Grossberg, 1980, 1982b, 1984a, 1987, 1999b, 2013; Raizada & Grossberg, 2003); this is described within Adaptive Resonance Theory, or ART;

(2) how the brain learns the emotional meanings of such events through cognitive-emotional interactions, notably rewarding and punishing experiences, and how the brain determines which events are motivationally predictive, as during attentional blocking and unblocking (Dranias, Grossberg, & Bullock, 2008; Grossberg, 1971, 1972a, 1972b, 1980, 1982, 1984, 2000b; Grossberg, Bullock, & Dranias, 2008; Grossberg & Gutowski, 1987; Grossberg & Levine, 1987; Grossberg & Schmajuk, 1987); this is described within the Cognitive-Emotional-Motor, or CogEM, model; and

(3) how the brain learns to adaptively time the attention that is paid to motivationally important events, and when to respond to these events, in a context-appropriate manner (Fiala, Grossberg, & Bullock, 1996; Grossberg & Merrill, 1992, 1996; Grossberg & Paine, 2000; Grossberg & Schmajuk, 1989); this is described within the START model.

All three component models have been mathematically and computationally characterized elsewhere in order to explain behavioral and brain data about normal and abnormal behaviors. The principles and mechanisms that these models employ have thus been independently validated through their ability to explain a wide range of data. nSTART builds on this foundation to explain data about conditioning and memory consolidation, as it is affected by early and late amygdala, hippocampal, and cortical lesions, as well as BDNF expression in hippocampus and cortex. The exposition in this section heuristically states the main modeling concepts and mechanisms before building upon them to mathematically realize the current model advances and synthesis.

The simulated data properties emerge from interactions of several brain regions whose processes evolve on multiple time scales, interacting in multiple nonlinear feedback loops. In order to simulate these data, the model incorporates only those network interactions that are rate-limiting in generating the targeted data. More detailed models of the relevant brain regions, that are consistent with the model interactions simulated herein, are described below, and provide a guide to future studies aimed at incorporating a broader range of functional competences.

2.2. Adaptive Resonance Theory.

The first model upon which nSTART builds is called Adaptive Resonance Theory, or ART. ART is reviewed because a key process in nSTART is a form of category learning, and also because nSTART simulates a cognitive-emotional resonance that is essential for explaining its targeted data. ART proposes how the brain can rapidly learn to attend, recognize, and predict new objects and events without catastrophically

forgetting memories of previously learned objects and events. This is accomplished through an attentive matching process between the feature patterns that are created by stimulus-driven bottom-up adaptive filters, and learned top-down expectations (Figure 3). The top-down expectations, acting by themselves, can also prime the brain to anticipate future bottom-up feature patterns with which they will be matched.

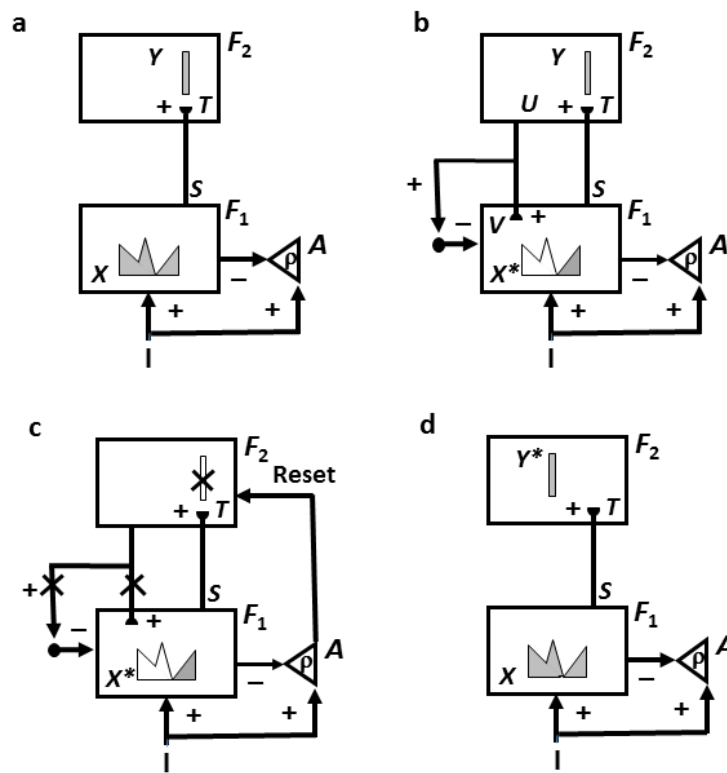


Figure 3. The ART1 memory search and learning cycle. ART searches for and learns a new recognition category using cycles of match-induced resonance and mismatch-induced reset. Active patterns are shaded gray; inhibited patterns are not shaded. (a) Input pattern I is instated across feature detectors at level F_1 as an activity pattern X , at the same time that it generates excitatory signals to the orienting system A with a gain ρ that is called the *vigilance* parameter. Activity pattern X generates inhibitory signals to the orienting system A as it generates a bottom-up input pattern S to the category level F_2 . A dynamic balance within A between excitatory inputs from I and inhibitory inputs from S keeps S quiet. The bottom-up signals in S are multiplied by learned adaptive weights to form the input pattern T to F_2 . The inputs T are contrast-enhanced and normalized within F_2 by recurrent lateral inhibitory signals that obey the membrane equations of neurophysiology, otherwise called shunting interactions. In a winner-take-all competition, selection and activation is reserved for a small number of cells within F_2 that receive the largest inputs. The chosen cells represent the category Y that codes for the feature pattern at F_1 . (b) The category activity Y generates top-down signals U that are multiplied by adaptive weights to form a prototype, or critical feature pattern, V

that encodes the expectation that the active F_2 category has learned for what feature pattern to expect at F_1 . This top-down expectation input V is added at F_1 cells. If V mismatches I at F_1 , then a new STM activity pattern X^* (gray area), is selected at cells where the patterns match well enough. In other words, X^* is active at I features that are confirmed by V . Mismatched features (white area) are inhibited. When X changes to X^* , total inhibition decreases from F_1 to A . (c) If inhibition decreases sufficiently, A releases a nonspecific arousal burst to F_2 ; that is, “novel events are arousing”. Within the orienting system A , the vigilance parameter ρ (represented in a triangle) determines how bad a match will be tolerated before a burst of nonspecific arousal is triggered. This arousal burst triggers a memory search for a better-matching winner-take-all category, as follows: Arousal resets F_2 by inhibiting Y . (d) After Y is inhibited, X is reinstated and Y stays inhibited as X activates a different category, that is represented by a different winner-take-all activity pattern Y^* , at F_2 . Search continues until a better matching, or novel, category is selected. When search ends, an attentive resonance triggers learning of the attended data in adaptive weights within both the bottom-up and top-down pathways. As learning stabilizes, inputs I can activate their globally best-matching categories directly through the adaptive filter, without activating the orienting system. [Adapted with permission from Carpenter and Grossberg (1987).]

In nSTART, it is assumed that each CS and US is familiar, and has already undergone object category learning before the current simulations begin. The CS and US inputs to the sensory cortex in the nSTART model macrocircuit are assumed to be processed as learned categories (Figure 2). nSTART models a second-stage of category learning between sensory cortex and orbitofrontal cortex. In the brain, this stage goes from an object category to an object-value category. The learning in this pathway embodies a simplified form of category learning. In general, each object category can get associated with more than one object-value category, so can learn to generate different responses when different value categories are active. These adaptive connections are thus one-to-many. Conceptually, the two stages of learning, at the object category stage, and the object-value category stage, can be interpreted as a coordinated category learning process through which the prefrontal cortex, notably the orbitofrontal cortex, categorizes objects and their motivational significance (Barbas, 1995, 2007; Freedman, Riesenhuber, Poggio, & Miller, 2002; Meyers, et al., 2008; Rolls, 1998, 2000). nSTART simulates such conditioning with only a single drive, and one-to-one connections, so that

strengthening of the connection from object category to object-value category represents a simplified form of this category learning process. Distributed ART, or dART, (Carpenter, 1994, 1997) shows how ART can be generalized to learn distributed object categories.

As in other ART models, a top-down expectation pathway also exists from orbitofrontal cortex to sensory cortex. It provides top-down attentive modulation of sensory cortical activity, and is part of the cortico-cortico-amygdalar-hippocampal resonance that develops in the model during learning. This *cognitive-emotional resonance*, which plays a key role in the current model and its simulations, as well as its precursors in the START and iSTART models, is the main reason that nSTART is considered to be part of the family of ART models. Indeed, Grossberg (2016) summarizes an emerging classification of the brain resonances that support conscious seeing, hearing, knowing, and feeling that includes this cognitive-emotional resonance. nSTART explains how this cognitive-emotional resonance is sustained through time by adaptively-timed hippocampal feedback signals (Figure 2). This hippocampal feedback plays a critical role in the model's explanation of data about memory consolidation, and its ability to explain how the brain bridges the temporal gap between stimuli that occurs in experimental paradigms like trace conditioning. Finally, the role of the hippocampus in sustaining the cognitive-emotional resonances helps to explain the experimentally reported link between conditioning and consciousness (Clark & Squire, 1998).

In a complete ART model, when a sufficiently good match occurs between the bottom-up input pattern and the top-down expectation, the system locks into a resonant

state that focuses attention on the matched features and drives learning to incorporate them into the learned category; hence the term *adaptive* resonance. ART also predicts that *all conscious states are resonant states*, and the Grossberg (2016) classification of resonances contributes to clarifying their diverse functions throughout the brain. Such an adaptive resonance is one of the key mechanisms whereby ART ensures that memories are dynamically buffered against catastrophic forgetting. In addition to the attentive resonant state itself, a hypothesis testing, or memory search, process in response to unexpected events helps to discover predictive recognition categories in response to unexpected events. This hypothesis testing cycle is also not incorporated into nSTART, but is compatible with the nSTART mechanisms that are simulated. These mechanisms are summarized here for completeness.

One critical mechanism that is included is the matching of bottom-up input patterns by learned top-down expectations. As noted above, a simplified form of this matching process is included in nSTART in order to explain the cognitive-emotional resonances that support memory consolidation and the link between conditioning and consciousness. Hypothesis testing, or memory search, is not simulated because it is assumed that, after object category learning of CS and US inputs is complete, unexpected events are minimized in the kinds of highly controlled delay and trace conditioning experiments that are the focus of the current study.

Another mechanism, also not included in nSTART, regulates how coarse or fine matches need to be to elicit a resonance. The degree of match between bottom-up and top-down signal patterns that is required for resonance, sustained attention, and learning

to occur is set by a *vigilance* parameter (Carpenter & Grossberg, 1987) (see ρ in Figure 3a). Vigilance may be increased by predictive errors, and controls whether a particular learned category will represent concrete information, such as a particular view of a particular face, or abstract information, such as the fact that everyone has a face. Low vigilance allows the learning of general and abstract recognition categories, whereas high vigilance forces the learning of specific and concrete categories. Given that the inputs to the nSTART model are just simple CS and US stimuli, the current simulations do not need to vary the degree of abstractness of the categories to be learned, so vigilance control has been omitted for simplicity.

A big enough mismatch designates that the selected category does not represent the input data well enough, and drives a memory search, or hypothesis testing, for a category that can better represent the input data. In a more complete nSTART model, hypothesis testing would enable the learning and stable memory of large numbers of thalamo-cortical and cortico-cortical recognition categories. Such a hypothesis-testing process includes a novelty-sensitive orienting system, which is predicted to include both the nonspecific thalamus and the hippocampus (Figure 3c; Carpenter & Grossberg, 1993; Grossberg, 2013; Grossberg & Versace, 2008). In nSTART, the model hippocampus includes the crucial process of adaptively timed learning that can bridge temporal gaps of hundreds of milliseconds to support trace conditioning and memory consolidation. In a more general nSTART model that is capable of self-stabilizing its learned memories, hippocampus would also be involved in the memory search process.

In an ART model that includes memory search, when a mismatch occurs, the orienting system is activated and generates nonspecific arousal signals back to the attentional system that carries out the category learning. These arousal signals rapidly reset the active recognition categories that have been reading out the poorly matching top-down expectations (Figure 3c). The cause of the mismatch is hereby removed, thereby freeing the bottom-up filter to activate a different recognition category (Figure 3d). This cycle of mismatch, arousal, and reset can repeat, thereby initiating a memory search, or hypothesis testing cycle, for a better-matching category. If no adequate match with a recognition category exists, say because the bottom-up input represents an unfamiliar experience, then the search process automatically activates an as yet uncommitted population of cells, with which to learn a new recognition category to represent the novel information.

All the learning and search processes that ART predicted have received support from behavioral, ERP, anatomical, neurophysiological, and/or neuropharmacological data, which are reviewed in the ART articles listed above. See, in particular, Grossberg (2013). Indeed, the role of hippocampus in novelty detection has been known for many years (Deadwyler, West, & Lynch, 1979; Deadwyler et al., 1981; Vinogradova, 1975). In particular, the hippocampal CA1 and CA3 regions have been shown to be involved in a process of comparison between a prior conditioned stimulus and a current stimulus by rats in a non-spatial auditory task, the continuous non-matching-to-sample task (Sakurai, 1990). During performance of the task, single unit activity was recorded from several areas: CA1 and CA3, dentate gyrus (DG), entorhinal cortex, subicular complex, motor

cortex (MC), prefrontal cortex and dorsomedial thalamus. Go and No-Go responses indicated, respectively, whether the current tone was perceived as the same as (match) or different from (nonmatch) the preceding tone. Since about half of the units from the MC, CA1, CA3, and DG had increments of activity immediately prior to a Go response, these regions were implicated in motor or decisional aspects of making a match response. On non-match trials, units were also found in CA1 and CA3 with activity correlated to a correct No-Go response. Corroborating the function of the hippocampus in recognition memory, but not in storing the memories themselves, Otto & Eichenbaum (1992) reported that CA1 cells compare cortical representations of current perceptual processes to previous representations stored in parahippocampal and neocortical structures to detect mismatch in an odor-guided task. They noted that “the hippocampus maintains neither active nor passive memory representations” (p. 332).

Several articles have proposed finer anatomical and neuropharmacological details about how vigilance control may be achieved. Grossberg & Versace (2008) have proposed how the nonspecific thalamus can be activated by novel sensory events and can thereby trigger hypothesis testing. In their Synchronous Matching ART (SMART) model, a predictive error can lead to a mismatch within the nucleus basalis of Meynert, which releases acetylcholine broadly in neocortex, leading to an increase in vigilance and a memory search for a better matching category. Palma, Grossberg, & Versace (2013a, 2013b) further model how acetylcholine-modulated processes work, and explain a wide range of data that support basic properties of vigilance control by using their modeling synthesis.

2.3. CogEM and MOTIVATOR models.

Recognition categories can be activated when objects are experienced, but do not reflect the emotional or motivational value of these objects. Such a recognition category can, however, be associated through reinforcement learning with one or more drive representations, which are brain sites that represent internal drive states and emotions. Activation of a drive representation by a recognition category can trigger emotional reactions and incentive motivational feedback to recognition categories, thereby amplifying valued recognition categories with motivated attention as part of a cognitive-emotional resonance between inferotemporal cortex, amygdala, and orbitofrontal cortex. When a recognition category is chosen in this way, it can trigger choice and release of actions that realize valued goals in a context-sensitive way.

Such internal drive states and motivational decisions are incorporated into nSTART using mechanisms from the second model, called the Cognitive-Emotional-Motor, or CogEM, model. CogEM simulates the learning of cognitive-emotional associations, notably associations that link external objects and events in the world to internal feelings and emotions that give these objects and events value (Figure 3a and 3b). These emotions also activate the motivational pathways that energize actions aimed at acquiring or manipulating objects or events to satisfy them.

The CogEM model clarifies interactions between two types of homologous circuits: one circuit includes interactions between thalamus, sensory cortex, and amygdala; the other circuit includes interactions between sensory cortex, orbitofrontal cortex, and amygdala. The nSTART model (Figure 2) simulates cortico-cortico-

amygdalar interactions. At the present level of simplification, the same activation and learning dynamics could also simulate interactions between thalamus, sensory cortices, and the amygdala. In particular, the CogEM model proposes how emotional centers of the brain, such as the amygdala, interact with sensory and prefrontal cortices—notably orbitofrontal cortex—to generate affective states, attend to motivationally salient sensory events, and elicit motivated behaviors. Neurophysiological data provide increasing support for the predicted role of interactions between amygdala and orbitofrontal cortex in focusing motivated attention on cell populations that can select learned responses which have previously succeeded in acquiring valued goal objects (Baxter et al., 2000; Rolls, 1998, 2000; Schoenbaum, Setlow, Saddoris, & Gallagher, 2003).

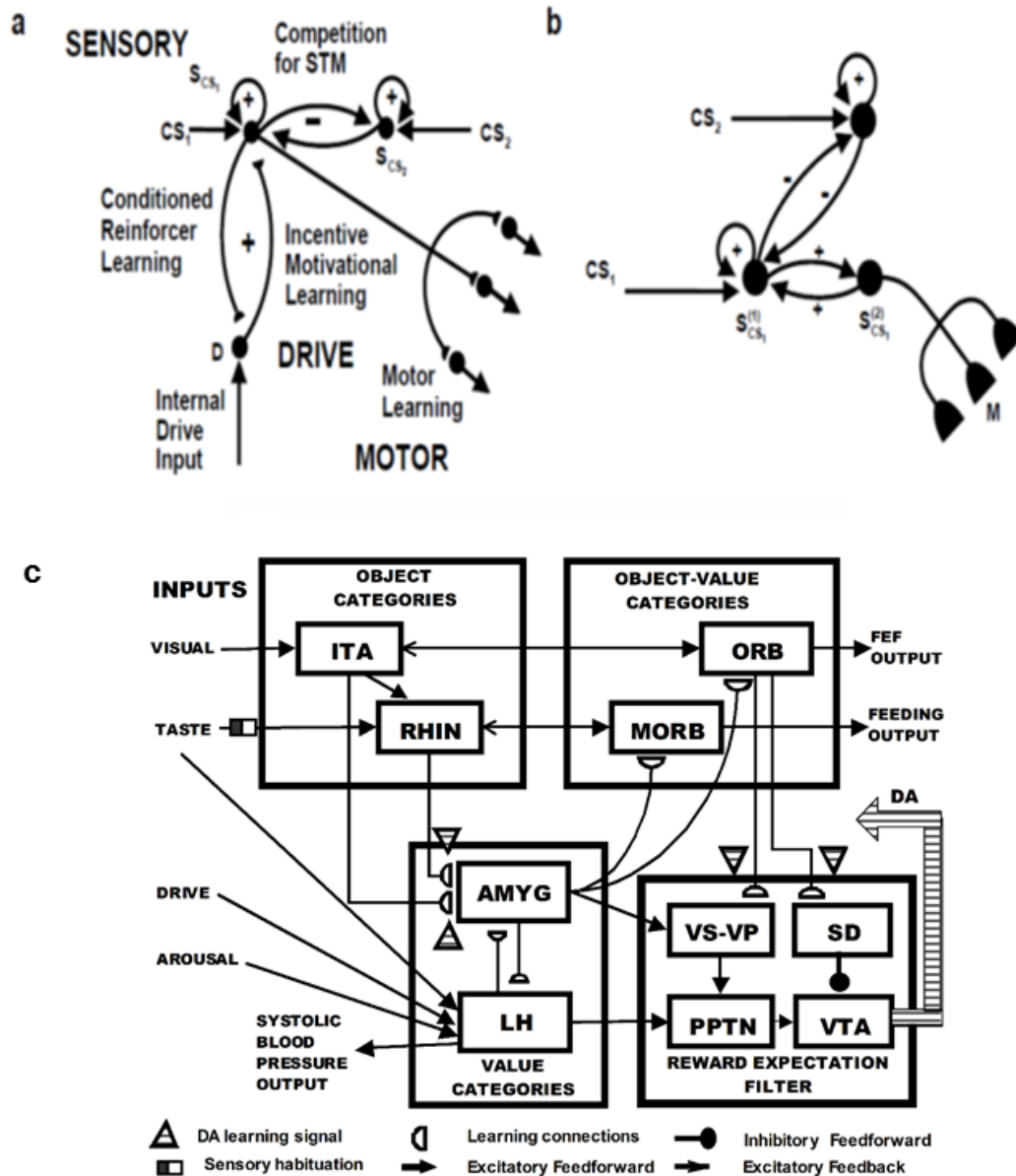


Figure 4. Cognitive-Emotional-Motor (CogEM) Models. (a) The simplest Cognitive-Emotional-Motor (CogEM) model: Three types of interacting representations (sensory, S; drive, D; and motor, M) that control three types of learning (conditioned reinforcer, incentive motivational, and motor) help to explain many reinforcement learning data. (b) In order to work well, a sensory representation S must have (at least) two successive stages, $S^{(1)}$ and $S^{(2)}$, so that sensory events cannot release actions that are motivationally inappropriate. The two successive stages of a sensory representation S are interpreted to be in the appropriate sensory cortex (corresponds to $S^{(1)}$) and the prefrontal cortex, notably the orbitofrontal cortex (corresponds to $S^{(2)}$). As indicated in Figure 4a, the prefrontal stage requires motivational support from a drive representation D such as amygdala, to be fully effective, in the form of feedback from the incentive

motivational learning pathway. Amygdala inputs to prefrontal cortex cause feedback from prefrontal cortex to sensory cortex that selectively amplifies and focuses attention upon motivationally relevant sensory events, and thereby “attentionally blocks” irrelevant cues. [Reprinted with permission from Grossberg and Seidman (2006).] (c) The amygdala and basal ganglia work together, embodying complementary functions, to provide motivational support, focus attention, and release contextually appropriate actions to achieve valued goals. For example, the basal ganglia substantia nigra pars compacta (SNc) releases Now Print learning signals in response to unexpected rewards or punishments, whereas the amygdala generates incentive motivational signals that support the attainment of expected valued goal objects. The MOTIVATOR model circuit diagram shows cognitive-emotional interactions between higher-order sensory cortices that support object categories and an evaluative neuraxis composed of the hypothalamus, amygdala, basal ganglia, and orbitofrontal cortex that supports object-value categories. [Reprinted with permission from Dranias et al. (2008).]

In ART, resonant states can develop within sensory and cognitive feedback loops.

Resonance can also occur within CogEM circuits between sensory and cognitive representations of the external world and emotional representations of what is valued by the individual. Activating the (sensory cortex)-(amygdala)-(prefrontal cortex) feedback loop between cognitive and emotional centers is predicted to generate a cognitive-emotional resonance that can support conscious awareness of events happening in the world and how we feel about them. This resonance tends to focus attention selectively upon objects and events that promise to satisfy emotional needs. Such a resonance, when it is temporally extended to also include hippocampus, as described below, helps to explain how trace conditioning occurs, as well as the link between conditioning and consciousness that has been experimentally reported.

Figures 4a and 4b summarize the CogEM hypothesis that (at least) three types of internal representation interact during classical conditioning and other reinforcement learning paradigms: sensory cortical representations *S*, drive representations *D*, and motor representations *M*. These representations, and the learning that they support, are incorporated into the nSTART circuit (Figure 2).

Sensory representations S temporarily store internal representations of sensory events in short-term and working memory. *Drive representations* D are sites where reinforcing and homeostatic, or drive, cues converge to activate emotional responses. *Motor representations* M control the read-out of actions. In particular, the S representations are thalamo-cortical or cortico-cortical representations of external events, including the object recognition categories that are learned by inferotemporal and prefrontal cortical interactions (Desimone, 1991; Gochin, Miller, Gross, & Gerstein, 1991; Harries & Perrett, 1991; Mishkin, Ungerleider, & Macko, 1983; Ungerleider & Mishkin, 1982), and that are modeled by ART. Sensory representations temporarily store internal representations of sensory events, such as conditioned stimuli (CS) and unconditioned stimuli (US), in short-term memory via recurrent on-center off-surround networks that tend to conserve their total activity while they contrast-normalize, contrast-enhance, and store their input patterns in short-term memory (Figures 4a and 4b).

The D representations include hypothalamic and amygdala circuits (Figures 2 4 and 5) at which reinforcing and homeostatic, or drive, cues converge to generate emotional reactions and motivational decisions (Aggleton, 1993; Bower, 1981; Davis, 1994; Gloor et al., 1982; Halgren, Walter, Cherlow, & Crandall, 1978; LeDoux, 1993). The M representations include cortical and cerebellar circuits that control discrete adaptive responses (Evarts, 1973; Ito, 1984; Kalaska, Cohen, Hyde, & Prud'homme, 1989; Thompson, 1988). More complete models of the internal structure of these several types of representations have been presented elsewhere (e.g., Brown, Bullock, & Grossberg, 2004; Bullock, Cisek, & Grossberg, 1998; Carpenter & Grossberg, 1991;

Contreras-Vidal, Grossberg, & Bullock, 1997; Dranias, Grossberg, & Bullock, 2008; Fiala, Grossberg, & Bullock, 1996; Gnadt & Grossberg, 2008; Grossberg, 1987; Grossberg, Bullock & Dranias, 2008; Grossberg & Merrill, 1996; Grossberg & Schmajuk, 1987; Raizada & Grossberg, 2003), and can be incorporated into future elaborations of nSTART without undermining any of the current model's conclusions.

nSTART does not incorporate the basal ganglia to simulate its targeted data, even though the basal ganglia and amygdala work together to provide motivational support, focus attention, and release contextually appropriate actions to achieve valued goals (Flores & Diserhoft, 2009). The MOTIVATOR model (Dranias et al., 2008; Grossberg et al., 2008) begins to explain how this interaction happens (Figure 4c), notably how the amygdala and basal ganglia may play complementary roles during cognitive-emotional learning and motivated goal-oriented behaviors. MOTIVATOR describes cognitive-emotional interactions between higher-order sensory cortices and an evaluative neuraxis composed of the hypothalamus, amygdala, basal ganglia, and orbitofrontal cortex. Given a conditioned stimulus (CS), the model amygdala and lateral hypothalamus interact to calculate the expected current value of the subjective outcome that the CS predicts, constrained by the current state of deprivation or satiation. As in the CogEM model, the amygdala relays the expected value information to orbitofrontal cells that receive inputs from anterior inferotemporal cells, and medial orbitofrontal cells that receive inputs from rhinal cortex. The activations of these orbitofrontal cells code the subjective values of objects. These values guide behavioral choices.

The model basal ganglia detect errors in CS-specific predictions of the value and timing of rewards. Excitatory inputs from the pedunculopontine nucleus interact with timed inhibitory inputs from model striosomes in the ventral striatum to regulate dopamine burst and dip responses from cells in the substantia nigra pars compacta and ventral tegmental area. Learning in cortical and striatal regions is strongly modulated by dopamine. The MOTIVATOR model is used to address tasks that examine food-specific satiety, Pavlovian conditioning, reinforcer devaluation, and simultaneous visual discrimination. Model simulations successfully reproduce discharge dynamics of known cell types, including signals that predict saccadic reaction times and CS-dependent changes in systolic blood pressure. In the nSTART model, these basal ganglia interactions are not needed to simulate the targeted data, hence will not be further discussed.

Even without basal ganglia dynamics, the CogEM model has successfully learned to control motivated behaviors in mobile robots (e.g., Baloch & Waxman, 1991; Chang & Gaudiano, 1998; Gaudiano & Chang, 1997; Gaudiano, Zalama, Chang, & Lopez-Coronado, 1996).

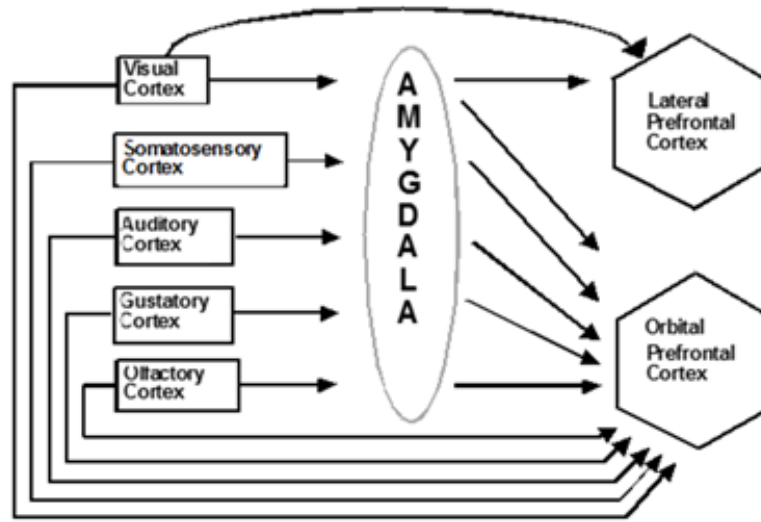


Figure 5. Orbital prefrontal cortex receives multiple projections. Orbital prefrontal cortex receives projections from sensory cortices (visual, somatosensory, auditory, gustatory, and olfactory) and from the amygdala, which also receives inputs from the same sensory cortices. The amygdala, in turn, projects to the orbital prefrontal cortex. These anatomical stages correspond to the model CogEM stages in Figure 4b. [Reprinted with permission from Barbas (1995).]

Three types of learning take place among the CogEM sensory, drive, and motor representations (Figure 4a). *Conditioned reinforcer learning* enables sensory events to activate emotional reactions at drive representations. *Incentive motivational learning* enables emotions to generate a motivational set that biases the system to process cognitive information consistent with that emotion. *Motor learning* allows sensory and cognitive representations to generate actions. nSTART simulates both conditioned reinforcer learning, from thalamus to amygdala, or from sensory cortex to amygdala, as well as incentive motivational learning, from amygdala to sensory cortex, or from amygdala, to orbitofrontal cortex (Figure 2). Instead of explicitly modeling motor learning circuits in the cerebellum, nSTART uses CR cortical activation in addition to the amygdala as sources of input to the pontine nucleus as an indicator of the timing and

strength of conditioned motor outputs (Freeman & Muckler, 2003; Kalmbach et al, 2009; Siegel et al., 2012; Woodruff-Pak & Disterhoft, 2007).

During classical conditioning, a CS activates its sensory representation S before the drive representation D is activated by an unconditioned stimulus (US), or other previously conditioned reinforcer CSs. If it is appropriately timed, such pairing causes learning at the adaptive weights within the $S \rightarrow D$ pathway. The ability of the CS to subsequently activate D via this learned pathway is one of its key properties as a conditioned reinforcer. As these $S \rightarrow D$ associations are being formed, incentive motivational learning within the $D \rightarrow S$ incentive motivational pathway also occurs, due to the same pairing of CS and US. Incentive motivational learning enables an activated drive representation D to prime, or modulate, the sensory representations S of all cues, including the CSs, that have consistently been correlated with it. That is how activating D generates a “motivational set”: it primes all of the sensory and cognitive representations that have been associated with that drive in the past. These incentive motivational signals are a type of motivationally-biased attention. The $S \rightarrow M$ motor, or habit, learning enables the sensorimotor maps, vectors, and gains that are involved in sensory-motor control to be adaptively calibrated, thereby enabling a CS to read-out correctly calibrated movements as a CR.

Taken together, these processes control aspects of the learning and recognition of sensory and cognitive memories, which are often classified as part of the declarative memory system (Mishkin, 1982, 1993; Squire & Cohen, 1984); and the performance of

learned motor skills, which are often classified as part of the procedural memory system (Gilbert & Thatch, 1977; Ito, 1984; Thompson, 1988).

Once both conditioned reinforcer and incentive motivational learning have taken place, a CS can activate a (sensory cortex)-(amygdala)-(orbitofrontal cortex)-(sensory cortex) feedback circuit (Figures 2 and 4a). This circuit supports a cognitive-emotional resonance that leads to core consciousness and "the feeling of what happens" (Damasio, 1999) while it enables the brain to rapidly focus motivated attention on motivationally salient objects and events. This is the first behavioral competence that was mentioned above in Section 1.1. This feedback circuit could also, however, without further processing, immediately activate motor responses, thereby leading to premature responding in many situations.

We show below that this amygdala-based process is effective during delay conditioning, where the CS and US overlap in time, but not during trace conditioning, where the CS terminates before the US begins, at least not without the benefit of the adaptively timed learning mechanisms that are described in the next section. Thus, although the CogEM model can realize the first behavioral competence that is summarized above, it cannot realize the second and third competences, which involve bridging temporal gaps between CS, US, and conditioned responses (see Section 2.1). Mechanisms that realize the second and third behavioral competences enable the brain to learn during trace conditioning.

It is also important to acknowledge that, as reviewed in Section 1.4, the amygdala may have a time-limited role during aversive conditioning (Lee & Kim, 2004). As the

association of eyeblink CS-US becomes more consolidated through the strengthening of direct thalamo-cortical and cortico-cortical learned associations, the role of amygdala may become less critical.

2.4. Spectral Timing model and hippocampal time cells.

The third model, called the Spectral Timing model, clarifies how the brain learns adaptively timed responses in order to acquire rewards and other goal objects that are delayed in time, as occurs during trace conditioning. Spectral timing enables the model to bridge an interstimulus interval (ISI), or temporal gap, of hundreds of milliseconds, or even seconds, between the CS offset and US onset. This learning mechanism has been called *spectral timing* because a “spectrum” of cells respond at different, but overlapping, times and can together generate a population response whose adaptively timed cell responses become maximal at, or near, the time when the US is expected (Grossberg & Merrill, 1992, 1996; Grossberg & Schmajuk, 1989), as has been shown in neurophysiological experiments about adaptively timed conditioning in the hippocampus (Berger & Thompson, 1978; Nowak & Berger, 1992; see also Tieu et al., 1999).

Each cell in such a spectrum reaches its maximum activity at different times. If the cell responds later, then its activity duration is broader in time, a property that is called a Weber law, or scalar timing, property (Gibbon, 1977). Recent neurophysiological data about “time cells” in the hippocampus have supported the Spectral Timing model prediction of a spectrum of cells with different peak activity times that obey a Weber law. Indeed, such a Weber law property was salient in the data of MacDonald et al. (2011), who wrote: “...the mean peak firing rate for each time cell occurred at sequential

moments, and the overlap among firing periods from even these small ensembles of time cells bridges the entire delay. Notably, the spread of the firing period for each neuron increased with the peak firing time..." (p. 3). MacDonald et al. (2011) have hereby provided direct neurophysiological support for the prediction of spectral timing model cells ("small ensembles of time cells") that obey the Weber law property ("spread of the firing period...increased with the peak firing time").

To generate the adaptively timed population response, each cell's activity is multiplied, or gated, by an adaptive weight before the memory-gated activity adds to the population response. During conditioning, each weight is amplified or suppressed to the extent to which its activity does, or does not, overlap times at which the US occurs; that is, times around the ISI between CS and US. Learning has the effect of amplifying signals from cells whose timing matches the ISI, at least partially. Most cell activity intervals do not match the ISI perfectly. However, after such learning, the sum of the gated signals from all the cells—that is, its population response—is well-timed to the ISI, and typically peaks at or near the expected time of US onset. This sort of adaptive timing endows the nSTART model with the ability to learn associations between events that are separated in time, notably between a CS and US during trace conditioning.

Evidence for adaptive timing has been found during many different types of reinforcement learning. For example, classical conditioning is optimal at a range of inter-stimulus intervals between the CS and US that are characteristic of the task, species, and age, and is typically attenuated at zero ISI and long ISIs. Within an operative range,

learned responses are timed to match the statistics of the learning environment (e.g., Smith, 1968).

Although the amygdala has been identified as a primary site in the expression of emotion and stimulus-reward associations (Aggleton, 1993), as summarized in Figures 2 and 5, the hippocampal formation has been implicated in the adaptively timed processing of cognitive-emotional interactions. For example, Thompson et al. (1987) distinguished two types of learning that go on during conditioning of the rabbit Nictitating Membrane Response: adaptively timed “conditioned fear” learning that is linked to the hippocampus, and adaptively timed “learning of the discrete adaptive response” that is linked to the cerebellum. In particular, neurophysiological evidence has been reported for adaptive timing in entorhinal cortex activation of hippocampal dentate and CA3 pyramidal cells (Berger & Thompson, 1978; Nowak & Berger, 1992) to which the more recently reported “time cells” presumably contribute.

Spectral timing has been used to model challenging behavioral, neurophysiological, and anatomical data about several parts of the brain: the hippocampus to maintain motivated attention on goals for an adaptively timed interval (Grossberg & Merrill, 1992, 1996; cf. Friedman, Bressler, Garner, & Ziv, 2000), the cerebellum to read out adaptively timed movements (Fiala, Grossberg, & Bullock, 1996; Ito, 1984), and the basal ganglia to release dopamine bursts and dips that drive new associative learning in multiple brain regions in response to unexpectedly timed rewards and non-rewards (Brown, Bullock, & Grossberg, 1999, 2004; Schultz, 1998; Schultz et al., 1992).

2.5. Distinguishing expected and unexpected disconfirmations.

Adaptive timing is essential for animals that actively explore and learn about their environment, since rewards and other goals are often delayed in time relative to the actions that are aimed at acquiring them. The brain needs to be dynamically buffered, or protected against, reacting prematurely before a delayed reward can be received. The Spectral Timing model accomplishes this by predicting how the brain distinguishes *expected non-occurrences*, also called *expected disconfirmations*, of reward, which should not be allowed to interfere with acquiring a delayed reward, from *unexpected non-occurrences*, also called *unexpected disconfirmations*, of reward, which can trigger the usual consequences of predictive failure, including reset of working memory, attention shifts, emotional rebounds, and the release of exploratory behaviors. In the nSTART model, and the START model before it, spectral timing circuits generate adaptively timed hippocampal responses that can bridge temporal gaps between CS and US and provide motivated attention to maintain activation of the hippocampus and neocortex between those temporal gaps (Figures 2 and 6).

What spares an animal from erroneously reacting to expected non-occurrences of reward as predictive failures? Why does an animal not immediately become so frustrated by the non-occurrence of such a reward that it prematurely shifts its attentional focus and releases exploratory behavior aimed at finding the desired reward somewhere else, leading to relentless exploration for immediate gratification? Alternatively, if the animal does wait, but the reward does not appear at the expected time, then how does the animal

then react to the unexpected non-occurrence of the reward by becoming frustrated, resetting its working memory, shifting its attention, and releasing exploratory behavior?

Any solution to this problem needs to account for the fact that the process of registering ART-like sensory matches or mismatches is not itself inhibited (Figure 3): if the reward happened to appear earlier than expected, the animal could still perceive it and release consummatory responses. Instead, the *effects* of these sensory mismatches upon reinforcement, attention, and exploration are somehow inhibited, or *gated off*. That is, a primary role of such an adaptive timing mechanism seems to be to inhibit, or gate, the mismatch-mediated arousal process whereby a disconfirmed expectation would otherwise activate widespread signals that could activate negatively reinforcing frustrative emotional responses that drive extinction of previous consummatory behavior, reset working memory, shift attention, and release exploratory behavior.

The START model unifies networks for spectrally timed learning and the differential processing of expected vs. unexpected non-occurrences, or disconfirmations (Figure 6). In START, learning from sensory cortex to amygdala in $S_i \rightarrow D$ pathways is supplemented by a parallel $S_i \rightarrow H$ hippocampal pathway. This parallel pathway embodies a spectral timing circuit. The spectral timing circuit supports adaptively timed learning that can bridge temporal gaps between cues and reinforcers, as occurs during trace conditioning. As shown in Figure 6, both of these learned pathways can generate an inhibitory output signal to the orienting system A. As described within ART (Figure 3c), the orienting system is activated by novelty-sensitive mismatch events. Such a mismatch can trigger a burst of nonspecific arousal that is capable of resetting the currently active

recognition categories that caused the mismatch, while triggering opponent emotional reactions, attention shifts, and exploratory behavioral responses. The inhibitory pathway from D to A in Figure 6 prevents the orienting system from causing these consequences in response to expected disconfirmations, but not to unexpected disconfirmations (Grossberg & Merrill, 1992, 1996). In particular, read-out from the hippocampal adaptive timing circuit activates D which, in turn, inhibits A. At the same time, adaptively timed incentive motivational signals to the prefrontal cortex (pathway $D \rightarrow S_i^{(2)}$ in Figure 6) are supported by adaptively timed output signals from the hippocampus that help to maintain motivated attention, and a cognitive-emotional resonance for a task-appropriate duration.

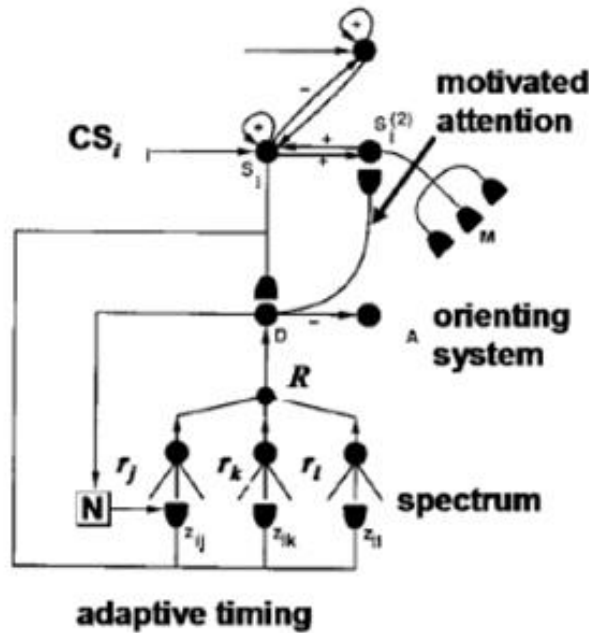


Figure 6. Macrocircuit of the START model of conditioning, attention, and timing. In the START model, conditioning, attention, and timing are integrated. Adaptively timed hippocampal signals R maintain motivated attention via a cortico-hippocampal-cortical feedback pathway, at the same time that they inhibit activation of orienting system circuits A via an amygdala drive representation D . The orienting system is also assumed to occur in the hippocampus. The adaptively timed signal is learned at a spectrum of cells whose activities respond at different rates r_j and are gated by different adaptive weights z_{ij} . A transient Now Print learning signal N drives learned changes in these adaptive weights. In the nSTART model, the

hippocampal feedback circuit operate in parallel to the amygdala, rather than through it. See Section 2.5 for details. [Reprinted with permission from Grossberg and Merrill (1992).]

Thus, in the START model, two complementary pathways are proposed to control spectrally-timed behavior: one excites adaptively-timed motivated attention and responding, and the other inhibits orienting responses in response to expected disconfirmations. Adaptively-timed motivated attention is mediated through an inferotemporal-amygdala-orbitofrontal positive feedback loop in which conditioned reinforcer learning and incentive motivational learning work together to rapidly focus attention upon the most salient cues, while blocking recognition of other cues via lateral inhibition (see Figures 5 and 6). The hippocampal adaptive timing circuit works in parallel to maintain activity in this positive feedback loop and thereby focus motivated attention on salient cues for a duration that matches environmental contingences.

2.6. nSTART model.

The nSTART model builds upon, extends, and unifies, the ART, CogEM, and START models in several ways to explain data about normal and abnormal learning and memory. First, nSTART incorporates a simplified model hippocampus and adaptively timed learning within the model's thalamo-hippocampal and cortico-hippocampal connections (Figure 2). Second, nSTART incorporates a simplified version of ART category learning in its bottom-up cortico-cortical connections. Third, learning in these connections, and in the model's hippocampo-cortical connections, is modulated by a simple embodiment of Brain Derived Neurotrophic Factor (BDNF). Fourth, the sensory cortical and orbitofrontal cortical processing stages habituate in an activity-dependent

way, a property that has previously been used to model other cortical development and learning processes, such as the development of visual cortical area V1 (e.g., Grossberg & Seitz, 2003; Olson & Grossberg, 1998).

The nSTART model focuses on amygdala and hippocampal interactions with sensory cortex and orbitofrontal cortex during conditioning (Figures 2 and 6), with the hippocampus required to support learning and memory consolidation, especially during learning experiences such as trace conditioning wherein a temporal gap between the associated stimuli needs to be bridged, as described in Section 1.4. Consolidation is enabled, in the brain and in the model, by a self-organizing process whereby active neurons and specific neural connections are reinforced and strengthened through positive feedback.

BDNF-mediated hippocampal activation is proposed to maintain and enhance cortico-cortical resonances that strengthen and stabilize partial learning based on previously experienced bottom-up sensory inputs. This partial learning occurs during conditioning trials within the bottom-up adaptive filters that activate learned recognition categories, and within the corresponding top-down expectations. After the consolidation process strengthens these pathways, the hippocampus is no longer required for performance of CRs, but rather the prefrontal cortex takes on a critical role in generating successful performance of the CR in concert with the associated thalamic sensory input (Takehara et al., 2003) and amygdala-driven motivational support. Since amygdala and prefrontal cortex provide input to the pontine nuclei, their collective activity there reflects the salience of the CS in generating a trace CR (Siegel, et al., 2012; Siegel, et al., 2015).

The prefrontal cortex interacts with the cerebellum via the pontine nucleus to directly mediate adaptively timed conditioned responses (Weiss & Disterhoft, 2011; Woodruff-Pak & Disterhoft, 2007). A detailed biochemical model of how the cerebellum learns to control adaptively timed conditioned responses is developed in Fiala, Grossberg, & Bullock (1996), with Ca^{++} -modulated metabotropic glutamate receptor (mGluR) system playing a critical role in enabling temporal gaps to be bridged via a spectral timing circuit.

2.7. Linking consciousness, conditioning, and consolidation.

The nSTART model traces the link between consciousness and conditioning to cognitive-emotional resonances that are sustained long enough to support consciousness. Such cognitive-emotional resonances maintain *core consciousness* (Damasio, 1999) and the ability to make responses, somatosensory responses in the case of eyeblink conditioning, that depend on interactions between sensory cortex and orbitofrontal cortex, or thalamus and medial prefrontal cortex (Powell & Churchwell, 2002). The nSTART model proposes that, when the hippocampus is removed, and with it the capacity to sustain a temporally prolonged cognitive-emotional resonance and adaptively timed focusing of motivated attention upon cognitively relevant information, then core consciousness and performance may be impaired. The model hereby explains how interactions among thalamus, hippocampus, amygdala, and cortex may support the conscious awareness that is needed for trace conditioning, but not delay conditioning (Clark & Squire, 1998).

As explained by the model, memory consolidation during trace conditioning builds upon cooperative interactions among several different neural pathways in which learning takes place during trace conditioning trials. Consider the case of the circuits in Figures 4 and 5, for example. A property of the CogEM model, which is supported by neurophysiological data, as summarized below, is that the (sensory cortex)→(orbitofrontal cortex) pathway, by itself, is not able to initiate efficient conditioning. Motivational support is needed as well. How this is proposed to occur is illustrated by considering what would happen if the sensory cortex and prefrontal cortex were lumped together, as in Figure 4a. Then, after a reinforcing cue activated a sensory representation S , it could activate a motor representation M at the same time that it also sent conditioned reinforcer signals to a drive representation D such as the amygdala. As a result, a motor response could be initiated before the sensory representation received incentive motivational feedback to determine whether the sensory cue *should* generate a response at that time. For example, eating behavior might be initiated before the network could determine if it was hungry; avoidance behavior before a determination of danger.

This deficiency is corrected by interactions between a sensory cortex and its prefrontal, notably orbitofrontal, cortical projection, as in Figure 4b and its anatomical interpretation in Figure 5. Here, the various sensory cortices play the role of the first cortical stage $S_{CS}^{(1)}$ of the sensory representations, the orbitofrontal cortex plays the role of the second cortical stage $S_{CS}^{(2)}$ of the sensory representations, and the amygdala and related structures play the role of the drive representations D . This two-stage sensory representation overcomes the problem just mentioned by assuming that each orbitofrontal

cell obeys a *polyvalent* constraint whereby it can fire vigorously only if it receives input from its sensory cortex *and* from a motivational source such as a drive representation. This polyvalent constraint on the model prefrontal cortex prevents this region from triggering an action until it gets incentive feedback from a motivationally-consistent drive representation (Grossberg, 1971, 1982). More specifically, presentation of a given cue, or CS, activates the first stage $S_{CS}^{(1)}$ of its sensory representation (in sensory cortex) in Figure 4b. This activation is stored in short-term memory using positive feedback pathways from the sensory representation to itself. The stored activity generates output signals to all the drive representations with which the sensory representation is linked, as well as to the second stage $S_{CS}^{(2)}$ of the sensory representation (in prefrontal cortex). The second stage $S_{CS}^{(2)}$ obeys the polyvalent constraint: It cannot fire while the CS is stored in short-term memory unless it receives converging signals from the first sensory stage (via the $S_{CS}^{(1)} \rightarrow S_{CS}^{(2)}$ pathway) and from a drive representation (via the $S_{CS}^{(1)} \rightarrow D \rightarrow S_{CS}^{(2)}$ pathway).

Early in conditioning, a CS can activate its representation $S_{CS}^{(1)}$ in the sensory cortex, but cannot vigorously activate its representation $S_{CS}^{(2)}$ in the orbitofrontal cortex, or a drive representation D in the amygdala. A US can, however, activate D . When the CS and US are paired appropriately through time, the conditioned reinforcer adaptive weights in the $S_{CS}^{(1)} \rightarrow D$ pathway can be strengthened. The converging CS-activated inputs from $S_{CS}^{(1)}$ and US-activated inputs from D at $S_{CS}^{(2)}$ also enable the adaptive weights in the incentive motivational pathway $D \rightarrow S_{CS}^{(2)}$ to be strengthened. After conditioning,

during retention testing when only the CS is presented, the two pathways $S_{CS}^{(1)} \rightarrow S_{CS}^{(2)}$ and $S_{CS}^{(1)} \rightarrow D \rightarrow S_{CS}^{(2)}$ can supply enough converging input to fire the orbitofrontal representation $S_{CS}^{(2)}$ without the help of the US. It should be noted that the association $S_{CS}^{(1)} \rightarrow S_{CS}^{(2)}$ can also link the CS-activated sensory representation with the US-activated orbitofrontal representation, which can read out the response even before conditioning trials begin.

These properties are consistent with the following anatomical interpretation. The amygdala and related structures have been identified in both animals and humans to be a brain region that is involved in learning and eliciting memories of experiences with strong emotional significance (Aggleton, 1993; Davis, 1994; Gloor et al., 1982; Halgren, Walter, Cherlow, & Crandall, 1978; LeDoux, 1993). The orbitofrontal cortex is known to be a major projection area of the ventral, or object-processing cortical visual stream (Barbas, 1995, 2007; Fulton, 1950; Fuster, 1989; Rolls, 1998; Wilson, Scalaidhem, & Goldman-Rakic, 1993). Cells in the orbitofrontal cortex are sensitive to the reward associations of sensory cues, as well as to how satiated the corresponding drive is at any time (e.g., Mishkin & Aggleton, 1981; Rolls, 1998; 2000). The feedback between the prefrontal and sensory cortical stages may be interpreted as an example of the ubiquitous positive feedback that occurs between cortical regions including prefrontal and sensory cortices (Felleman & Van Essen, 1991; Höistad & Barbas, 2008; Macchi & Rinvik, 1976; Sillito, Jones, Gerstein, & West, 1994; Tsumoto, Creutzfeldt, & Legédy, 1978; van Essen & Maunsell, 1983). In CogEM, it provides a top-down ART attentional priming

signal that obeys the ART Matching Rule. Finally, the CogEM, and nSTART, models are consistent with data suggesting that the ventral prefrontal cortex and the amygdala are involved in the process by which responses are selected on the basis of their emotional valence and success in achieving rewards (Damasio, Tranel, & Damasio, 1991; Passingham, 1997). In particular, Fuster (1989) has concluded from studies of monkeys that the orbitofrontal cortex helps to suppress inappropriate responses. These monkey data are consistent with clinical evidence that patients with injury to orbitofrontal cortex tend to behave in an inappropriate manner (Blumer & Benson, 1975; Liddle, 1994).

2.8. Bridging the temporal gap: Hippocampus does this, not amygdala.

The need to regulate orbitofrontal outputs using drive information puts into sharp relief the problem that the brain needs to solve in order to be capable of trace conditioning, or indeed of any learning wherein there is a temporal gap between the stimuli that need to be associated: if the amygdala cannot bridge the temporal gap between CS and US during trace conditioning, what can? If there were no structure capable of bridging that gap, then either the motivational appropriateness of responding would be sacrificed, or the ability to learn across temporal gaps. As briefly noted above, the nSTART model proposes how the brain solves this problem by using the hippocampus to bridge the temporal gap, using spectrally timed learning and BDNF processes in connections from thalamus and sensory cortex to the hippocampus, combined with learned incentive motivational processes and BDNF in connections from hippocampus to neocortex (Figure 2).

Initially, during trace conditioning, the interstimulus interval (ISI) between the CS and US is too large to be bridged by either the direct (sensory cortex)→(orbitofrontal cortex) pathway or by the indirect (sensory cortex)→(amygdala)→(orbitofrontal cortex) pathway. In other words, by the time the US becomes active, CS-activated signals from the sensory cortex to the amygdala and the orbitofrontal cortex have significantly decayed, so that they cannot strongly drive associative learning between simultaneously active CS and US representations. In contrast, in the manner explicated by the model, the greater persistence afforded by hippocampal adaptive timing enables CS-activated signals via the hippocampus to bridge this ISI. Then, when paired with the US, which can activate its own sensory cortical and orbitofrontal cortical representations, CS-activated associations can begin to form in the (sensory cortex)→(hippocampus)→(orbitofrontal cortex) pathway, and can support feedback from orbitofrontal cortex to the CS representation in sensory cortex, thereby enabling a sustained cognitive-emotional resonance that can support conscious awareness. Model hippocampal neurotrophins extend this temporal interval and enhance the strength of these effects. Once both the sensory cortex and orbitofrontal cortex are simultaneously active, associations can also start to form directly from the CS-activated representation in the sensory cortex to the orbitofrontal cortex, thereby consolidating the learned categorical memory that associates an object category with an object-value category. As these direct connections consolidate, the hippocampus becomes less important in controlling behaviors that are read out from orbitofrontal cortical sites.

After partial conditioning gets learning started in associated thalamo-cortical and cortico-cortical pathways, during the memory consolidation process, hippocampal adaptively timed circuits, and even beyond that, BDNF activity, persist and support resonating cortico-cortical and cortico-hippocampo-cortical activity. The polyvalent constraint on the firing of orbitofrontal cells is therefore achieved even after learning trials cease. Without hippocampal support after partial conditioning, this cannot occur. The model suggests that this is why early, but not late, hippocampal lesions interfere with the formation and consolidation of conditioned responses.

CHAPTER 3. Model Description

3.1. nSTART model overview.

The nSTART model is here described in terms of the processing stages that are activated during a conditioning trial, and the functional role of each stage is explained. Figure 2 illustrates the model as a macrocircuit. Figure 7 shows a set of diagrams that summarize the processing steps and relationships among the model variables. Appendix A combines them to form a complete circuit diagram (Figure 18) whose mathematical equations and parameters are also specified. Model parameters have the same values for all simulations except where modifications have been made to simulate lesions or different US levels.

For each trial, conditioning variables are simulated from 1 to 2000 ms. Three types of trials simulate the learning of conditioning contingencies: acquisition or training (CS-US pairing), retention or testing (CS only), and no stimulus (neither CS nor US) in order to extend the time between the last training trial and the testing trial. Between any two trials, process variables are either reset to initial values, or not, depending on their functional role. There are two types of process variables: one for intra-trial process dynamics (these variables are reset for each trial), and one for inter-trial cumulative learning (these variables are not reset for each trial). Cumulative learning variables are identified below in the discussion of the functional role of each process. See Table 2 in Appeddix A for a list of all variables.

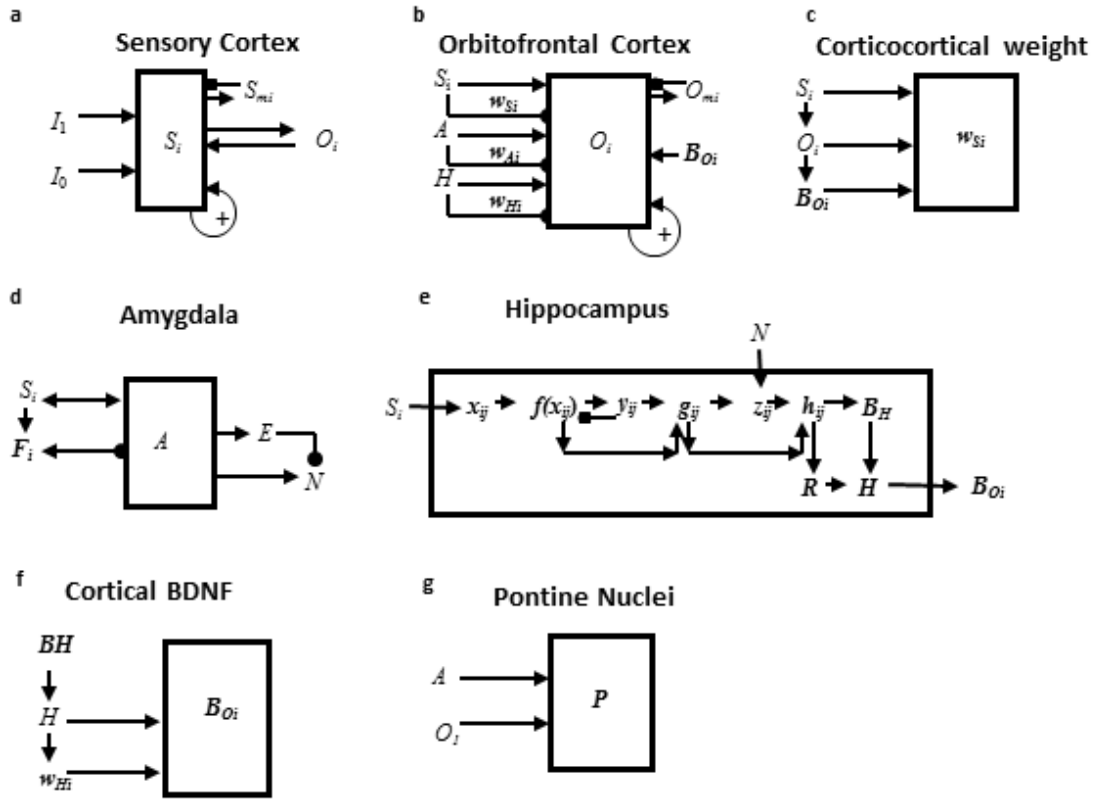


Figure 7. Processing Steps for nSTART Conditioning. The processing steps for a conditioning trial in the nSTART model are illustrated. As conditioned variables or activities that represent learning, the following are not reset to zero between trials in order to simulate inter-trial learning: adaptive weights w_{Si} , w_{Ai} , w_{Hi} , F_i , and z_{ij} ; and hippocampal and orbitofrontal BDNF B_H and B_{Oi} , respectively. See below for details. (a) External stimuli, I_i activate sensory representations in the sensory cortex S_i via the thalamus T_i (see Section 3.2.1). Orbitofrontal cortical activity O_i (see Section 3.3.1) generates a top-down excitatory feedback signal back to S_i . The total excitatory signal, including this positive feedback, is gated by the habituating transmitter gate S_{mi} (see Section 3.2.2). (b) Excitatory inputs to orbitofrontal cortex from sensory cortex (S_i , Section 3.2), amygdala (A , Section 3.4), and hippocampus (H , Section 3.5) are gated by learned presynaptic weights (w_{Si} , w_{Ai} , and w_{Hi} , respectively; see Section 3.3.2). An example of this processing shown in Figure 7c. Orbitofrontal BDNF (B_{Oi} , Section 3.3.3) extends duration of O_i activity. The total excitatory signal, including positive feedback, is gated by the habituating transmitter gate O_{mi} (see Section 3.3.4). (c) The learned weight w_{Si} from sensory cortex to orbitofrontal cortex is modulated by orbitofrontal and BDNF signals. (d) Amygdala (A) receives inputs from sensory cortex (S_i) that are gated by conditioned reinforcer adaptive weights (F_i ; see Section 3.4.2). The transient Now Print signal (N) that drives the learning of adaptively timed hippocampal responses is the difference between the excitatory signal from amygdala (A) and an inhibitory signal from a feedforward amygdala-activated inhibitory interneuron (E), which time-averages amygdala activity (see Section 3.5.8). (e) Sensory cortical (S_i) inputs to hippocampus (H) learn to adaptively time (z_{ij}) the ISI using the Now Print signal (N) to drive learning within a spectral timing circuit. The cells in the spectral timing circuit react to sensory cortical (S_i) inputs at 20 different rates that are subscripted with j . The resulting activations (x_{ij}) generate sigmoidal output signals ($f(x_{ij})$). These outputs are multiplied by their habituating transmitter gates (y_{ij}) to produce an activation spectrum (g_{ij}) which determines the rate at which the adaptive weights (z_{ij}) learn from N . See Section 3.5.8

for details. The z_{ij} multiply the g_{ij} to generate net outputs h_{ij} (Section 3.5.4). that are added to generate an adaptively timed population input (R ; see Section 3.5.3) to hippocampus (H). R also regulates hippocampal BDNF (B_H), which further extends hippocampal activity through time (see Section 3.5.9). H also supports production of orbitofrontal BDNF (B_{Of}) (see Section 3.3.3). (f) Hippocampal BDNF (B_H) is an indirect promoter of the production of cortical BDNF (B_{Cf}) through its excitatory effect on the activity H . (g) Pontine nuclei (P) are excited by amygdala (A) and orbitofrontal cortex (O) and are the final common pathway for generating a CR. These processing components are combined in Figure 18.

3.2. Sensory cortex and thalamus.

3.2.1. Sensory cortical dynamics.

The dynamics of sensory cortex were simulated (Figure 2). Thalamic activity was set equal to the resultant sensory cortical activity, for computational simplicity. CS and US inputs are labeled I_1 and I_0 , respectively. Input I_i activates the i^{th} sensory cortical cell, $i = 0$ or 1 . The inputs are turned on and off through time by presentation and termination of a CS input (I_1) or US input (I_0), and are defined by a saturating function $I = f(\sigma) = 16\sigma/(1+3\sigma)$ of an external stimulus intensity σ .

Sensory cortex cell activities S_i compete for a limited capacity of activation via a recurrent on-center off-surround network of cells that obey membrane, or shunting equations. (Appendix A.2.1, Equations 1 and 2). These recurrent interactions use a nonlinear signal function (Appendix A.2.2, Equation 4) that contrast-enhances network activity patterns and sustains the contrast-enhanced activities in short-term memory after the input pattern ends. In addition to the bottom-up input I_i and the recurrent on-center interactions, excitatory inputs include a top-down attentional signal O_i from object-value categories in the orbitofrontal cortex. This feedback pathway closes a bottom-up/top-down feedback

loop between sensory cortex and orbitofrontal cortex and gain-amplifies cortico-cortical activity (Appendix A.3.1, Equation 7).

A habituating transmitter gate S_{mi} multiplies the total excitatory input and is inactivated by it in an activity-dependent way, thereby preventing unlimited perseverative activation of the cortico-cortical excitatory feedback loop (Appendix A.2.3, Equation 6). This gate can be realized in several ways, one being a presynaptic chemical transmitter that is released by axonal signals, and the other as a postsynaptic membrane current. The orbitofrontal cortical cells have an analogous habituating process (Appendix A.3.4, Equation 13). When all these processes interact, a brief input can trigger sustained cortical activity via the recurrent on-center, modulated by orbitofrontal attentional feedback, until it habituates in an activity-dependent way, or is reset by recurrent competitive interactions.

3.2.2. Signal functions in the recurrent on-center off-surround network.

In order to suppress noise in the system and contrast enhance cell activity, the signal function $f_s(S_i)$ in the recurrent on-center off-surround network is faster-than-linear (Grossberg, 1973, 1980), with a firing threshold that is larger than the passive equilibrium point and grows linearly with cell activity above threshold (Appendix A.2.2, Equation 4).

3.2.3. Habituating transmitter gates.

The habituating transmitter gate at each sensory cortical cell accumulates at a constant rate up to a maximum value, and is inactivated at a rate proportional to the size

of the excitatory signal that it gates, multiplied by the amount of available transmitter (Appendix A.3.1, Equation 6; Abbott et al., 1997; Grossberg, 1968b, 1972, 1980).

3.3. Orbitofrontal cortex, category learning, and incentive motivational learning.

3.3.1. Orbitofrontal cortical dynamics.

Sensory cortical activity S_1 can generate excitatory signals to cells with orbitofrontal cortical activity O_1 . As in the sensory cortex, orbitofrontal cortical cells compete via a recurrent on-center off-surround network whose cells obey the membrane, or shunting, equations of physiology. These recurrent dynamics enable orbitofrontal cortical activity to contrast-normalize and contrast-enhance its inputs, and for cell activities that win the competition to persist in short-term memory after inputs terminate. Finally, again as in the model sensory cortex, the total excitatory input to prefrontal cortical cells can habituate in an activity-dependent way (Appendix A.3.4, Equation 13).

3.3.2. Cortical category learning and incentive motivational learning.

Adaptive weights w_{S1} exist in this pathway from CS-activated sensory cortex to orbitofrontal cortex, and may be strengthened by the conditioning process. Support for category learning process is a critical event that enables conditioned responding to occur after sufficient memory consolidation occurs, so that hippocampal support is no longer required.

Before conditioning occurs, when a CS is presented, it can activate its sensory representation, and sends signals to its orbitofrontal representation, amygdala, and

hippocampus. However, before conditioning occurs, these signals cannot vigorously activate other regions of the model network. When the US occurs, it can activate its own sensory and orbitofrontal cortical representations, as well as the amygdala and hippocampus. Incentive motivational signals from the amygdala and hippocampus can then be broadcast nonspecifically to many orbitofrontal cortical cells, including those that receive signals from the CS. The hippocampal incentive motivational signals last longer than the amygdala signals because of their capacity for adaptively-timed responding across long ISIs, as will be noted in Section 3.5. Only those orbitofrontal cortical cells that receive a simultaneous combination of CS-activated and US-activated signals can start to vigorously fire.

When O_1 becomes active at the same time that signals from S_1 , are active, the adaptive weight w_{s_1} in the corresponding category learning pathway to orbitofrontal cortex (Appendix A.3.2, Equation 9) can grow. Category learning enables a CS to activate an orbitofrontal representation that can release conditioned responses further downstream. As in the START model, the sensory cortex (Appendix A.2.1, Equation 2), amygdala (Appendix A.4.1, Equation 14), and hippocampus (Appendix A.5.2, Equation 16), all play a role in this cortico-cortical category learning process, during which incentive motivational learning from both amygdala and hippocampus to orbitofrontal cortex also takes place, with adaptive weights w_{Ai} and w_{Hi} in the corresponding pathways (Appendix A.3.2).

After being gated by its adaptive weight w_{S1} , a sensory cortical input to an orbitofrontal cell is multiplicatively modulated, or gated, by the sum of amygdala, hippocampal, and BDNF incentive motivational signals (A , H and B_O , respectively; see Section 3.3.2). As noted above, when these converging signals are sufficiently large at the beginning of conditioning, O_1 can become active, so all three types of adaptive weights abutting the prefrontal cortical cell, from sensory cortex, amygdala, and hippocampus (w_{Si}, w_{Ai}, w_{Hi}), can be conditioned if their input sources are also active at these times (see Figures 7b and 7c). In situations where the ISI is large, as during trace conditioning, the incentive motivational signal from hippocampus may be large, even if the signal from amygdala is not.

As explained in Section 3.5, the hippocampus can maintain its activity for an adaptively-timed duration that can span a long trace interval. In addition, BDNF at the hippocampus B_H (Section 3.3.3) and orbitofrontal cortex B_{Oi} (Section 3.5.9) can sustain prefrontal cortical activity for an even longer duration. This action of BDNF captures in a simplified way how BDNF-modulated hippocampal bursting is maintained during memory consolidation.

These adaptive weights all obey an *outstar learning* law (Grossberg, 1968a, 1980). In the incentive motivational pathways from amygdala and hippocampus, learning is gated on and off by a sampling signal that grows with amygdala or hippocampal activity, plus hippocampal BDNF activity (Appendix A.3.2, Equations 10 and 11). When the sampling signal is on, it determines the rate at which the corresponding adaptive weight

time-averages activity O_1 , thereby combining both Hebbian and anti-Hebbian learning properties.

3.3.3. Orbitofrontal BDNF.

Orbitofrontal BDNF B_{O_i} (Appendix A.3.3, Equation 7) slowly time-averages the level of hippocampal activity H , and thereby extends its duration. This BDNF process hereby helps to maintain cortical activity across an extended CS-US temporal gap during trace conditioning, and thus to support the consolidation of cortico-cortical category learning.

3.3.4. Habituated transmitter gates.

As in Section 3.2.3, the habituated transmitter gate at each cortical cell prevents unlimited perseverative activation of orbitofrontal cortical cells via their positive feedback loops. As before, such a habituated transmitter gate accumulates at a constant rate up to a maximum value, and is inactivated at a rate proportional to the size of the excitatory signal that it gates, multiplied by the amount of available transmitter (Appendix A.2.3, Equation 5).

3.4. Amygdala and conditioned reinforcer learning.

3.4.1 Amygdala drive representation dynamics.

The amygdala has a complex cytotoxic architecture that represents emotional states and generates incentive motivational signals (Aggleton & Saunders, 2000). The amygdala is simplified in nSTART to enable conditioned reinforcer learning and

incentive motivation learning to occur, as in the CogEM and START models (see Figure 4). In the nSTART model, a single drive representation of amygdala activity A (Appendix A.4.1, Equation 14) is activated by the sum of excitatory inputs from sensory cortex S_i that are gated by conditioned reinforcer adaptive weights.

3.4.2 Conditioned reinforcer learning.

These adaptive weights determine how well sensory cortex can activate A . Conditioned reinforcer learning is a key step in converting a conditioned stimulus into a conditioned reinforcer that can activate the amygdala. Together with incentive motivational learning in the pathway from amygdala to orbitofrontal cortex (Appendix A.3.2), a sensory cortical input can stimulate the amygdala which, in turn, can provide motivational support to fire orbitofrontal cortical cells (Figure 2).

The CS cannot strongly excite the drive representation activity A before conditioning takes place. During conditioning, the US can directly activate A via its sensory representation. Pairing of CS-activated signals from the sensory cortex to the amygdala with those of the US to the amygdala causes conditioned reinforcer learning in the adaptive weights within the (sensory cortex)-to-amygdala pathways.

As in the case of incentive motivational learning, the learning law that is used for conditioned reinforcer learning is an *outstar learning* law (Appendix A.4.2, Equation 15) whereby a sensory cortical representation can sample and learn a spatial pattern of conditioned reinforcer adaptive weights across multiple drive representations. The current model simulations only consider such learning at a single drive representation.

3.5. Hippocampus and adaptively timed learning..

3.5.1. *Adaptively-timed hippocampal learning.*

As noted in Section 3.3.1, the hippocampus receives adaptively timed inputs that can maintain its activity for a duration that can span the trace interval. The hippocampus can hereby provide its own incentive motivational pathway to orbitofrontal cortical cells in cases when the amygdala cannot. In addition, BDNF at the model hippocampus and prefrontal cortex can sustain prefrontal cortical activity for an even longer duration. The adaptively timed “spectral timing” process spans several processing steps.

3.5.2. *Adaptively-timed hippocampal activity.*

The adaptively timed signal R and the hippocampal BDNF signal B_H together maintain activity of the model hippocampus (Appendix A.5.2, Equation 16) across trace conditioning intervals, and also during periods after partial conditioning when no further external inputs are presented. In these latter periods, sustained hippocampal activity provides the incentive motivational signals that support memory consolidation of cortico-cortical category learning.

Figure 7f shows the functional relationships between hippocampal BDNF (B_H), hippocampal activity (H), the hippocampal-to-orbitofrontal learned weight (w_{Hi}), and the hippocampal-to-orbitofrontal stimulation of cortical BDNF (B_{Oi}) production.

3.5.3. *Adaptively-timed population output signal.*

The adaptively timed input from the sensory cortex to the hippocampus is the population output $R = \sum_{i,j} h_{ij}$ of spectrally-timed and learning-gated signals (Appendix A.5.3, Equation 17). The individual signals h_{ij} are not well timed, but the population response R is, and its activity peaks around the *ISI*. Adaptively timed learning is thus an emergent property of this entire population of cell sites.

3.5.4. *Activation spectrum.*

The components of the adaptively timed signal R are defined as follows: First, a population of hippocampal cell sites with activities x_{ij} (Appendix A.5.5, Equation 20) reacts to the excitatory input signal from sensory cortex at a spectrum of rates, ranging from fast to slow, that span the different ISIs to be learned. Activity x_{ij} generates a sigmoidal output signal $f(x_{ij})$ to the next processing stage.

3.5.5. *Habituated transmitter spectrum.*

Each signal $f(x_{ij})$ is gated by with a habituated transmitter gate y_{ij} (Appendix A.5.6, Equation 22) that is similar in structure and function to the habituated transmitter gates described in Section 3.2.3. The different rates at which each spectral activity $f(x_{ij})$ responds causes the corresponding habituated transmitter y_{ij} to habituate at a different

rate. Habituated transmitter y_{ij} multiplies, or gates, the corresponding signal $f(x_{ij})$ to generate a net output signal g_{ij} (Appendix A.5.7, Equation 23).

3.5.6. Gated signal spectrum and time cells.

Multiplication of the increasing $f(x_{ij})$ with the decreasing y_{ij} generates a unimodal curve $g_{ij} = f(x_{ij})z_{ij}$ through time. Each g_{ij} peaks at a different time, and curves that peak at later times have broader activation profiles through time (see Figure 11c), thereby realizing a *Weber law* property. Predicted properties of these cell responses were reported in neurophysiological data about hippocampal *time cells* (MacDonald et al., 2011). The Spectral Timing model predicts how such time cells may be used both to bridge the long ISIs that occur during trace conditioning, and to learn adaptively timed output signals that match the timing of experienced ISIs during delay or trace conditioning. This learning is proposed to occur in the following way.

3.5.7. Spectral learning law.

To generate the adaptively-timed response R , each signal g_{ij} is multiplied, or gated, by a long-term memory (LTM) trace z_{ij} (Appendix A.5.8, Equation 24). In addition, g_{ij} helps to control learning by z_{ij} : when g_{ij} is positive, z_{ij} can approach the value of a Now Print learning signal N at a rate proportional to g_{ij} . Each z_{ij} thus changes by an amount that reflects the degree to which the curves g_{ij} and N , which represent sensory and reinforcement values, respectively, are simultaneously large. If g_{ij} is large

while N is large, then z_{ij} will increase. If g_{ij} is large while N is small, then z_{ij} will decrease. Thus, adaptively timed learning selectively amplifies those z_{ij} whose sampling signals g_{ij} are on when N is on. Since the z_{ij} represent adaptively timed learned traces that persist across trials, they are not reset to initial values between trials but rather are cumulative across trials.

Signal N is activated transiently by increments in amygdala activity, and is thus active at times when the amygdala receives either US or conditioned CS inputs. A direct excitatory output signal from amygdala (Appendix A.4.1, Equation 14) and an inhibitory signal from an amygdala-activated inhibitory interneuron E (Appendix A.5.8, Equation 26) combine to compute N (Appendix A.5.8, Equation 25); see Figure 7d. In response to larger inputs A , N increases in amplitude, but not significantly in duration. Thus, learning rate can change without undermining learned timing.

3.5.8. Doubly-gated signal spectrum.

The adaptive weight z_{ij} gates the sampling signal g_{ij} to generate a twice-gated output signal $h_{ij} = 8f(x_{ij})y_{ij}z_{ij}$ from each of the differently timed cell sites (Appendix A.5.4, Equation 18); see Figure 11d. Comparison of h_{ij} with g_{ij} in Figure 11d shows how the population response $R = \sum_{i,j} h_{ij}$ learns to match the ISI.

3.5.9. *Hippocampal BDNF.*

R causes production and release of hippocampal BDNF B_H (Appendix A.5.9, Equation 27). Sustained BDNF activity helps to maintain hippocampal activity even longer than R can, and thus its incentive motivational support to orbitofrontal cortex across the CS-US ISI intervals during trace conditioning and memory consolidation (Figure 7e).

3.6. The Pontine Nuclei.

3.6.1. *Final common path for conditioned output.*

Projections from the amygdala and orbitofrontal cortex input to the pontine nuclei (Figure 7g). Pontine activity P controls output signals that generate a CR (Kalmbach et. al., 2009; Siegel et al., 2012; Woodruff-Pak & Disterhoft, 2007; see Appendix A.6.1, Equation (22)).

CHAPTER 4. Results

4.1. Summary of six key simulation measures.

Using a single set of model parameters except when the US intensity was varied, the following measurements are used to simulate the experimental data. Where there is an intact or partial hippocampus in the simulation, the adaptively timed signal within the hippocampus, R , is used to illustrate how the hippocampus reflects CR-timed performance, as seen in many experimental data (Smith, 1968; Schmaltz & Theios, 1972; Berger, 1984; Thompson, 1988). Orbitofrontal cortical activity, O , is reported since it is involved in activating downstream conditioned motor outputs (Kalmbach, et. al., 2009; Siegel et al., 2012; Woodruff-Pak & Disterhoft, 2007); and is a critical site of long-term memory consolidation in the model (Appendix A.5.3, Equation 17). In addition, the activity of the pontine nuclei P (Appendix A.6.1, Equation 28) is reported in all cases because it serves as a common output path for CR (Kalmbach, et. al., 2009; Siegel, et al., 2012; Woodruff-Pak & Disterhoft, 2007). To understand how CR activity is generated in the pons, the activity profiles of sensory cortex (S), amygdala (A), and hippocampus (H) are also reported.

These key output measures are a function of all of the variables in the system. To understand some of the dynamics that will be described in the following sections, consider orbitofrontal cortical activity (O_i). nSTART model parameters have been selected such that a true winner-take-all (WTA) competition for orbitofrontal cortical activity is not operative since activation remains in each of the two nodes representing the CS and the US throughout learning and retention testing. As illustrated in Appendix B.4,

the retention test outcome after 20 trials, O_i does not exhibit a WTA profile but rather a dynamic equilibrium. The graph of O_i (first row, third column) shows the critical impact of the associated learning variables wT_i , wA_i and wH_i (third row, second, third, and fourth columns, respectively) and cortical BDNF BO_i (third row, first column) on cortical activity. Appendix B also shows the time course of all nSTART system variables during normal trace conditioning during acquisition trial 1, 5 and 20 (Appendices B.1, B.2 and B.3, respectively) so that the change in each variable is illustrated as learning continues. Note that the graph for the adaptively timed signal within the hippocampus, R , (fourth row, fifth column) shows the output from all previous trials in the run. The description of each variable and its role in the processing steps for nSTART conditioning is given in Figure 7, a circuit diagram of their interactions in Figure 18, and a list of them in Table 1 in Appendix A.

4.2. Simulation of normal trace conditioning.

Figure 8a shows behavioral data for normal trace conditioning during rabbit nictitating membrane conditioning for multiple ISIs in response to different US levels (Smith, 1968). These data exhibit the Weber law property whereby smaller ISIs generate earlier response peaks with narrower variances. The data also generally show the typical inverted-U envelope through time at each US intensity level for each ISI curve as well as collectively as the ISI increases. Finally, the data show that, whereas conditioned response timing is only sensitive to the ISI, response amplitude is also sensitive to US intensity (1, 2, and 4 MA).

Under the learning conditions in the Smith (1968) experiments, where a living animal has much more complex knowledge, motivation, and attentional distractions than in a computational model like nSTART, 110 trials, on each of 10 consecutive days, were completed to obtain the given CR data, which are smoothed averages of the individual trials. Smith noted that his data of “average topographies present a somewhat distorted picture of individual CRs...the later peak of the averaged response appeared to be later than the mean of the individual responses” (Smith, 1968, p.683; see Figure 8a).

Figure 8b shows how hippocampal adaptive timing R in nSTART simulates these properties of normal conditioning on a recall trial, in response to the CS alone, after 20 prior learning trials for each ISI in response to three different US amplitudes. The peak activities and timing of both the cortex and the pontine nuclei (Figure 8d) reflect the properties of the adaptively timed hippocampal output to them.

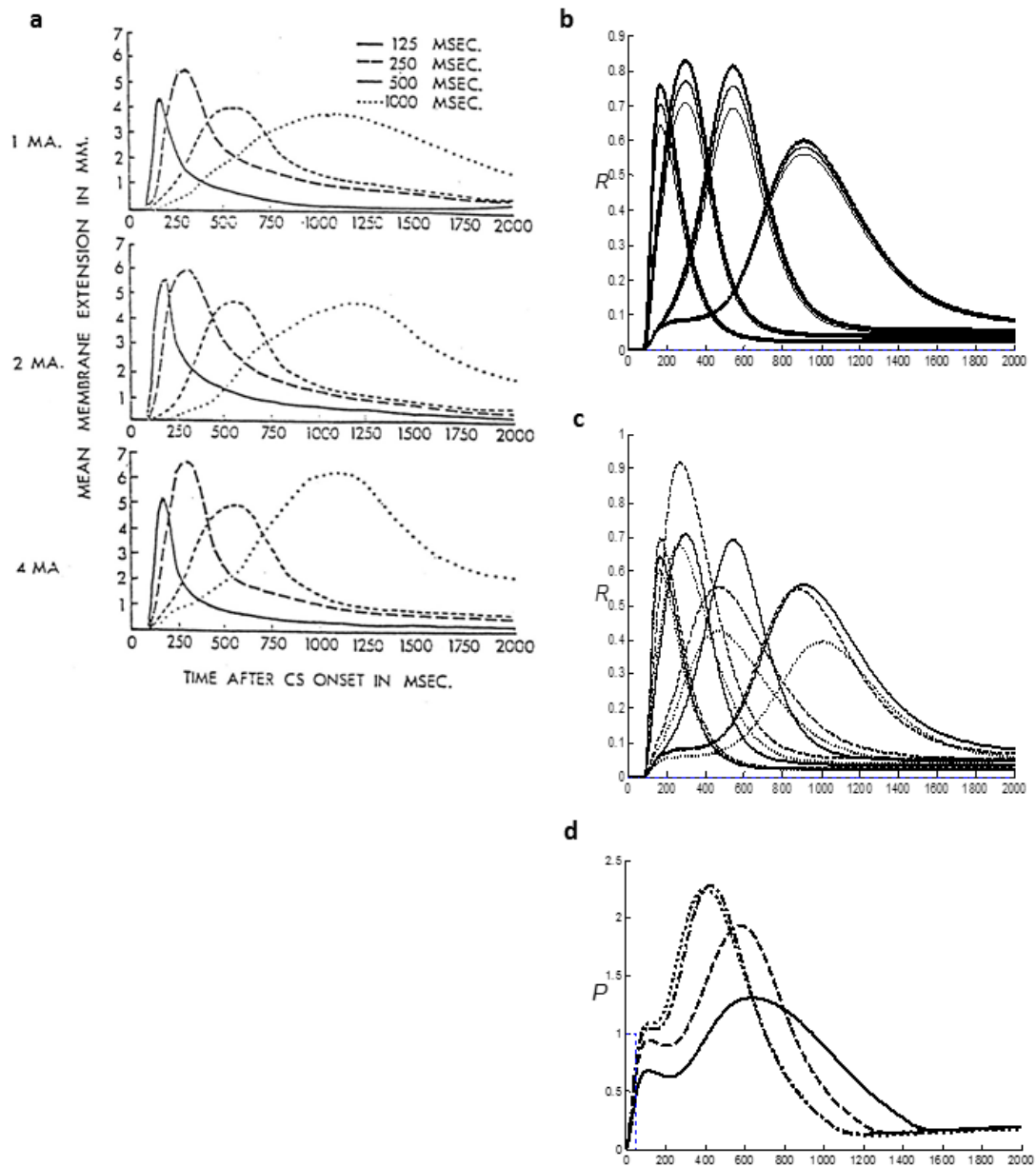


Figure 8. Data and simulations of trace conditioning at multiple ISIs. (a) Data showing trace conditioning data at multiple ISIs for different US levels (Smith, 1968). (b) Simulation of Smith data by nSTART model is based on 20 acquisition trials per ISI for time = 1 to 2000 ms, US level = 1 (solid line), 2 (thicker solid line), and 4 (thickest solid line). The hippocampal output signal R (Equation 17) is plotted for a retention test trial in response to the CS alone. Simulating qualitative properties of the data, peak amplitude of each curve is near its associated ISI of 125, 250, 500 and 1000 ms, respectively. The model is sensitive to US intensity. (c) A comparison of the normal simulation of the Smith data in (b) using US level

=1 (solid line), with simulation of two abnormal treatments: with no hippocampal BDNF (dashed-line) and with no hippocampal BDNF and no cortical BDNF (dotted-line). Short ISIs show an increase in amplitude, longer ISIs show a decrease. (d) Activity in the pontine nuclei (P) for a retention test in response to the CS only: ISI = 125 ms (dotted line), ISI = 250 ms (dotted-dashed line), ISI = 500ms (dashed line), ISI = 1000 ms (solid line). The CS input is shown as a vertical dashed bar starting at a CS onset at 1 ms. Short ISIs (125 ms and 250 ms) do not exhibit typical pontine profiles; *in vivo*, very short ISIs are likely processed directly by the pons and its connection to the cerebellum. As the ISI becomes longer and a CR is more reliant on the timed orbitofrontal connection to the pons, pontine activity matches the experimental data.

When orbitofrontal BDNF B_{O1} (Section 3.3.3) is eliminated after acquisition trials in model simulations, adaptive timing is impacted more negatively for longer ISIs (Figure 8c). This learning impairment is due to a weakened cortico-cortico-hippocampal feedback loop, which is critical in trace conditioning.

nSTART is robust in that, with a single set of parameters, it can learn long ISIs better under normal conditions with additional learning trials; for example, the retention test output for ISI = 1000 after 20 and 40 acquisition trials shows that peak R amplitude and timing changed from 0.5616 at 911 ms to 0.5393 at 949 ms, respectively. The activity profiles of the pontine nuclei are consistent with these results: P peak amplitude and timing changed from 1.311 at 639 ms, at 20 trials, to 1.689 at 601 ms, at 40 trials. These peak timings are within the effective 400ms signaling window that has been found experimentally (Kalmbach, et. al., 2009; Siegel, et al., 2012; Woodruff-Pak & Disterhoft, 2007).

4.3. Delay conditioning with and without hippocampus.

A comparison of simulations of delay conditioning after 5 training trials with and without hippocampal lesions (see H in Figure 9a) and indicates that an intact model hippocampus is not required for delay conditioning (see P in Figure 8a), as also occurs typically in the data (see Table 1, Section 4.9). The involvement of the amygdala in each

case (normal, 50% partial ablation, and 80% partial ablation) is apparent when their peak activities are compared. While *in vivo* the cerebellum typically is able to learn delay conditioning without forebrain processing, the model illustrates how the amygdala may motivationally support a parallel input channel to the pontine activity found in normal delay conditioning.

This effect is enhanced after 10 training trials (Figure 9b). *In vivo*, output pathways like the pontine pathway are supplemented by adaptively timed cerebellar response learning, which would strengthen these tendencies.

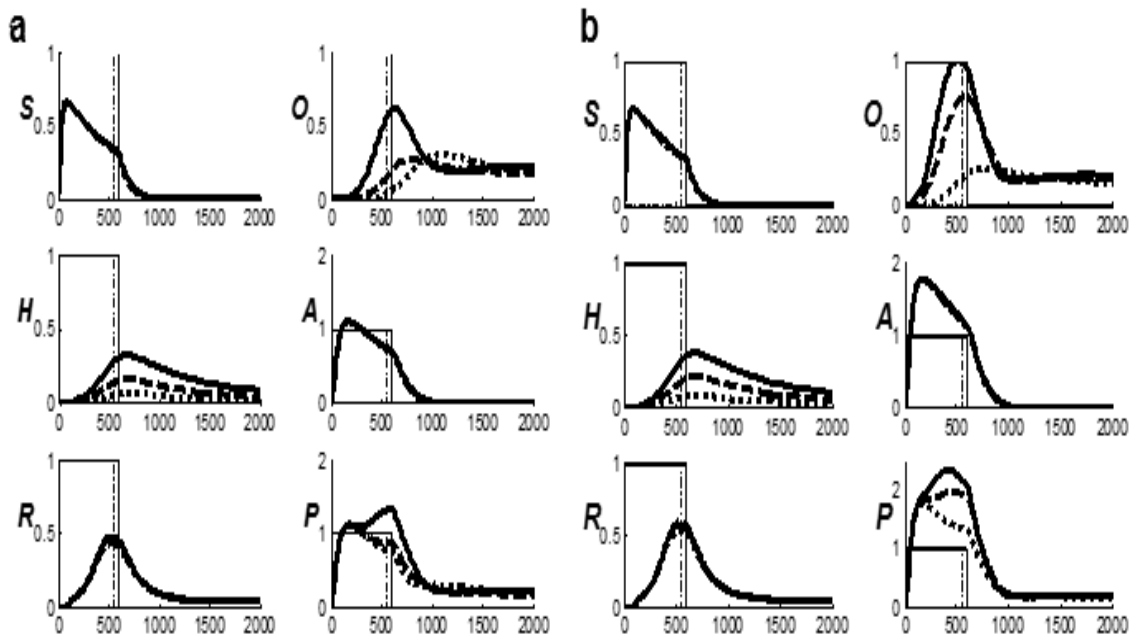


Figure 9. Simulation of delay conditioning data. The hippocampus is not required for delay conditioning. (a) To simulate hippocampal lesions before any delay conditioning trials, the scalar β_H in the hippocampus excitation term in Equation 16 was progressively decreased. There were 5 training trials with US onset at 550 ms, US duration = 50 ms, US offset at 600 ms, and US level = 1. The results show network activations in response to a CS after training: sensory cortex (*S*), orbitofrontal cortex (*O*), hippocampus (*H*), amygdala (*A*), hippocampal adaptive timing (*R*), and the pontine nuclei (*P*). The CS is represented by vertical solid lines, the US onset during training by a vertical dashed line (in delay conditioning, the CS offset and the US offset coincide). Delay conditioning shows little change in pontine activity in the normal (solid line) versus 50% (dashed line) and 80% (dotted line) lesions. (b) 10 learning trials, instead of the 5 trials in (a), yield better learning, including at the orbitofrontal cortex.

Experimental data when the ISI is relatively long, for example, 1500 ms in rats, do show deficits in the initial timing and amplitude of the CR, and in the time to acquire the CR, when hippocampus is damaged. These experimenters (Beylin, et al., 2001) counted any response within 500 ms of US onset as a CR. We do not simulate this finding due to the variability of these results. They can, however, be qualitatively explained if the sensory cortical responses habituate at later times when the CS is sustained for such long durations. Then an at least partial temporal gap would be created between internal CS activations and US onset. This kind of result could then be explained using the same mechanisms that are used to explicit deficits during trace conditioning after hippocampal damage (Section 4.5).

4.4. Delay and trace conditioning with and without amygdala.

Simulations of amygdala lesions are also consistent with experimental data (graphs labeled A in Figure 10). Delay conditioning with partial and complete amygdala lesions demonstrate the experimental finding (Lee & Kim, 2004) that the amygdala is required for optimal acquisition and retention of the CR, as reflected in the simulated hippocampal response amplitude for adaptive timing (R), the orbitofrontal cortical response amplitude (O), and especially the pontine response amplitude (P). To simulate partial lesions of the amygdala in delay conditioning, the gain of the excitatory inputs from the sensory cortex to the amygdala (Appendix A.4.1, Equation 14, parameter β_A) is lowered from the baseline value of 40 to 30, and then to 20. When the growth rate is thus attenuated, there is normal timing in delay conditioning but with a smaller peak

amplitude in the amygdala, and also in the hippocampus, which depends upon amygdala-triggered Now Print signals to train the temporal distribution of spectrally timed hippocampal learning (Figure 10a). The lower peak amplitude reflects the fact that *in vivo* there is slower and weaker learning of the adaptively timed response. The experimental finding that 4 to 5 more days of training rats with amygdala lesions can support learning of the CR (Lee and Kim, 2004) may also include support from extra-amygdala circuits. Additional training also improves learning in the model (Figure 10b). However, when the amygdala is completely ablated before training, there is no hippocampal response. The cortical and pontine peak amplitudes show similar results.

The dynamics of the nSTART cortico-cortico-hippocampal loop explains how aversive conditioning can occur with partial amygdala lesions. Activity in the model orbitofrontal cortex, based in part on hippocampal and amygdala inputs (Appendix A.3.1, Equation 7), continues to support adaptively timed learning via its input to sensory cortex (Appendix A.2.1, Equation 2), and sensory cortical input to the hippocampal activation spectrum (Appendix A.3.5, Equation 19) supports adaptively timed learning (Appendix A.3.3, Equation 17). For this to occur, there has to be enough amygdala input to generate a Now Print signal that shapes the adaptively timed response through learning. *In vivo*, other circuits are also involved that are outside the scope of the nSTART model (see Figure 2), such as cerebellum, hypothalamus, and basal ganglia, but their responses are

not rate-limiting in simulating the main effects above.

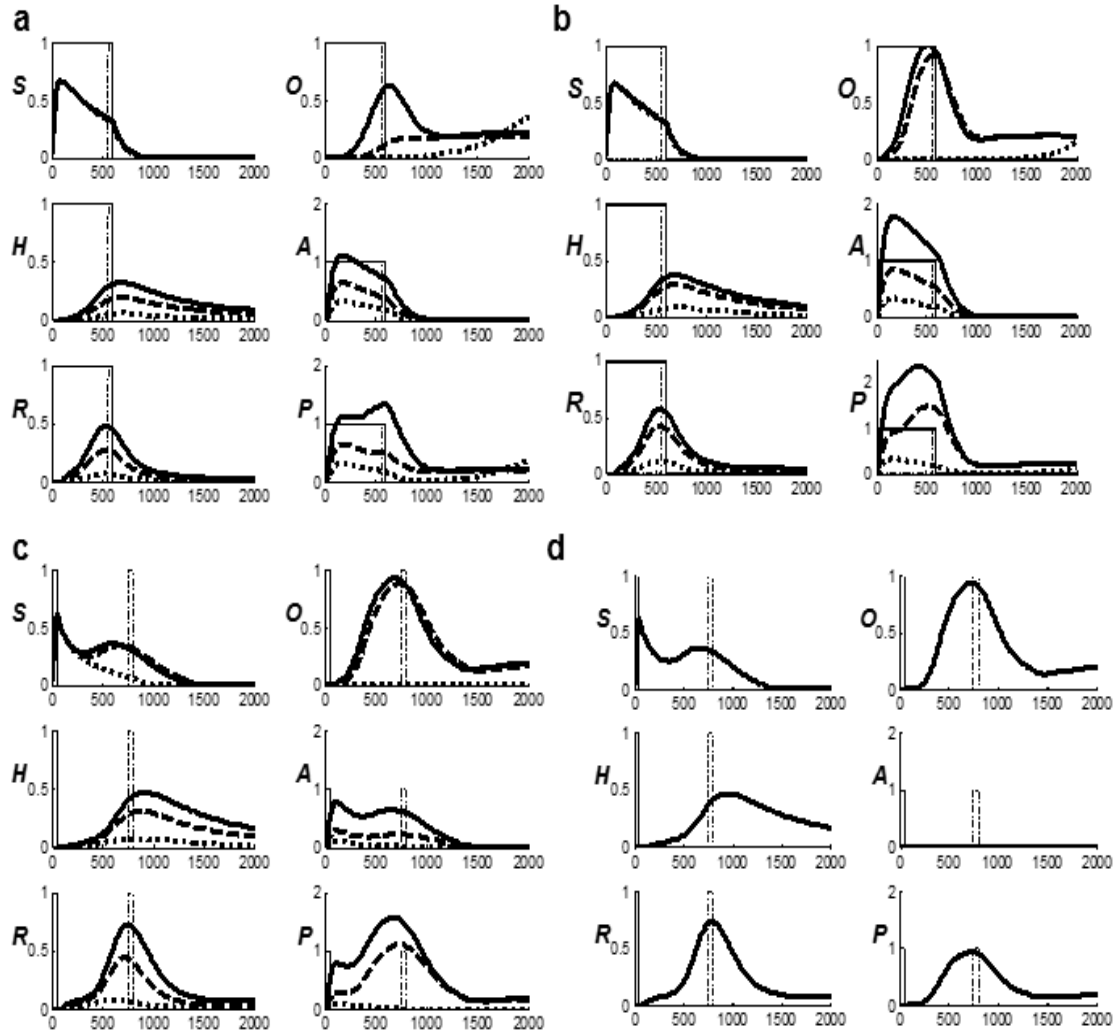


Figure 10. Simulation of amygdala lesion data. Simulations of amygdala lesions demonstrate that the amygdala is required for optimal acquisition but not for successful retention. (a) To simulate partial lesions of the amygdala before any training trials occur in delay conditioning (5 training trials; US onset at 550 ms, US duration = 50 ms, US offset at 600 ms, US level = 1), scalar β_A in the amygdala excitation term in Equation 14 was progressively decreased. The results based on the CS-only presentation during retention testing are presented on a single graph of the variables for sensory cortex (S), orbitofrontal cortex (O), hippocampus (H), amygdala (A), hippocampal adaptive timing (R), and pontine nuclei (P): normal (solid line), 25% decrease (dashed line) and 50% decrease (dotted line). These graphs show a marker for the US presented in training for reference only (vertical dashed lines). The CS is also represented (vertical solid lines). Accurate CR peak amplitude timing as measured by R remained consistent in all cases as *in vivo* but require additional training for improved responses (see Figure 10b). The activity profiles of the pontine nuclei vary with the strength and timing of cortical activity to effect a CR. *In vivo* they are supplemented by learning in the cerebellum, where an adaptively-timed association is made between signals from the tone CS pathway from auditory nuclei to the pons, and from the pons via mossy fiber projections to the

cerebellum, where they are trained by signals from the reflex US pathway from the trigeminal to inferior olive nuclei and then via climbing fibers to the cerebellum (Christian & Thompson, 2003; Fiala, Grossberg, & Bullock, 1996). (b) Simulation after 10 delay conditioning training trials after partial lesions of the amygdala. All other input parameters and output variables are the same as in Figure 10a. The CR peak amplitude improved as measured by *R*. Again, the activity profiles of the pontine nuclei vary with the strength and timing of cortical activity. (c) Simulation of partial lesions of the amygdala before any training trials occur in trace conditioning (20 training trials, US onset at 750 ms, US duration = 50 ms, US level = 1) show that both the CR amplitude and timing as measured by *R* and *P* are negatively impacted: normal (solid line), 25% decrease (dashed line) and 50% decrease (dotted line). The activity profiles of the pontine nuclei (*P*) reflect the experimental data that amygdala is important in trace conditioning. (d) Trace conditioning with amygdala (*A*) ablated 100% after 20 acquisition trials but just before the retention test. On retention test with CS only, normal activity profiles for CS and US in sensory cortex (*S*) and orbitofrontal cortex (*O*) support normal adaptively-timed response in hippocampus (*R*), indicating a time-limited involvement of the amygdala during acquisition. The activity profile of the pontine nuclei (*P*) also supports the simulation of the data that amygdala involvement is time-limited.

The amygdala is required for delay conditioning acquisition, but not for its expression.

The cortico-cortico-cerebellar circuit can execute the timed response after learning.

Simulations of complete amygdala lesions (outputs of Appendix A.4.1, Equation 14 for amygdala and Equation 15 for conditioned reinforcement are both zero) show that there is no CR learned if the lesion is made pre-training, but an acquired CR is retained if the lesion is made post-training (Figure 10d), in agreement with some experimental data (Lee & Kim, 2004; Sosina, 1993) but not all (McGaugh, 2002; Siegel, et al., 2015).

Furthermore, while Buchel et al., (1999) had reported decelerated trace conditioning when amygdala lesions were made before training, simulation of a 50% partial lesion of the amygdala before trace conditioning followed by a retention test after 60 training trials (US onset at 750 ms, US level = 1) still shows severe impairments compared with 20 training trials. Perhaps the lesion is so large that recovery may not be possible at all (Siegel, et al., 2015).

In particular, the amygdala has been found to be unnecessary for fear conditioning acquisition in Pavlovian experimental paradigms in which the aversive US is so negative

that autonomic reflex pathways may control the learning (Lehman et al., 2000; Vazdarjanova & McGaugh, 1998). However, in appetitive learning and instrumental conditioning, the amygdala is always required for acquisition (Cahill & McGaugh, 1990; McGaugh, 2002). This latter property is explained by the model hypothesis that conditioned reinforcer learning and incentive motivational learning both involve the amygdala, and provide positive attentional feedback that supports the rapid category learning required to enable the CS to elicit a CR via the orbitofrontal cortex (Figure 2). Within the dynamics of the nSTART model, this kind of amygdala-mediated motivated attention supports the acquisition of delay and trace conditioning by strengthening adaptively timed attentional shifts based on learned cues. After conditioning, both delay and trace CRs may be mediated more completely by fast cortico-cortical activation of recognition categories via learned cortical weights that serve to activate the adaptively-timed cerebellar motor response without continued need for involvement of the amygdala or the hippocampus.

The nSTART model predicts that, if both amygdala and hippocampus are ablated before or after delay conditioning, then the amygdala lesion most influences delay conditioning, as above. If both amygdala and hippocampus are ablated before trace conditioning, then the model proposes how the hippocampal damage prevents the CR from being learned, because the required cortico-cortical connections that establish long-term memory trace could not be formed using spectral timing as a temporal bridge. Finally, if both amygdala and hippocampus are ablated long enough after trace

conditioning ends, then the model predicts that strong learned cortico-cortical associations will already have formed.

Such cortico-cortical learning, supported by amygdala and hippocampus, is a primary form of memory consolidation in the model, but this form of consolidation does *not* imply that the "same information" is transferred from associative links that involve amygdala and hippocampus to cortico-cortical associations. In addition, the mechanism for memory consolidation that is simulated by nSTART does not propose that memory engrams are quickly learned by the hippocampus and then slowly transferred to the neocortex, as some have proposed, a proposal that seems beset with fundamental difficulties; see Section 5.2. Rather, nSTART demonstrates how hippocampal endogenous activation capable of bridging the temporal gap can energize the strengthening and consolidation of cortico-cortical pathways that are the same pathways that were partially learned before consolidation begins.

For simplicity, the nSTART model lumps amygdala and hypothalamus together, and thus does not simulate how spared hypothalamic connections might enable responding after an amygdala lesion. The MOTIVATOR model (Section 2.3, Figure 4c; Dranias, Grossberg, & Bullock, 2008; Grossberg, Bullock, & Dranias, 2008) explicitly simulates hypothalamic, amygdala, and basal ganglia contributions to conditioning and motivated performance that are consistent with the current results, and that can be incorporated without undermining the current results in a future extended model.

4.5. Trace conditioning with and without hippocampus.

Data from early, intermediate, and late stages of normal trace conditioning trace acquisition trials (McEchron & Disterhoft, 1997; Kim et al., 1995; Takehara et al., 2003) were simulated. In the nSTART model, learning to adaptively time a response to a stimulus is the result of an adaptively timed spectrum of cells (Section 3.5). Figures 11a-e show the spectral activity and output during the simulation after the initial acquisition trial. This process unfolds as follows (see Figure 7 for diagrams of network processing steps and Figure 18 for a complete circuit diagram).

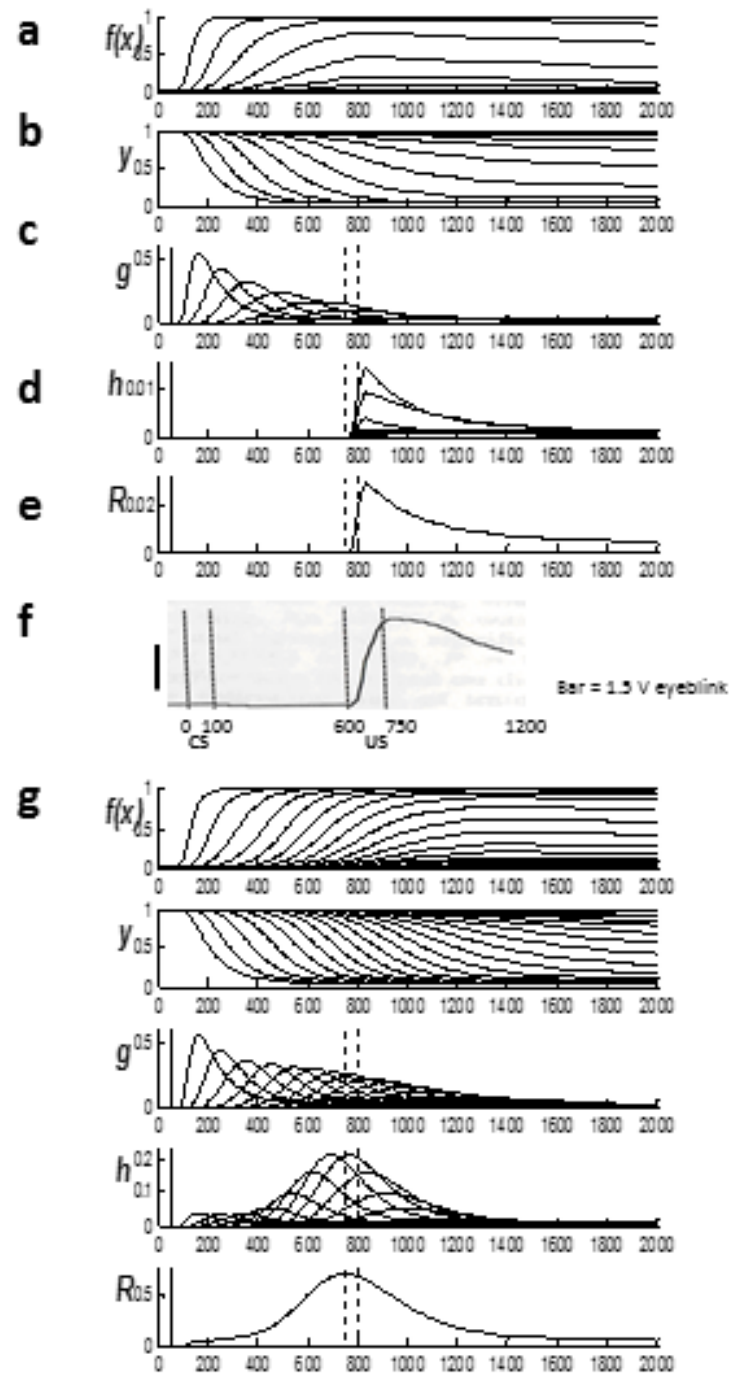


Figure 11. Trace conditioning simulation data. Trace conditioning simulation data from the initial acquisition trial (a-e) compare well with experimental data in (f) that show average voltage measure for

eyeblick response (closure upward) of excitatory hippocampal pyramidal cells during trace conditioning (f). (a) Hippocampal activation spectrum ($f(x_{1j})$, see Equations 19 - 21). (b) Habituated transmitter gates (y_{1j} , Equation 22). (c) Transmitter-Gated signals. ($g_{1j} = f(x_{1j})y_{1j}$, Equation 23). (d) Adaptively timed gated signals ($h_{1j} = 8g_{1j}z_{1j}$, Equation (18)). (e) Population response ($R = \sum_j h_{1j}$, Equation 17) after one training

trial. This curve compares well with: (f) Experimental data showing voltage measures for eyeblink responses averaged across animals for a single day of training, from a study of hippocampal CA1 pyramidal cell activity during trace conditioning. The CS duration is marked by the leftmost vertical dashed lines; the US by the rightmost vertical dashed lines. (g) The hippocampal activation spectrum at retention after 20 conditioning trials. [Data in (f) reprinted with permission from McEchron & Disterhoft (1997).]

As described in Sections 3.5.5, the signals $f(x_{ij})$ are generated by the activities $x_{ij}(t)$ of the j^{th} spectral cell (or cell population) (i, j) in response to the i th input I_i (Appendix A.5.5, Equations 19 - 21, and Figure 11a). Each x_{ij} responds at a different rate r_j to I_i . In particular, we use $i = 1$ to represent the CS and $i = 0$ to represent the US. Thus, $f(x_{1j})$ signals are generated by the CS. They cause the release of chemical transmitters $y_{1j}(t)$ that habituate, or are inactivated, at a rate proportional to their driving signals $f(x_{1j})$ (Appendix A.5.5, Equation 19, and Figure 11b). The transmitters interact with, or gate, their respective signals to generate gated sampling signals g_{1j} that are products of $f(x_{1j})$ and y_{1j} (Figure 11c). These sampling signals g_{1j} are the differently timed responses of cell sites that together form the basis for spectrally timed learning.

Learning of the association between CS and US occurs at each spectral cell site only when its g_{1j} is positive. Thus, each g_{1j} samples learning of US activity that is correlated with it. Both the timing and rate of learning by the adaptive timing weights z_{1j} (Appendix A.5.8, Equation 24) covary with the size of the corresponding g_{1j} . Due to the fact that the various g_{1j} have their peak activities at different times, each site is maximally sensitive to learning correlations with different delays between CS and US.

The signals g_{lj} give rise to adaptively timed outputs $h_{ij} = 8g_{ij}z_{ij}$ wherein the signals g_{lj} are multiplied, or gated, by their adaptive weights z_{lj} (Figure 11d). When the adaptively weighted signals for all spectral components are added together, they form a total population output R that is adaptively timed to peak at, or near, the expected time of US onset. Thus, spectral timing is a property of an entire population of pathways that respond at different rates, no one of which, by itself, adequately represents accurate ISI timing. The hippocampal response after the initial acquisition trial is shown in Figure 11e. Figure 11f shows data of McEchron & Disterhoft (1997) that exhibits similar timing from early acquisition trials. Figure 11g shows simulation output from the retention test after 20 acquisition trials; cf., Figure 8.

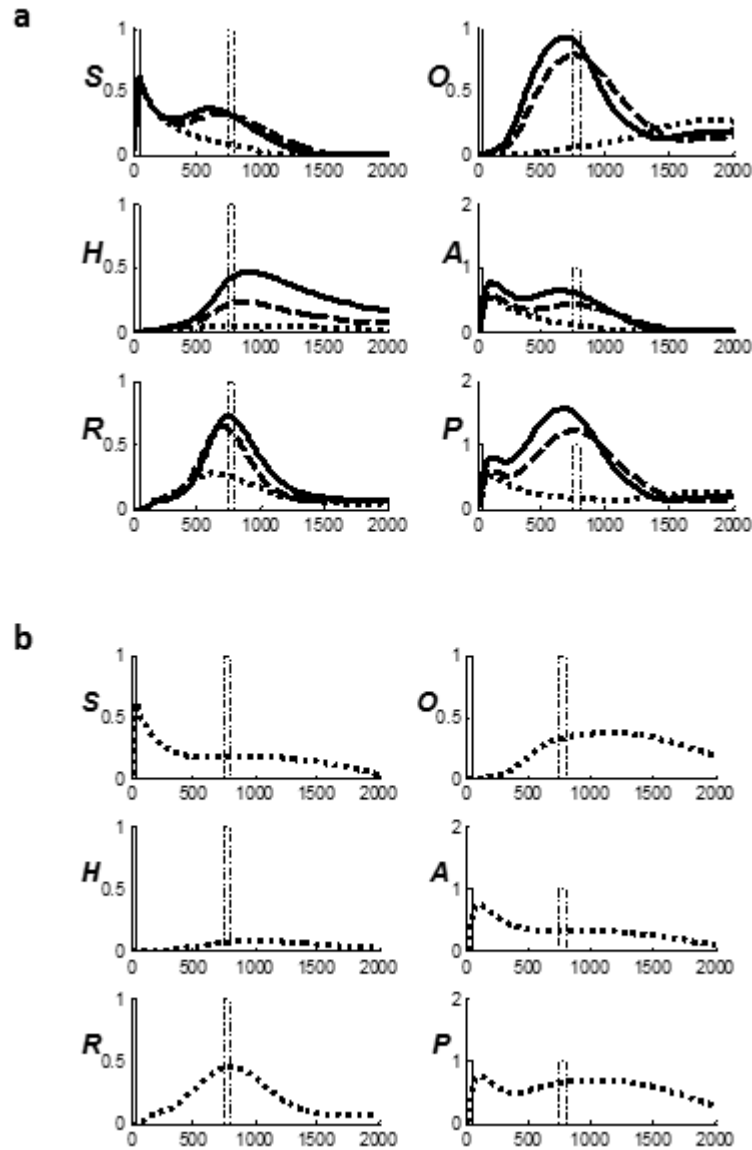


Figure 12. Optimal trace conditioning depends on an intact hippocampus. Optimal trace conditioning depends on adequate hippocampus function. (a) To simulate partial lesions of the hippocampus before any training trials occur in trace conditioning, scalar β_H in the hippocampal excitation term in Equation 16 was progressively decreased. This was followed by 20 training trials, with US onset at 750 ms, US duration = 50 ms, and US amplitude = 1. The results of retention testing are shown for the activities of sensory cortex (S), orbitofrontal cortex (O), hippocampus (H), amygdala (A), hippocampal adaptive timing (R), and the pontine nuclei (P). These graphs show a marker for the US presented in training for reference only (vertical dashed lines). The CS is also represented (vertical solid lines). Compared with normal retention testing results after 20 acquisition trials results (solid line), a 50% decrease (dashed line) gave a small reduction in CR peak amplitude and retained good timing while an 80% decrease (dotted line) caused deficits in both amplitude and timing. (b) While extended training (60 trials rather than 20) with 80% ablation shows minor

improvement in the amplitude and timing of R , the amplitude and timing of P remain too small to support a normal CR. An intact hippocampus is thus required for efficient trace conditioning.

The simulation of the property that trace conditioning depends on an intact hippocampus is shown in Figure 12. The model proposes how a neurotrophic cascade from hippocampus to cortex supports learning of an associative connection between sensory cortex and orbitofrontal cortex in response to CS and US pairing during trace conditioning (Appendix A.3.2, Equation 9). Unless there is enough time to build the cortico-cortical synaptic connections required to consolidate memory, both the timing and amplitude of learning rapidly degrade, as in anterograde amnesia (see Section 4.7). Figure 12a summarizes simulations of how various levels of hippocampal ablation (normal: solid line; 50% ablation: dashed line; 80% ablation: dotted line) cause progressively weaker responses that also become premature after sufficient ablation. These effects are due to the elimination of many, but not all, of the adaptively timed hippocampal cell responses that, taken together, span the ISI, as shown in Figures 11a-e. The duration of this spectral activity is also a key to understanding the role of the hippocampus in trace conditioning and consciousness (see Section 4.7). Even in the case of an 80% lesion, Figure 12b shows that extended training yields some improvement in the timing and amplitude of response indicators for adaptive timing within the hippocampus (R) and the pontine nuclei (P).

The nSTART prediction of when and how the hippocampus is involved in cortical learning was described in Section 3.5 and is illustrated by the simulation results in Figures 13. Figure 13a simulates the property that the establishment of a long-term

memory as a result of trace conditioning requires a critical consolidation period with a normally functioning hippocampus. Figure 13a (first row) compares effects of early hippocampal ablation with delayed hippocampal ablation on orbitofrontal peak amplitude, which provides one measure of the strength of the CR. In the partially trained case with five acquisition trials (first row, left column), a reduction in cortical activity results if the hippocampal ablation is made early (dotted line), immediately after acquisition and before the consolidation period, during which there are no stimulus (NS) trials before the CS, as compared with the activity that is attained after a late ablation (solid line), which is made after the NS trials and just before CS. In contrast, in the fully trained case after 20 acquisition trials (first row, right column), no impairment ensues. There is no difference in orbitofrontal activity between early hippocampal ablation (dotted line) and late hippocampal ablation (solid line) because cortico-cortical connections have already become sufficiently large before the ablation occurs. These simulations are in agreement with experimental data (Kim et al., 1995; McEchron & Disterhoft, 1997; Moyer, et al., 1990; Takehara et al., 2003).

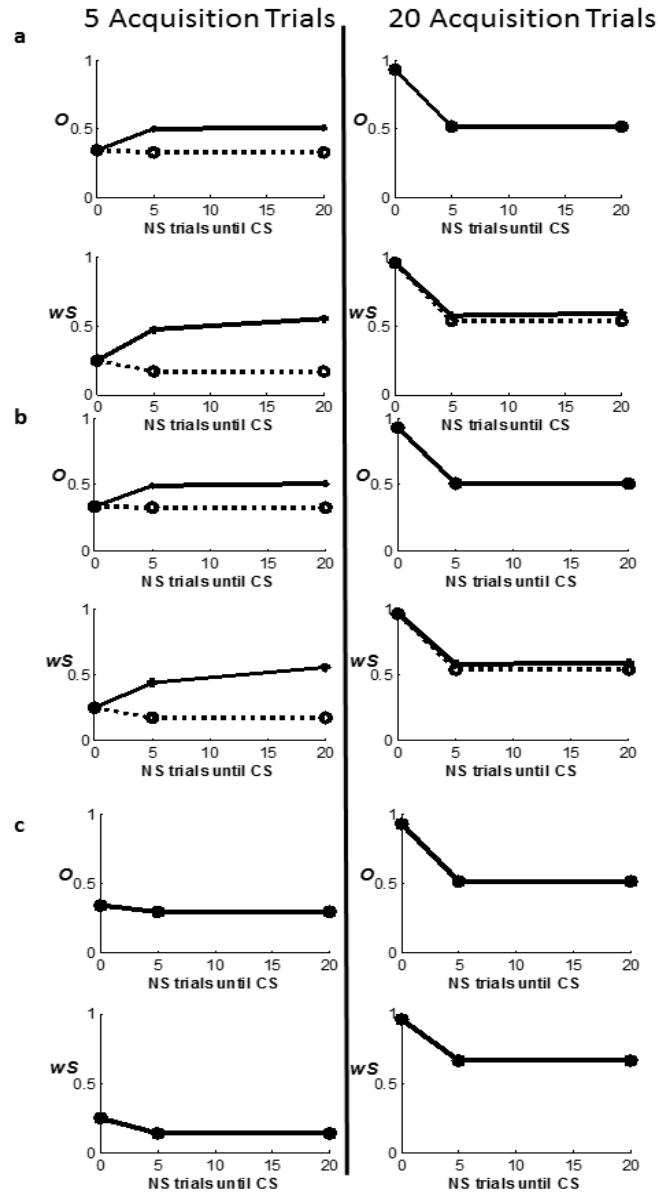


Figure 13. Simulation of consolidation with early versus late hippocampal ablation. Simulations of early versus late hippocampal ablation after trace conditioning trials with US onset at 750 ms, US duration = 50 ms, and US amplitude = 1. There is a critical period after learning trials end that is sensitive to hippocampal ablation, as shown in changes in the peak amplitude of the cortical CR when post-acquisition hippocampal ablation follows learning with 5 acquisition trials (left column; partially trained) and 20 acquisition trials (right column; fully trained). Three cases are simulated: (a) the normal baseline system, (b) with no post-acquisition hippocampal BDNF and (c) with no post-acquisition hippocampal BDNF and no post-acquisition cortical BDNF. In each treatment, training trials are followed by various periods of no

stimulus (NS) trials (durations of inter-trial intervals) with hippocampal ablation either relatively early or late. A retention test with CS presentation follows the NS period. Cortical peak amplitude (first rows) and CS-activated cortico-cortical adaptive weights (second rows) in each simulation are shown for late hippocampal ablation (solid lines) and early hippocampal ablation (dotted lines) for each treatment.

The adaptive weights from sensory cortex to orbitofrontal cortex for each of the cases in Figure 13a (first row) are shown in Figure 13a (second row). In particular, the lower two graphs show cortico-cortical adaptive weights that covary with the orbitofrontal cortical activity for each scenario. After partial training with 5 acquisition trials, early hippocampal ablation prevents an increase in adaptive weight because a critical source of incentive motivational support from the hippocampus is removed before the weight can reach an asymptote (Figure 13a, second row, left column, dotted line). Late hippocampal ablation (Figure 13a, left column, solid line) enables weight learning to benefit from this support. After 20 trials of training to asymptote, hippocampal support is no longer needed (Figure 13a, second row, right column).

It should, however, be emphasized that activation of sensory cortex will continue to activate both the orbitofrontal cortex and hippocampus after learning is complete. This kind of memory consolidation does not imply that the "memory trace" moves from hippocampus to orbitofrontal cortex (cf., Nadel and Moscovitch, 1997).

When hippocampal BDNF is eliminated after acquisition trials (Figure 13b), the simulation results are largely unchanged. However, when both hippocampal and orbitofrontal BDNF are removed after acquisition trials in the partially trained case (Figure 13c, left column), there are the same deleterious effects on orbitofrontal activity (Figure 13c, left column, first row) and on cortico-cortical weights (Figure 13c, left column, second row) for both the early and late ablation treatments, due to the lack of

orbitofrontal BDNF support for consolidation. In the fully trained case (Figure 13c, right column), removal of hippocampal and orbitofrontal BDNF during early and late ablation treatments yield similar orbitofrontal activities (Figure 13c, right column, first row) and cortico-cortical weights (Figure 13c, right column, second row) because consolidation has already occurred. Measures of pontine activity in the model also support this analysis since they are driven by cortical input.

4.6. Delay and trace conditioning with and without thalamus or sensory cortex.

Thalamic lesions negatively affect many types of learning since the thalamus is the gateway to perception and higher-levels of emotional and cognitive processing. Experimental data on thalamic lesions before delay or trace conditioning slow acquisition to some degree (Buchman & Thompson, 1990; Powell & Churchwell, 2002). However, the deficit is greater in trace conditioning than in delay conditioning, since there are then alternate paths available for auditory CS representations to the cerebellum.

The model predicts that lesions to thalamus, with an equivalent effect on sensory cortex, that are made after delay or trace conditioning would also impair retention for two reasons: (1) disruption of stimulus input processing, and (2) damage to the pathways that support cortico-cortical learning of the association between CS and US, which also serve to control CR performance in the post-consolidation stage of learning. Figure 14 shows that general CR acquisition is impaired in proportion to the extent of the lesion, as reflected in the simulated hippocampal response amplitude (R), orbitofrontal cortex (O), and pontine nuclei (P). The simulations show that, as *in vivo* for thalamic lesions, the

disruption to trace conditioning (Figure 14b) is more severe than disruption to delay conditioning (Figure 14a). Extended training (doubling the number of training trials) improves performance for delay conditioning (Figure 14c) but causes little improvement for trace conditioning in the lesion cases, although it does cause improvement in the no lesion case (Figure 14d).

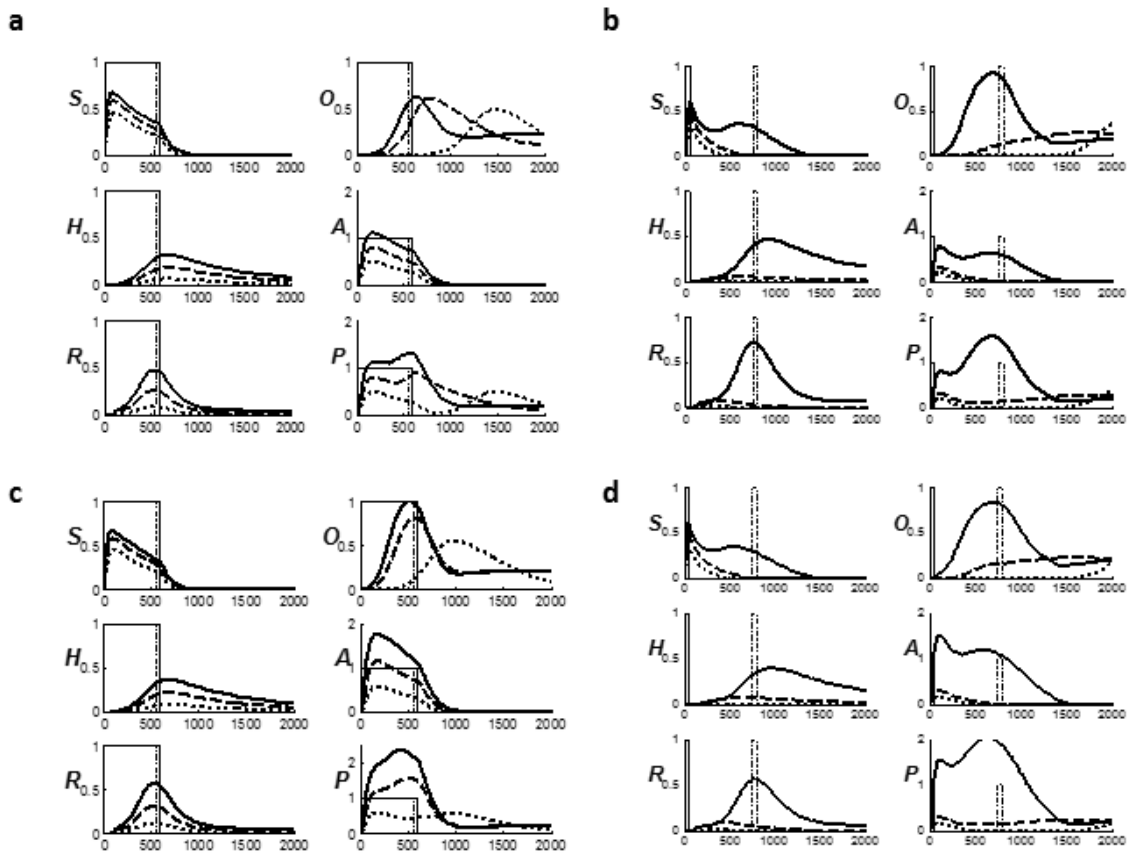


Figure 14. Simulations of sensory cortical or thalamic lesions. Simulations of lesions of the thalamus, with equivalent effects on sensory cortex, demonstrate that the sensory cortex is required for optimal acquisition and retention in both delay and trace conditioning. To simulate partial lesions of the sensory cortex before any training trials occur, scalar β_S in the sensory cortex (Equation 2) was progressively decreased: normal = solid line, 25% decrease = dashed line, and 50% decrease = dotted line. The results of retention testing by CS presentation are shown for sensory cortex (*S*), orbitofrontal cortex (*O*), hippocampus (*H*), amygdala (*A*), hippocampal adaptive timing (*R*), and the pontine nuclei (*P*). Vertical dashed lines mark the time of US presentation during training, but not recall, trials. Vertical solid lines mark the onset and offset of the CS during training trials. Lesions to the sensory cortex weaken learning as a function of the conditioning paradigm and the extent of the lesion, with a special focus on *O* and *P*. (a) Recall after 5 training trials of delay conditioning in all three cases. (b) Worse trace conditioning was seen

in the lesioned cases, even after 20 training trials, than in the corresponding delay conditioning cases in (a). (c) Doubling the number of training trials during delay conditioning to 10 training trials improved performance in all three cases. (d) Doubling the number of training trials during trace conditioning to 40 trials improved performance in the no-lesion case, but had a negligible effect in the two lesioned cases.

4.7. Conditioning, consciousness, and amnesia.

The link between consciousness and conditioning (Clark, Manns, & Squire, 2002) is clarified by contrasting what happens during delay versus trace conditioning in normal and amnesic subjects. The nSTART model requires a sustained interaction of sensory cortex, orbitofrontal cortex, and hippocampus to achieve trace conditioning. From his clinical data from brain-damaged patients, Damasio (1999, pp. 157-158, 195ff, 265) heuristically derived a CogEM-type model and noted that conscious awareness of “the feeling of what happens” relies on a sustained feedback interaction. The nSTART model (Figure 2) builds on the START model (Grossberg and Merrill, 1992, 1996) to explain this sort of data with its prediction that this sort of conscious awareness is supported by a sustained, adaptively timed, cognitive-emotional resonance, which is mechanized as a temporal-amygdala-orbitofrontal resonance that is supported by hippocampal feedback. This specific resonance specializes the ART prediction that “all conscious states are resonant states” (Grossberg, 1999). This explanation clarifies why trace conditioning is facilitated by conscious awareness but delay conditioning is not, why a normal subject may not be consciously aware of delay conditioning, and why amnesics with bilateral hippocampal lesions perform like unaware controls on delay and trace conditioning.

In particular, the emotional path via amygdala operates more quickly than the cognitive path of self-awareness via hippocampus. Furthermore, during delay

conditioning, adaptively-timed responding can be controlled through the cerebellum, so the hippocampus is not a critical component of successful delay conditioning and, thus, neither is awareness.

Recent experiments have supported the CogEM prediction (Grossberg, 1975, 1984) that emotional responses are part of an attentive cognitive-emotional resonance, and that amygdala activity may be influenced by factors such as stimulus valence, attentional load, competing cognitive task demands, and ambiguity (Pessoa, Padmala, & Morland, 2005; Pessoa, Japee, & Ungerleider, 2000). These experimental results are, moreover, consistent with the hypothesis that a sustained cortico-cortico-hippocampal resonance supports consciousness, since parallel hippocampal and amygdala activations occur during normal conditioning. Indeed, adaptively-timed hippocampally timed cognitive-emotional resonances are predicted to help prevent premature reset by the attentional focus on a valued goal object expected disconfirmations by task-irrelevant cues; see Section 2.5 (Grossberg & Merrill, 1992, 1996). A hippocampal role is also consistent with the facts that lesions to the amygdala slow acquisition of delay conditioning, but do not impact already acquired responses (Section 4.4; Lee & Kim, 2004) and that, although amygdala plays a key role in associative learning, researchers also note that: “circuitry within the amygdala (AM) or a closely related structure is necessary for some aspects of the formation, maintenance, or expression of these CRs” (Choi & Brown, 2003, p. 8713).

4.8. Anterograde and retrograde amnesia.

The model clarifies data related to the production of retrograde amnesia due to ablation of the medial prefrontal cortex before, during, or after completion of the consolidation process. Whereas the hippocampus is necessary for the acquisition and consolidation of trace conditioning (Section 4.5)—the lack thereof causes anterograde amnesia and recent retrograde amnesia (Clark, Broadbent, Zola, & Squire, 2002; Clark & Squire, 1998; Gabrieli et al., 1995; McGlinchey-Berroth et al., 1997; but see also Bayley, Frascino, & Squire, 2005)—the medial prefrontal cortex is necessary for the retention of a high percentage of CRs after trace conditioning occurs in normal subjects. In agreement with data (Kronforst-Collins & Disterhoft, 1998), the simulated CR that results when the orbitofrontal cortex is ablated before or after 20 trace conditioning trials shows impaired timing and amplitude in the pontine nuclei responses (Figures 15b and 15d, respectively). Takehara et al. (2003) analyzed this phenomenon as a failure to retain or retrieve memory of the associated adaptive response, and not a simple failure of adaptive timing, because the ablation in their experiments did not affect CR timing. In the nSTART model, the notion that the orbitofrontal cortex provides a critical pathway that helps to read-out the conditioned response via connections to the pontine nuclei is consistent with this retrieval interpretation. In addition, since direct damage to motor cortex does not impair trace eyeblink conditioning (Ivkovich & Thompson, 1997), an alternative interpretation that a motor circuit has failed is not supported.

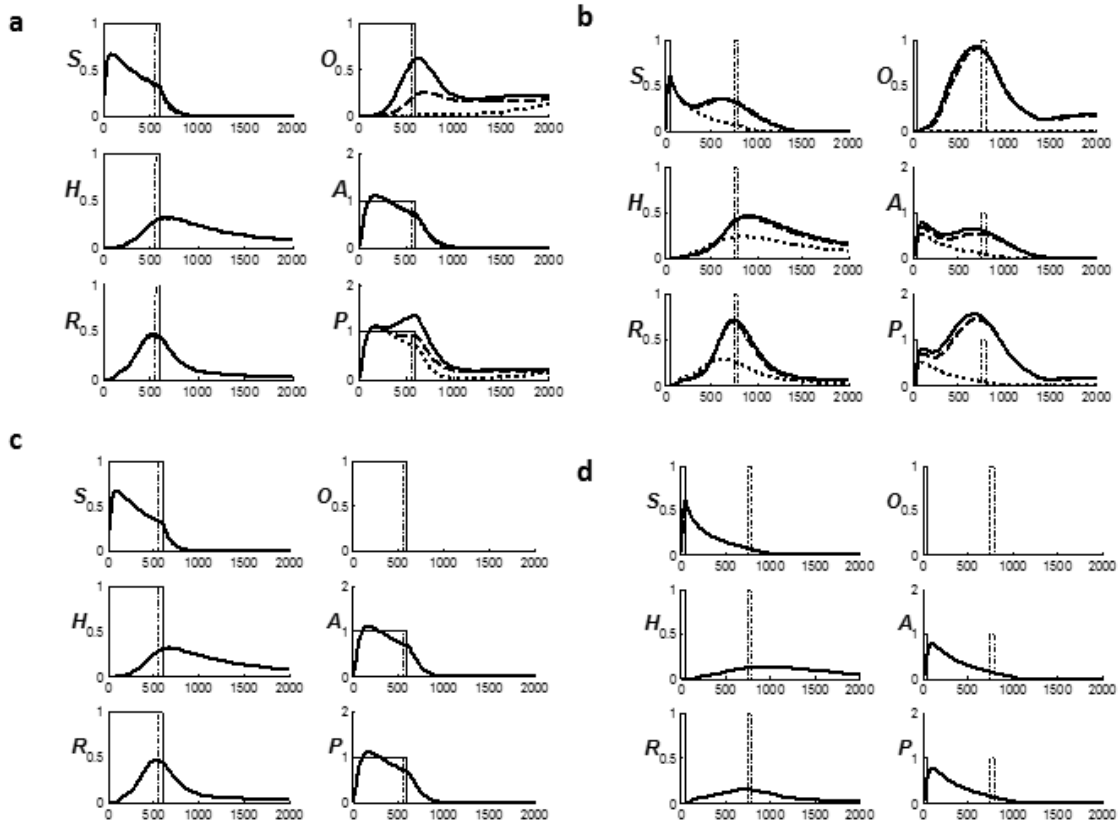


Figure 15. Simulations of orbitofrontal cortical lesions. Pre-training orbitofrontal cortical lesions do not impair delay conditioning as much as trace conditioning. Scalar β_o in the orbitofrontal cortex (Equation 7) was progressively decreased to simulate a lesion. In (a) and (b), the unlesioned normal case = solid line, 5% lesion = dashed line, and 10% lesion = dotted line. The CS and US inputs were chosen as in Figure 14. The results of retention testing due to CS presentation are shown by graphing the activities of sensory cortex (S), orbitofrontal cortex (O), hippocampus (H), amygdala (A), hippocampal adaptive timing (R) and pontine nuclei (P): (a) Delay conditioning with 5 acquisition trials. (b) Trace conditioning with 20 acquisition trials. (c) Complete lesions after delay conditioning with 5 acquisition trials do not impact the ability to perform the CR as reflected in R and P amplitudes, although timing of P is impaired. (d) Complete orbitofrontal lesions after trace conditioning with 20 acquisition trials greatly reduce the ability to perform the CR as reflected in collapsed R and P amplitudes, and a failure of P timing. Thus orbitofrontal cortex is required for performance after trace conditioning in the data and the model.

In the nSTART model, orbitofrontal cortical ablation also interferes with the ability of the CS to sustain the learned cortico-cortical resonance that results in an adaptively timed response profile of the CR in the hippocampus. Indeed, anterograde

amnesia may also result if new memories cannot be consolidated due to cortical insult that prevents, or greatly weakens, such a resonance (see Figure 13c). Figures 15a and 15c show that, when the model orbitofrontal cortex is ablated before or after 5 delay conditioning trials, the CR is not negatively affected, which fits data showing that delay conditioning does not require conscious awareness of the stimulus contingencies (Clark & Squire, 1998; Manns, Clark & Squire, 2001) and that amnesics can learn delay conditioning, but not trace conditioning (Clark, et al., 2001).

The intact hippocampus may also support sustained conscious resonance during normal delay conditioning, but it is not required for the ISI durations in the cited studies: "...those conditioning tasks that require the integrity of the hippocampus are the same tasks that aware participants can acquire and unaware participants cannot..." (Clark & Squire, 2004, p. 1467). In particular, for these ISIs, there may not have been enough time to generate a fully developed conscious cognitive-emotional resonance.

These simulation results display the temporal properties of hippocampal and cortical involvement in normal learning involving declarative memory. Amnesia data properties, such as the loss of recent memory, the inability to form new memory, or the loss of remote memory, are consistent with these dynamics in terms of the age of the memory when processing becomes abnormal: with hippocampal injury, new memories rapidly perish while old memories persist; with cortical injury (Figure 13), new memories might be formed with support from other structures, depending on what cortical structures were damaged, while old memories that critically depend on the cortex perish. Cortical injury may involve the lack of activity in ablated areas, or hyperactivity in the

remaining functioning cells (Li, Bandrowski, & Prince, 2005). In any case, the magnitude of the learning deficit depends on locations and scope of damage. Specific effects of interruption on learning and memory—that is, the type of amnesia—are dependent on the task, the stage of learning, and the specific brain area that is deficient, among other variables. The current model illustrates how lesions of several different brain areas, at different times before, during, or after the course of learning, can differentially contribute to this complex pattern of behavioral deficits.

4.9. Summary of simulation results and experimental data.

In summary, the nSTART model simulates and qualitatively explains key data patterns concerning how thalamic, prefrontal cortical, amygdala, and hippocampal lesions may influence learning and memory. These data patterns are summarized in Table 1, including, for example, the hallmark hippocampal activity profiles over time during delay conditioning (Berger et al., 1980) and trace conditioning (McEchron & Disterhoft, 1997), the role of hippocampal and cortical lesions in influencing acquisition and retention of recently learned versus remotely learned eyeblink responses (Kim et al., 1995; Takehara et al., 2003), and the ability of amnesic individuals to do delay conditioning, but not trace conditioning, along with corresponding differences in conscious awareness (Clark et al., 2001).

<u>Lesions of</u>			
<u>Hippocampus</u>	<u>Before conditioning</u>	<u>Early after conditioning</u>	<u>Late after conditioning</u>
Delay	<i>CR acquisition- YES</i>	<i>CR retention- YES</i>	<i>CR retention- YES</i>
paradigm	Berger, 1984	Akase et al. 1989	Akase et al. 1989
	Chen et al. 1995	Orr & Berger 1985	
	Daum et al. 1989	Port et al. 1996	
	Ivkovich & Stanton 2001	<i>CR retention- NO</i>	
	Lee & Kim 2004	<i>(long ISI)</i>	
	Port, et al. 1983	Beylin et al. 2001	
	Schmaltz & Theios 1972		
	Shors, et al. 1992		
	Solomon & Moore 1975		
	Weizenkratz &		
	Warrington 1979		
Trace	<i>CR acquisition- NO</i>	<i>CR retention- NO</i>	<i>CR retention- YES</i>
paradigm	Anagnostaras et al. 1999	Kim et al. 1995	Kim et al. 1995
	Berry & Thompson 1979	Moyer et al. 1990	Takehara et al. 2003
	Clark & Squire 1998	Takehara et al. 2003	
	Garrud et al. 1984	<i>CR retention- YES</i>	
	Gabrieli et al. 1995	<i>(short ISI)</i>	
	Ivkovich & Stanton 2001	Walker & Steinmetz 2008	
	James et al. 1987		
	Kaneko & Thompson		
	1997		
	Kim et al. 1995		
	Little et al. 1984		
	McGlinchey-Berroth et		
	al. 1997		
	Orr & Berger 1985		
	Power & Disterhoft 1999		
	Schmajuk et al. 1994		
	Schmaltz & Theios 1972		
	Solomon & Moore 1975		
	Solomon et al. 1990		
	Weiss & Thompson		
	1991a&b		

Woodruff-Pak 2001			
<u>Lesions of</u>			
<u>Cortex</u>	<u>Before conditioning</u>	<u>Early after conditioning</u>	<u>Late after conditioning</u>
Delay paradigm	<i>CR acquisition- YES</i> Mauk & Thompson 1987 McLaughlin et al. 2002 Oakley & Russell 1972 Takehara et al. 2003 Yeo et al. 1984	<i>CR retention- YES</i> Oakley & Russell 1972 Takehara et al. 2003 Yeo et al. 1984	<i>CR retention- YES</i> Oakley & Russell 1972 Takehara et al. 2003 Yeo et al. 1984
Trace paradigm	<i>CR acquisition- YES</i> Frankland & Bobtempi 2005 McLaughlin et al. 2002 <i>(short ISI)</i> Oakley & Steele Russell 1972 Simon et al. 2005 Takehara et al. 2003 Yeo et al. 1984 <i>CR acquisition- impaired</i> Kronforst & Disterhoft 1998 McLaughlin et al. 2002 <i>(long ISI)</i> Weible et al. 2000	<i>CR retention- YES</i> Frankland & Bobtempi 2005 Oakley & Steele Russell 1972 Simon et al. 2005 Takehara et al. 2003 Yeo et al. 1984	<i>CR retention- NO</i> Frankland & Bobtempi 2005 Oakley & Steele Russell 1972 Powell et al. 2001 Simon et al. 2005 Takehara et al. 2003 Yeo et al. 1984
<u>Lesions of</u>			
<u>Amygdala</u>	<u>Before conditioning</u>	<u>Early after conditioning</u>	<u>Late after conditioning</u>
Delay paradigm	<i>CR acquisition- YES but decelerated</i> Bechara et al. 1995 Blankenship et al. 2005 Lee & Kim 2004	<i>CR retention- YES but impaired</i> Lee & Kim 2004 McGaugh 2002	<i>CR retention- YES</i> Lee & Kim 2004

Trace paradigm	--Data not found <i>Predict CR acquisition- Yes but decelerated</i>	--Data not found <i>Predict CR retention- Yes</i> Büchel at al. 1999 Chau & Galvez 2012	--Data not found <i>Predict CR retention- Yes</i> Büchel at al. 1999 Chau & Galvez 2012
<u>Lesions of</u>			
<u>Thalamus</u>	<u>Before conditioning</u>	<u>Early after conditioning</u>	<u>Late after conditioning</u>
Delay paradigm	<i>CR acquisition- YES but decelerated</i> Buchanan & Thompson 1990 Halverson & Freeman 2006	--Data not found <i>Predict CR retention- Yes but impaired</i>	--Data not found <i>Predict CR retention- Yes but impaired</i>
Trace paradigm	<i>CR acquisition- YES but decelerated</i> Powell & Churchland 2006	--Data not found <i>Predict CR retention- Yes but impaired</i>	--Data not found <i>Predict CR retention- Yes but impaired</i>

Table 1. Experimental data on eyeblink conditioning with lesions. The specific impact to learning and memory of the conditioned response by lesions of hippocampus, cortex, amygdala, and thalamus is related to the phase of conditioning in which the lesions occur. Representative studies on rats, rabbits, and humans used various experimental preparations and performance criteria yet show patterns of effects on the acquisition and retention of a CR for delay and trace paradigms based on the age of the memory (degree of consolidation).

Additional data support the conclusion that the hippocampus is typically essential during acquisition of trace conditioning, while the neocortex is needed for normal retention. In particular, research in discriminative avoidance conditioning found that hippocampal control of thalamo-cortical excitatory volleys determined timing of CR output during acquisition; otherwise, signals from anterior ventral thalamic nuclei and feedback from

cingulate cortex area 29 determined timing of CR output during maintenance of learning (Gabreil, Sparenborg, & Stolar, 1987). These data support the facts that, while recent Nictitating Membrane Response (NMR) learning involving the trace conditioning paradigm is severely impaired by hippocampal lesions, its acquisition is resistant to cortical lesions. Conversely, NMR trace conditioning retention is not impaired by hippocampal lesions, but it is impaired by cortical lesions (Frankland & Bontempi, 2005; Oakley & Steele Russell, 1972; Simon, Knuckley, Churchwell, & Powell, 2005; Takehara et al., 2003; Yeo, Hardiman, Moore, & Steele Russell, 1984). In cases where the ISI is relatively short, the hippocampus is not required to support acquisition of the CR (Beylin et al., 2001), corresponding to nSTART short-term memory circuits whose persistent activities in both sensory cortical and amygdala representations are capable of bridging short temporal gaps.

The nSTART model proposes how the hippocampus consolidates learning of thalamo-cortical and cortico-cortical associations by using the same adaptively-timed pathways by which the hippocampus learns to adaptively time the appropriate duration of motivated attention in a task-selective manner (Grossberg & Merrill, 1992, 1996). By means of a consolidation process that is driven by BDNF-mediated endogenous hippocampal bursting, which *in vivo* is also driven by continual periodic septal input (Smythe et al., 1992), and BDNF modulation of local, activity-dependent circuits (Schuman, 1999; Thoenen, 1995; Tyler et al., 2002), these associations are stored and recalled in cortico-hippocampal, hippocampo-cortical and cortico-cortical pathways

(Sakurai, 1990), as demonstrated through nSTART computer simulations of the corresponding model pathways and mechanisms.

The fact that amygdala is not required after consolidation of Pavlovian conditioning does not contradict the claim of the CogEM model that amygdala is required for reinforcement learning for CR acquisition and performance. The polyvalent constraint on CogEM during learning is not required for performance in the consolidated case of aversive conditioning because the cortico-cortical connection along with extra-amygdala circuits, such as those involving volitional signals from the basal ganglia, would be sufficient to support performance. Indeed, Chang, Grossberg, and Cao (2014) have shown how such a convergence between cortico-cortical and basal ganglia volitional signals can initiate a directed search for a desired goal object in a cluttered scene, thereby illustrating how the Where's Waldo problem may be solved.

CHAPTER 5. Discussion.

5.1. Five different types of learning interact during conditioning and memory consolidation.

The nSTART model proposes that at least five different types of learning typically occur in parallel to ensure that associations can be formed and consolidated across temporal gaps, as occurs during trace conditioning (Figure 2). As defined conceptually in Section 2, described mathematically in Section 3, and simulated in Section 4, the nSTART model includes: *CS category learning* of the CS-US association via thalamo-cortical and cortico-cortical circuits, *conditioned reinforcement learning* via thalamo-amygdala and sensory cortical-amygdala circuits, *incentive motivational learning* via amygdala-orbitofrontal cortical circuits, and *adaptively-timed learning of motivated attention* via sensory cortical-hippocampal-orbitofrontal cortical circuits. There is also *adaptively-timed learning of motor responses* via the cerebellum, but this is not simulated in the current study. The key brain structures and processes explicitly represented in the nSTART model are summarized in Appendix A.1, Table 2.

5.2. Multiple hippocampal functions: Space, time, novelty, consolidation, and episodic learning.

The nSTART model does not presume to summarize all the functional roles that are played by the hippocampus *in vivo*. The hippocampus is known to participate in multiple functions, including spatial navigation, adaptively-timed conditioning, novelty detection, and the consolidation of declarative (notably, episodic) learning and memory. The hippocampus hereby raises a general issue that is confronted whenever one tries to

understand how a given brain region works: Why does each brain region support a particular combination of processes, rather than a different one? How do these processes interact in a way that makes functional sense of their anatomical propinquity? Related neural models have clarified how some of these other processes work, and why they are near one another anatomically. They are briefly reviewed in this section. The articles that develop these models include citations of many relevant experimental data.

In particular, these models indicate that more than one hippocampal process may be at work in parallel during memory consolidation. This expanded view of memory consolidation is clarified by model explanations of why novelty detection has been linked to the process of memory consolidation during the learning of recognition categories, whether or not this learning needs to bridge a long temporal gap. Adaptive Resonance Theory, or ART, proposes how a memory search can occur during the learning of recognition categories, and how a sufficiently big mismatch between learned top-down expectations and bottom-up feature patterns can activate the novelty-sensitive orienting system (Figure 3), which includes the hippocampus, to drive a memory search for a better matching category. The size of such a mismatch registers how novel the current stimulus is when calibrated against active top-down expectations. ART explains how such memory searches lead to learning of a stable, or consolidated, recognition category that requires no further searches, and thus to the cessation of hippocampal novelty potentials (Figures 3 and 16). After consolidation of a category is complete, presentation of a familiar object exemplar causes direct access to the globally best-matching category via thalamo-cortical and cortico-cortical pathways.

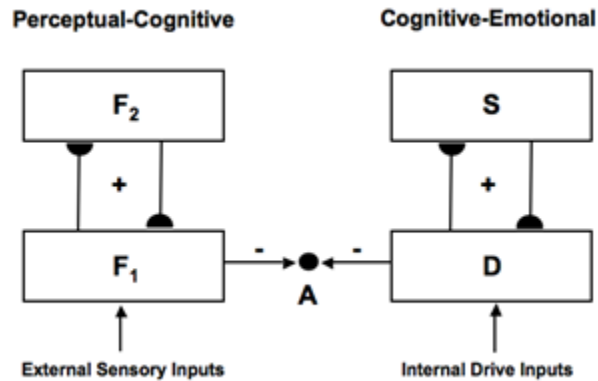


Figure 16. ART circuits for novelty processing. In the START model framework, ART category learning circuits and Spectral Timing circuits can both inhibit the orienting system: When a good enough match occurs between a feature pattern at level F_1 and the top-down expectation from the category level F_2 , inhibition can occur of the orienting system A , thereby preventing a memory search. If inhibition from the cognitive-emotional sensory-drive ($S-D$) resonance that is supported by hippocampal adaptive timing also inhibits A , then the orienting system again cannot fire until the adaptively timed signal is removed. The former mechanism clarifies how hippocampal novelty potentials fade away as thalamo-cortical and cortico-cortical category learning consolidates. The latter mechanism clarifies how orienting responses are inhibited during expected disconfirmations.

Carpenter & Grossberg (1993) and Grossberg (2013) have noted how these properties can qualitatively explain quite a few data about medial temporal amnesia when the model hippocampus is ablated, thereby eliminating memory search during the consolidation process. These properties include unlimited anterograde amnesia, limited retrograde amnesia, perseveration, difficulties in orienting to novel cues, a failure of recombinant context-sensitive processing, and differential learning by amnesics and normals on easy vs. demanding categorization tasks.

Thus, in addition to the important role of *adaptively-timed* hippocampal responses in bridging temporal gaps when events to be associated are separated in time, the hippocampus is also part of the *novelty-sensitive memory search* system for consolidating thalamo-cortical and cortico-cortical category learning. Both of these processes are

included in START model circuits (Figure 6), but without the enhancements that have enabled nSTART to simulate challenging data about early vs. late lesions of amygdala, hippocampus, and orbitofrontal cortex during delay and trace conditioning.

The adaptively-timed hippocampal circuits are part of a larger theory about why both spatial and temporal representations exist within the entorhinal-hippocampal system. Neural models have provided a unified explanation of how these spatial representations (Mhatre, Gorchetnikov, and Grossberg, 2012; Grossberg and Pilly, 2012, 2014; Pilly and Grossberg, 2012, 2014) and temporal representations (Grossberg and Merrill, 1992, 1996; Grossberg and Schmajuk, 1989) may arise in the entorhinal-hippocampal system during development and adult learning, and how they interact with other brain regions to control navigational behaviors and episodic learning and memory. This explanation emphasizes the fundamental role of brain designs for learning, attention, and prediction, and along the way articulates a rigorous mechanistic sense in which the hippocampus is indeed a “cognitive map” (O’Keefe and Nadel, 1978). This learning perspective also leads to the prediction that the network laws that give rise to the apparently very different behavioral properties of space and time are controlled by mechanistically homologous brain mechanisms, thereby clarifying why these spatial and temporal representations both occur in the entorhinal-hippocampal system, and how they can thus more easily interact to control navigation and episodic memory.

The timing model in question is the Spectral Timing model that has been used to explain and simulate data about normal and abnormal delay and trace conditioning (Grossberg & Merrill, 1992, 1996; Grossberg & Schmajuk, 1989). Due to the

computational homolog between spatial and temporal representations, the spatial model is called the Spectral Spacing model (Grossberg & Pilly, 2012, 2014). Both models learn to represent spatial and temporal properties of the environments that animals or humans experience (Gorchetnikov & Grossberg, 2007).

In the case of the Spectral Spacing model, this learning leads to grid cell receptive fields of multiple spatial scales along the dorsoventral axis of the medial entorhinal cortex that cooperate to form hippocampal place cells that can represent large spaces. In the case of the Spectral Timing model, this learning enables “time cells” that response at multiple temporal scales to cooperate to represent large time intervals. As noted in Section 2.4, the Spectral Timing model predicted in the 1980s the properties of time cells that have been reported in the hippocampus during the past few years, notably their Weber law properties. In both the Spectral Spacing and Spectral Timing models, a spectrum of cell rates generates a spatial gradient of cells with different properties. In the case of the Spectral Spacing model, grid cells with increasing spatial scales are learned along the dorsoventral axis of the medial entorhinal cortex. In the case of the Spectral Timing model, time cells with increasing onset times and variances are generated. It has been shown how Spectral Timing can be achieved using properties of the metabotropic glutamate receptor (mGluR) system, which proposes a biochemical basis for the ability of these cells to span such long time intervals (Fiala, Grossberg, & Bullock, 1996). An open question is whether the Spectral Spacing model uses a similar mechanism, suitably specialized?

These homologous spatial and temporal mechanisms have been used to provide a unified theoretical explanation, and quantitative computer simulations, of a body of challenging behavioral and neurobiological data about both space and time that have no other unified explanation at this time, leading to the name *neural relativity* for this mechanistic homology. In particular, the current study proposes how at least some time cells may participate in memory consolidation that requires the ability of the hippocampus to bridge across temporal gaps between stimuli that are associated through conditioning.

The coexistence of spatial and temporal learning in the hippocampus may support its role in episodic learning and memory, since episodic memories typically combine both spatial and temporal information about particular autobiographical events (Eichenbaum and Lipton, 2008; Tulving, 1972). The nSTART model does not include spatial representations, or the prefrontal working memory and list chunking networks for temporary and long-term storage of sequential information, and thus does not attempt to explain data about episodic learning and memory. Activation of such spatially-dependent episodic memories may always require hippocampal spatial representations, so a restricted gradient of retrograde amnesia may not be expected after hippocampal lesions that eliminated them. As noted within the "multiple traces" proposal of how memory consolidation works (Nadel & Moscovitch, 1997, p, 222): "The most parsimonious account of the data would be to assume that the hippocampal complex and neocortex continue to be involved in both the storage and the retrieval of episodic memory traces throughout life".

Episodic memories may depend upon knowledge of *sequences* of correlated object and spatial information, not just information about individual ones. This kind of sequential information is also important for carrying out context-sensitive searches for desired objects in scenes. For example, seeing a refrigerator and a stove at particular positions in a familiar kitchen may generate an expectation of seeing a sink at a different position. A large psychophysical database about contextual cueing (e.g., Brockmole et al., 2010; Chun, 2000; Chun and Jiang, 1998; Jiang and Wagner, 2004; Lleras and von Mühlenen, 2004; Olson and Chun, 2002) describes how both object and spatial information contribute to such expectations, while they drive efficient searches to discover and act upon desired goal objects. The ARTSCENE Search model (Huang & Grossberg, 2010) simulates how computation of spatial and object working memories, list chunks, and spatial and object priming signals may be accomplished using interactions between the perirhinal and parahippocampal cortices (Bar, Aminoff, & Schacter, 2008; Brown & Aggleton, 2001; Epstein, Parker, & Feiler, 2007; Murray & Richmond, 2001), prefrontal cortex, temporal cortex, and parietal cortex to simulate key psychophysical data from contextual cueing experiments. The nSTART, ARTSCENE Search, and Spectral Spacing models may in the future be fused to provide a foundation on which to build a more complete theory of episodic learning and memory.

5.3. Alternative models of memory consolidation.

The popular *unitary trace transfer hypothesis* assumes that there is a memory representation that is first stored in the hippocampus and then transferred to the neocortex to be consolidated (McClelland, McNaughton, & O'Reilly, 1995; Squire & Alvarez,

1995). McClelland, et al. (1995) thus propose “a separate learning system in the hippocampus and why knowledge originally stored in this system is incorporated in the neocortex only gradually” (p. 433). This hypothesis is justified by the assumption that the hippocampus can learn quickly, but the neocortex can only learn slowly, so the hippocampus is needed to first capture the memory and then that same memory representation is transferred to the more slowly learning neocortex. There are, however, fundamental conceptual and mechanistic problems with a unitary trace transfer hypothesis as presented by McClelland et al. (1995) that persist in more recent expositions (Atallah, Frank, & O’Reilly, 2004; O’Reilly & Rudy, 2000): a *representation* problem, a *learning rate* problem, and a *real-time learning* problem. These problems are illustrated by considering how the unitary trace hypothesis might explain how a normal person can see a movie once and remember it well enough to describe it later to a friend in considerable detail, even though the scenes flash by quickly.

The *representation problem* concerns the implicit claim that the hippocampus can represent and store all the remembered visual and auditory memories in the movie. There seems to be no experimental evidence, however, that the hippocampus contains such specialized perceptual representations. Moreover, if the hippocampus did contain all the perceptual representations that were needed to represent all visual and auditory memories, then what does the specialized perceptual circuitry of visual and auditory neocortex do? In this regard, the unitary trace modelers never simulate the perceptual contents of the memories that are assumed to be stored in hippocampus and transferred to neocortex.

The *learning rate problem* concerns the factual basis for the claim that the neocortex must learn slowly. In fact, there are numerous examples that fast perceptual and recognition learning can occur in the neocortex (e.g., Fahle, Edelman, & Poggio, 1995; Kraljic & Samuel, (2006); Sireteanu & Rettenbach, 1995, Stanley & Rubin, 2005; Wagman, Shockley, Reley, & Tervey, 2001). In addition, no evidence is presented by unitary trace transfer theorists that there are slower learning synapses in neocortex than hippocampus. Even one of the proponents of the slow cortical learning hypothesis has equivocated on this point: “data that appear to support the limited cortical learning view tend to be based on larger lesions of the medial temporal lobe...it is becoming clear that the cortex is capable of quite substantial learning on its own...” (O’Reilly & Rudy, 2000, p.395).

The *real-time learning problem* is admitted by the modelers but not solved. A model that has been used in unitary trace model simulations is back propagation. It is well-known that this model is not biologically plausible (e.g., Grossberg, 1988, Section 17). Back propagation must carry out *slow learning*. Its adaptive weights can change only slightly on each learning trial, thus requiring large numbers of acquisition trials to learn every item in its memory. If the learning rate is sped up, then the model can experience catastrophic forgetting. It is incapable of the kind of fast learning that is experienced while watching a movie or other rare but motivationally engaging series of events. It can only carry out supervised learning, which means that an explicit teacher provides external feedback about the correct response on every learning trial, unlike the *unsupervised learning* that is characteristic of many biological learning experiences, including

watching a movie. Its learned weights are computed using an unrealistic *non-local weight transport mechanism* that has no analog in the brain. Finally, because of its slow learning requirement, it is important that the data that are being learned have *stationary statistical properties*, so that each weight gets enough exposure to these properties over many learning trials to enable enough weight growth to occur. In other words, the probabilities of sequential events do not change through time, unlike the world in which we live.

In order to manage these weaknesses of back propagation, McClelland et al. (1995) developed their model based on a process of *interleaved learning* which is said to occur when memories are slowly transferred from the hippocampus to the neocortex via incremental adjustments in the neocortical representations, while being supervised by hippocampal teaching signals. Various sets of parameter values were used to fit their model to each of four data sets with varying degrees of success. Nevertheless, the authors state that such “...interleaved learning systems... are not at all appropriate for the rapid acquisition of arbitrary associations between inputs and responses” (McClelland et al., 1995, p. 432); in other words, their proposed model cannot do learning in real time.

Similar explanatory limitations are faced by connectionist models such as the one proposed by Moustafa, et al. (2013) that does not simulate biophysical properties of neurons, does not use a model that describes the anatomical areas involved in delay and trace conditioning, and does not consider the consolidation process. In addition, this model assumes a non-existent direct connection from hippocampus to motor output.

Beyond the self-criticism offered by McClelland et al. (1995), the unitary trace view of memory consolidation has come under criticism from various researchers on both

theoretical and experimental grounds. McGaugh (2000) points to protein synthesis and various neurotransmitters as providers of endogenous modulation of consolidation. In his view, the supposition that the molecular and cellular machinery of consolidation memory works slowly is “clearly wrong” (p. 248). Rather, consolidation seems slow because on-going experience *modulates* memory strength. In McGaugh's view, the amygdala plays a central role in modulating memories and, thus, in memory consolidation. Lesions of the amygdala disrupt the influence of epinephrine and glucocorticoids from the adrenal gland and, therefore, the consolidation process. In this view, the time-limited role of the hippocampus is to serve as a locus in memory processing in a wider consolidation circuit that includes bidirectional cortico-hippocampal interactions. Nadel and Bohbot (2001) inferred a process of consolidation from retrograde amnesia, but do not see consolidation as a transfer of memory from the hippocampus to other areas. Rather, interactions between systems preserve their respective specializations. All of these heuristic proposals have points of contact within the nSTART model.

Building on the critique of McClelland et al. (1995) given in Grossberg & Merrill (1996), the nSTART model embodies a quite different proposal of hippocampal function than that of the McClelland et al. (1995) model of consolidation. The nSTART model avoids the representation problem because neocortex and hippocampus learn different things. It avoids the learning rate problem because neocortex can learn as fast as sensory inputs and modulatory processes allow. It avoids the real-time learning problem because the fast real-time incremental learning that ART, CogEM, and START allow does not require unrealistic learning mechanisms such as interleaving, and works well in

environments whose statistics can change unpredictably through time (Carpenter & Grossberg, 1991, 1993; Grossberg, 2003, 2007, 2013; Grossberg & Levine, 1987; Grossberg & Merrill, 1992, 1996; Grossberg & Schmajuk, 1987, 1989).

Additionally, the nSTART model proposes how three basic learning problems are solved (Section 1.2): It enables fast motivated attention to be paid to salient objects and events using pathways to and from the amygdala that support conditioned reinforcer and incentive motivational learning (Figures 2 and 4-6). It maintains motivated attention for an appropriate duration on salient objects and events using an adaptively-timed cortical-hippocampal-cortical circuit that also inhibits unwanted orienting reactions (Figure 6). Finally, it prevents premature responses using adaptively-timed cerebellar motor learning (Figures 2 and 17). Thus, the hippocampal influence on cortical learning is not just a transfer of the same memory trace, but rather the result of interactions between multiple types of learning and multiple traces of memory consolidation. An enhanced understanding in nSTART of the role of neurotrophins in the creation and maintenance of memory and the role of attention in the generation of awareness and self-consciousness builds upon this analysis.

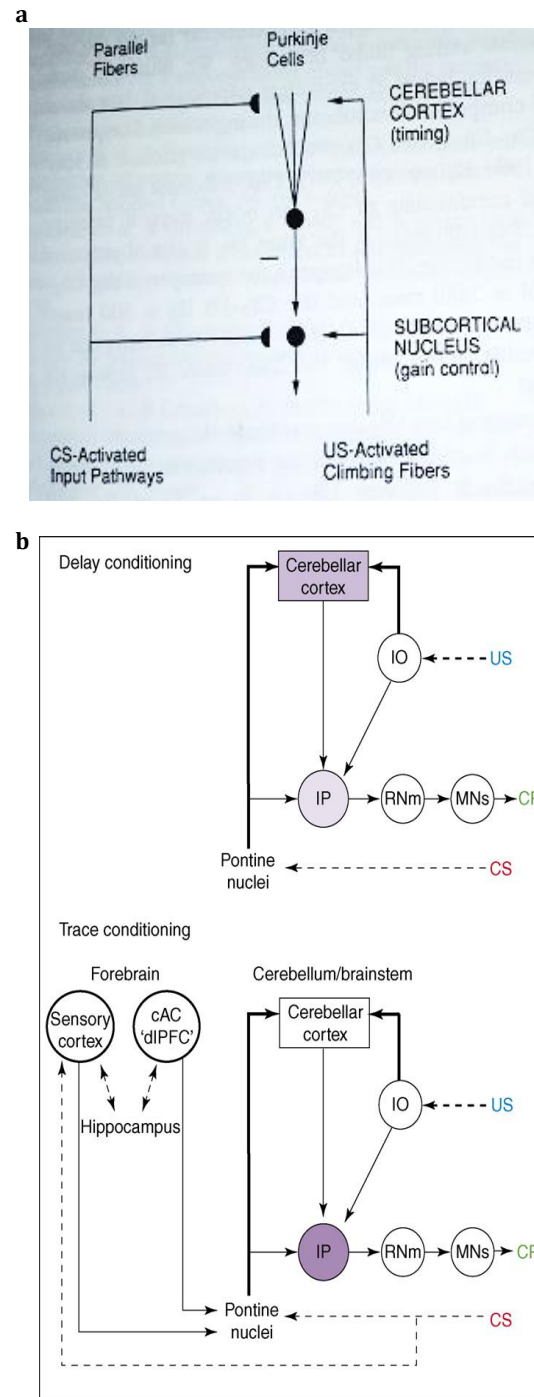


Figure 17. Paths to the cerebellum. (a) START model adaptively timed cerebellar learning circuit: Adaptively timed learning at at cerebellar Purkinje cells causes Long Term Depression, or LTD, of transmission from parallel fibers to Purkinje cells. LTD depresses the level of tonic inhibitory firing of these cells to cerebellar nuclei, thereby disinhibiting nuclear cells and allowing them to read-out their

learned gains in an adaptively timed way to control conditioned motor responses. [Reprinted with permission from Grossberg & Merrill (1996).] (b) Pontine nuclei as a key output pathway from the CS to the cerebellum. Two circuits are presented: delay conditioning only needs the cerebellar circuit; trace conditioning also requires forebrain preprocessing to bridge the temporal gap. [Reprinted with permission from Woodruff-Pak & Disterhoft (2007).]

5.4. Clinical relevance of BDNF.

In line with recent work on the etiology and treatment of neurological diseases such as Alzheimer's, Parkinson's, Huntington's, epilepsy, Rett's syndrome, and neuropsychiatric disorders such as depression, bipolar, anxiety-related, schizophrenia, and addiction (Autry & Monteggia, 2012; Hu & Russek, 2008), the nSTART model is consistent with clinical treatments for impaired cognitive function that implicate an important role for BDNF. In clinical applications, the deleterious effects on synaptic and behavioral plasticity associated with low-levels of BDNF may be reversed by exercise (Molteni et al., 2004), a finding with obvious relevance to educational intervention as well. Treatments that include cognitive and physical exercise have been shown to increase BDNF levels and to relieve symptoms (Cotman & Berchtold, 2002). In addition, BDNF levels, low in proportion to the severity of mania and depression, increase with clinical improvement using antidepressants and mood stabilizers (Post, 2007). However, too much excitation can cause problems and require therapies to down-regulate BDNF and related processes (Birnbaum et al., 2004; Koyama & Ikegaya, 2005). Continued research for more effective and applicable BDNF-based therapies is important in light of the potential BDNF has for successful management of neuropsychiatric disorders (Autry & Monteggia, 2012).

APPENDIX A. Mathematical Equations and Parameters

Appendix A.1. nSTART model overview

nSTART is a real-time neural network with multiple feedforward and feedback connections. On-center off-surround membrane, or shunting, equations with terms for spontaneous decay, input-driven excitation and inhibition, and recurrent excitation and inhibition represent a rate-based approximation to Hodgkin-Huxley dynamics. These equations were integrated over time using the Runge-Kutta 4 method for ODE numerical integration written in MatLab 12.1 running under the Windows 8 operating system on an Intel Quad Core microprocessor. The equations demonstrated the reported qualitative properties over a wide range of parameter choices. Final parameter selection was based on the goal of running all of the simulations using a single set of parameters. Figure 18 shows the mechanistic circuit diagram of the interacting nSTART pathways and processes that were illustrated in Figure 2 and Figure 7 and qualitatively described in Section 3.

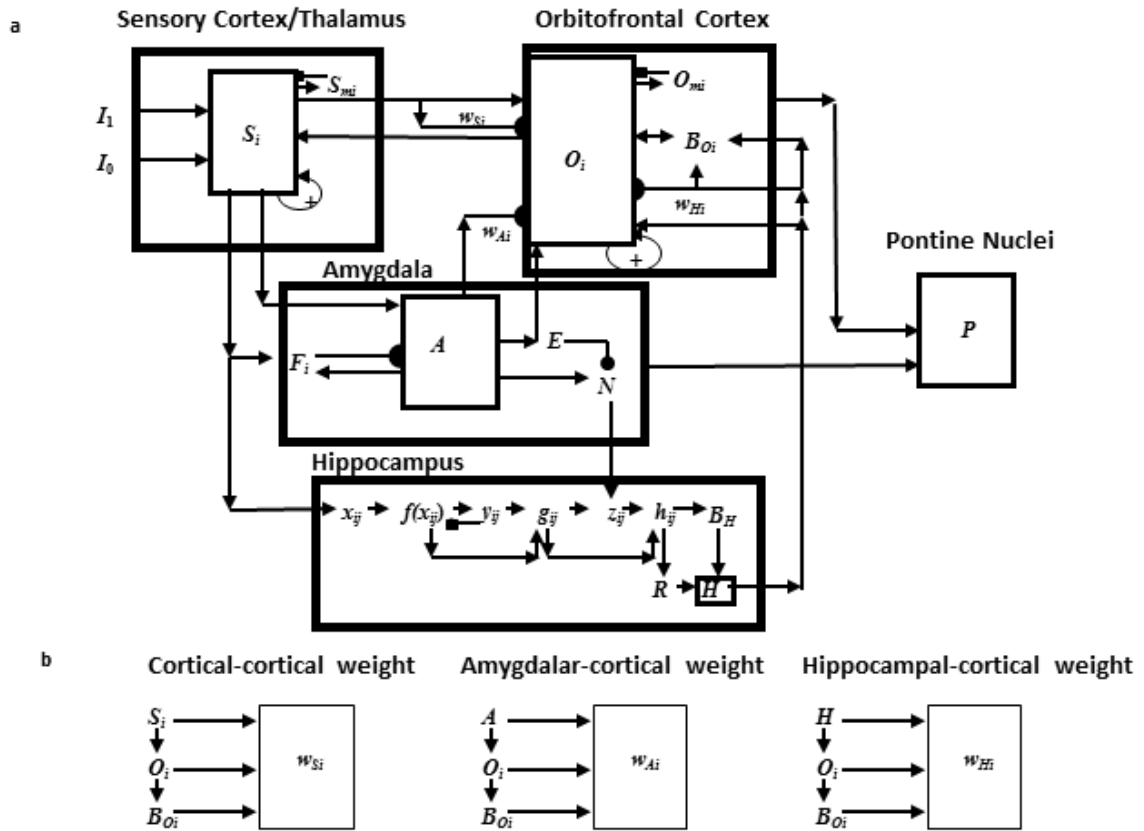


Figure 18. nSTART circuit diagram. Interacting thalamic, prefrontal cortical, amygdala and hippocampal processing circuits control adaptively timed responses in conditioning acquisition and maintenance. The circuit diagram is a composite of the macrocircuit structure given in Figure 2 and the processing detail given in Figure 7. Appendix A contains the mathematical definitions of the circuit variables.

The equations are formally described below. Table 2 presents all system variables and their initial values as well as the parameters with their values.

<u>SYSTEM EQUATION</u>	<u>VARIABLE</u>	<u>VALUE</u>
(2) Sensory Cortical Dynamics	S_i	initial value = 0
	β_s	25
	Conditioned	$I_I = 1$

	Stimulus	
	Unconditioned	$I_0 = 1, 2 \text{ or } 4$
	Stimulus	
	$f_S(S_i)$	See Equation (4)
	O_i	See Equation (7)
	S_{mi}	See Equation (6)
(3) Thalamic Dynamics	T_i	S_i ; See Equation (2)
(4) Signal Functions in the Recurrent On-Center Off-Surround Network	$f_S(S_i)$	initial value = 0 $\max(S_i - 0.02, 0)$
(5) Habituaive Transmitter Gates	N_{mi}	initial value = 1 For sensory cortex (S_{mi}), see Equation (6). For prefrontal cortex (O_{mi}), see Equation (13).
(6) Habituaive Transmitter Gates: Sensory Cortex	S_{mi}	initial value = 1 See Equation (2)
(7) Corticocortical Category Learning	O_i	initial value = 0
	β_0	12.5
	$f_S(S_i)$	See Equation (4)
	w_{Si}, w_{Ai}, w_{Hi}	See Equation (5)
	A	See Equation (14)
	H	See Equation (16)
	B_{Oi}	See Equation (12)

	O_{mi}	See Equation (13)
(8) Prefrontal Cortical Dynamics:	w_{Mi}	initial values = 0.01
Conditioned Weights at Cortical Synapse		No inter-trial reset.
($M = S$ (sensory cortex), A (amygdala) and		
H (hippocampus))		
	$f_M(M)$	If $M=S$, see Equation (9);
		if $M=A$, see Equation
		(10);
		if $M=H$, see Equation
		(11).
	B_{Oi}	See Equation (12)
	O_i	See Equation (7)
(9) Prefrontal Cortical Dynamics:	w_{Si}	initial value = 0.01
Conditioned Weights at Cortical Synapse		
for sensory cortex)		
	$f_S(S_i)$	See Equation (4)
	B_{Oi}	See Equation (12)
	O_i	See Equation (7)
(10) Prefrontal Cortical Dynamics:	w_{Ai}	initial value = 0.01
Conditioned Weights at Cortical Synapse		
for Amygdala		
	A	See Equation (14)
	B_{Oi}	See Equation (12)
	O_i	See Equation (7)
(11) Prefrontal Cortical Dynamics:	w_{Hi}	initial value = 0.01
Conditioned Weights at Cortical Synapse		

for Hippocampus

	H	See Equation (16)
	B_{Oi}	See Equation (12)
	O_i	See Equation (7)
(12) Cortical BDNF	B_{Oi}	initial value = 0 No inter-trial reset.
	H	See Equation (16)
	w_{Hi}	See Equation (11)
(13) Habituated Transmitter Gates: Prefrontal Cortex	O_{mi}	initial value = 1
		See Equation (7)
(14) Amygdala Drive Representation Dynamics	A	initial value = 0
	β_A	40
	$f_S(S_i)$	See Equation (4)
	F_i	See Equation (15)
(15) Conditioned Reinforcer Learning	F_i	constant US: $F_0 = 0.50$,; initial CS: $F_1 = 0.05$. No inter-trial reset.
	$f_S(S_i)$	See Equation (4)
	A	See Equation (8)
(16) Adaptively-Timed Hippocampal Activity	H	initial value = 0
	β_H	5
	R	See Equation (19)
	B_H	See Equation (27)

(17) Adaptively-Timed Population Output Signal	R	
	h_{ij}	See Equation (18)
(18) Doubly Gated Signal Spectrum (timed responses)	h_{ij}	initial value = 0
	$f(x_{ij})$	See Equation (19)
	y_{ij}	See Equation (22)
	z_{ij}	See Equation (24)
(19) Sigmoidal Signal Processing	$f(x_{ij})$	initial value = 0
(20) Activation Spectrum	x_{ij}	initial value = 0
	r_j	See Equation (21)
	$f_s(S_i)$	See Equation (19)
(21) Differential Rates of Spectral Timing	r_j	Range from 0.016 to 0.171
	j	Vary from 1 to 20
(22) Habituate Transmitter Spectrum	y_{ij}	initial value = 1
	$f(x_{ij})$	See Equation (19)
(23) Gated Signal Spectrum	g_{ij}	initial value = 0
	$f(x_{ij})$	See Equation (19)
	y_{ij}	See Equation (22)
(24) Spectral Learning Law	z_{ij}	initial value = 0. No inter-trial reset.
	g_{ij}	See Equation (23)
	N	See Equation (25)
(25) Now Print Signal	N	initial value = 0
	A	See Equation (14)

	E	See Equation (26)
(26) Inhibitory Interneuron	E	initial value = 0
	A	See Equation (14)
(27) Hippocampal BDNF	B_H	initial value = 0.
		No inter-trial reset.
	R	See Equation (17)
(28) Pontine Nuclei	P	initial value = 0
	A	See Equation (14)
	O_1	See Equation (7)

Table 2. nSTART System Equations. nSTART: system equations, variables, and parameters.

The model was tested by simulating data from reinforcement learning experiments, notably classical conditioning experiments. To simplify the model, we use two types of input: I_i , $i \geq 1$, which turns on when the i^{th} CS, CS_i , occurs, and I_0 , which turns on when a US occurs. I_i activates the i^{th} sensory representation S_i . Another population of cells A represents a drive representation in the amygdala. It receives a combination of sensory, reinforcement, and homeostatic (or drive) stimuli. Reinforcement learning, emotional reactions, and motivated attention decisions are controlled by A . During conditioning, presentation of a CS (I_1) before a US (I_0) causes activation of sensory cortical activity S_1 followed by activation of A . Such pairing

strengthens the adaptive weight, or long term memory trace, in the modifiable synapses from S_i to A , and converts CS_i into a conditioned reinforcer. Conditioned reinforcers hereby acquire the power to activate A via the conditioning process. These and other learning and performance processes of the nSTART model are defined by the following equations and parameters.

Appendix A.2. Sensory cortex and thalamus.

Appendix A.2.1. Sensory cortical dynamics.

Cell activity, or voltage $V(t)$, *in vivo* can be represented by the membrane, or shunting, equation:

$$C \frac{d}{dt} V = (V^+ - V)g^+ + (V^- - V)g^- + (V^p - V)g^p, \quad (1)$$

where C is capacitance; the constants V^+ , V^- , and V^p are excitatory, inhibitory, and passive saturation points of V , respectively; and g^+ , g^- , and g^p are conductances that can be changed by inputs (Grossberg, 1968b; Hodgkin, 1964). In the model equations, V is replaced with a symbol that represents the activity of a particular cell (population) in the network. A basic processing unit in the model is a network of shunting neurons that interact within a feedforward and/or feedback on-center off-surround network whose shunting dynamics contrast-normalize its cell activities (Grossberg, 1973, 1980). These networks also have a total activity with an upper bound that tends to be independent of the number of active cells.

The activity S_i of the i^{th} sensory cortical cell (population) obeys a competitive network:

$$\frac{d}{dt}S_i = -15S_i + \beta_S(1-S_i)(I_i + f_S(S_i)(1+O_i))S_{mi} - 15S_i \sum_{k \neq i} f_S(S_k)(1+O_k). \quad (2)$$

The inputs I_i are turned on and off by presentation and termination of a CS input (I_1) or US input (I_0) over time. Term $-15S_i$ describes passive decay of activity S_i . Term $\beta_S(1-S_i)(I_i + f_S(S_i)(1+O_i))S_{mi}$ describes excitatory interactions in response to input I_i , notably the recurrent on-center excitatory feedback signal $f_S(S_i)$ from population S_i to itself (Equation 4), the top-down modulatory attentional input O_i from orbitofrontal cortex, and the habitutive transmitter S_{mi} that depresses these excitatory interactions in an activity-dependent way (Equation 6). Excitation is scaled by parameter β_S . Due to the shunting term $\beta_S(1-S_i)$ in $\beta_S(1-S_i)(I_i + f_S(S_i)(1+O_i))S_{mi}$, activity S_i can continue to grow until it reaches the excitatory saturation point, which is set to 1 in Equation 2. Term $-15S_i \sum_{k \neq i} f_S(S_k)(1+O_k)$ describes lateral inhibition of S_i by competitive feedback signals $f_S(S_k)$ from the off-surround of other sensory cortical activities S_k , $k \neq i$, modulated by the corresponding top-down orbitofrontal signal O_k . Due to the excitatory feedback signals, a brief CS input (I_1) gives rise to a sustained STM activity S_i which can remain sensitive to the balance of signals across the network due to its shunting off-surround, notably by competition from activation in response to the US input (I_0).

The dynamics of (sensory cortical)-to-(orbitofrontal cortical) circuits are modeled (Figure 2). For simplicity, activity levels of thalamus (T_i) and sensory cortex (S_i) are lumped into a single representation:

$$T_i \equiv S_i. \quad (3)$$

With this convention in mind, simulation results may interchangeably mention thalamo-cortical or cortico-cortical connectivity, as required by a given context.

Appendix A.2.2. Signal functions in recurrent on-center off-surround shunting network.

The signal function $f_S(S_k)$ in Equation 2 is a particularly simple faster-than-linear signal function, one that is half-wave-rectified, and then linear above an output threshold: (Grossberg, 1973):

$$f_S(S_k) = [S_i - 0.02]^+ \equiv \max(S_i - 0.02, 0), \quad (4)$$

where 0.02 is the threshold value that must be exceeded for the signal to become positive. Faster-than-linear signal functions tend to suppress noise while contrast-enhancing the most active cell activity and making winner-take-all choices in networks such as (2), as proved in Grossberg (1973).

Appendix A.2.3. Habituated transmitter gates.

Habituated transmitters such as S_{mi} in (2) tend to obey equations of the following general form (Grossberg, 1968, 1972, 1980):

$$\frac{d}{dt} N_{mi} = 0.5(1 - N_{mi}) - 2.5f_N(N_i)N_{mi}. \quad (5)$$

The amount of neurotransmitter N_{mi} in (5) accumulates, scaled by a factor of 0.5, up to a limit of 1 due to the accumulation term $1 - N_{mi}$, and is inactivated, or habituates, by the gated release term $-2.5f_N(N_i)N_{mi}$, whereby N_{mi} is inactivated by mass action at a rate

proportional to the product of an excitatory signal $f_N(N_i)$ from either sensory cortex (Equation 2) or orbitofrontal cortex (Equation 7), and the amount N_{mi} of available transmitter. These modulators are similar to those in the habituated transmitter spectrum for hippocampal cells (Equation 22).

In particular, S_{mi} in (2) obeys:

$$\frac{d}{dt}S_{mi} = 0.5(1 - S_{mi}) - 2.5(I_i + f_S(S_i)(1 + O_i))S_{mi}. \quad (6)$$

S_{mi} accumulates up to a limit of 1 due to the accumulation term $0.5(1 - S_{mi})$, and is inactivated by mass action at a rate proportional to the product of $(I_i + f_S(S_i)(1 + O_i))$, the excitatory term in Equation 2 that the transmitter gates, and the amount of available transmitter S_{mi} . A similar transmitter equation acts within orbitofrontal cortex (Equation 13).

Appendix A.3. Orbitofrontal cortex, category learning, and incentive motivational learning.

Appendix A.3.1. Orbitofrontal cortical dynamics.

The activity O_i of the i^{th} orbitofrontal cortical cell (population) obeys a competitive network with adaptive learning weights:

$$\begin{aligned} \frac{d}{dt}O_i = & -10O_i + \beta_O(2 - O_i)((f_S(S_i) + 0.03)0.0625w_{Si}(Aw_{Ai} + 10Hw_{Hi} + 800B_{Ci}) + 0.75O_i)O_{mi} \\ & - 10O_i \sum_{k \neq i} O_k \end{aligned} \quad (7)$$

In (7), a phasic input from sensory cortex ($f_s(S_i)$, Equation 2), plus a tonic activity of 0.03 (see $f_s(S_i) + 0.03$), is modulated by inputs from the amygdala (A , Equation 14), hippocampus (H , Equation 16), and orbitofrontal BDNF (B_{Oi} , Equation 12). In addition, a recurrent self-excitatory feedback signal (O_i) supports persistence of orbitofrontal activity after the external sensory input is turned off and $f_s(S_i)$ decays to 0. As in Equation 2, there is a passive decay term $-10O_i$, an excitatory shunting on-center term $b_o(2 - O_i)((f_s(S_i) + 0.03)0.0625w_{Si}(Aw_{Ai} + 10Hw_{Hi} + 800B_{Oi}) + 0.75O_i)O_{mi}$ that can increase up to 2, its saturation point, an activity-dependent habituated transmitter gate O_{mi} of excitatory cortical interactions (Equation 7), and a shunting off-surround inhibitory term $-10O_i \sum_{k \neq i} O_k$ that enables contrast normalization. Adaptive weights, or LTM traces, w_{Si} , w_{Ai} , and w_{Hi} (see Equations 8, 9, 10, and 11) gate the inputs $f_s(S_i)$, A , and H , respectively. An excitatory gain of 10 multiplies H and of 800 multiplies B_{Oi} .

Appendix A.3.2. Cortical category learning and incentive motivational learning.

The learned adaptive weights to the orbitofrontal cortex all obey an outstar learning law (Grossberg, 1980), as described in Section 3. The weights from amygdala and hippocampus (w_{Ai} and w_{Hi} , respectively) supply incentive motivational support for cortico-cortical category learning by w_{Si} . All weights obey the general form:

$$\frac{d}{dt}w_{Mi} = 4(f_M(M_i) + B_{Oi})(-w_{Mi} + 2O_i), \quad (8)$$

where $M = S, A$, or H , depending on the context.

Learned adaptive weights from sensory cortex to orbitofrontal cortex obey:

$$\frac{d}{dt}w_{Si} = 4(f_s(S_i) + B_{Oi})(-w_{Si} + 2O_i), \quad (9)$$

where learning is gated on and off by a sampling signal $f_s(S_i) + B_{Oi}$ that is the sum of the sensory cortical signal $f_s(S_i)$, (Equation 4) and the orbitofrontal BDNF B_{Oi} (Equation 12). The sampling signal's size determines the rate at which weight w_{Si} approaches twice the orbitofrontal activity O_i (Equation 7) via term $-w_{Si} + 2O_i$.

Learned adaptive weights from amygdala to orbitofrontal cortex obey:

$$\frac{d}{dt}w_{Ai} = 4(0.1A + B_{Oi})(-w_{Ai} + 2O_i) \quad (10)$$

and from hippocampus to orbitofrontal cortex obey:

$$\frac{d}{dt}w_{Hi} = 4(0.5H + B_{Oi})(-w_{Hi} + 2O_i). \quad (11)$$

Appendix A.3.3. Orbitofrontal BDNF.

Orbitofrontal BDNF B_{Oi} is time-averages hippocampal signals H that are gated by learned weights w_{Hi} with an excitatory gain 3.125:

$$\frac{d}{dt}B_{Oi} = -B_{Oi} + 3.125Hw_{Hi}. \quad (12)$$

Appendix A.3.4. Habituate transmitter gates in orbitofrontal cortex.

Activity-dependent habituate neurotransmitters, or postsynaptic sites, O_{mi} that influence orbitofrontal cortical activity obey a specialized version of (5):

$$\frac{d}{dt}O_{mi} = 0.5(1 - O_{mi}) - 2.5((f_S(S_i) + 0.03)0.0625w_{Si}(Aw_{Ai} + 10Hw_{Hi} + 800B_{Ci}) + 0.75O_i)O_{mi},$$

(13)

that accumulates to a maximum value of 1 at rate 0.5 via term $0.5(1 - O_{mi})$, and

habituates, or is inactivated, at rate

$- 2.5((f_S(S_i) + 0.03)0.0625w_{Si}(Aw_{Ai} + 10Hw_{Hi} + 800B_{Ci}) + 0.75O_i)$ by the on-center input term in (7).

Appendix A.4. Amygdala and conditioned reinforcer learning.

Appendix A.4.1. Amygdala drive representation dynamics.

The amygdala activity A of the drive representation obeys:

$$\frac{d}{dt}A = -20A + b_A(10 - A)\sum_i f_S(S_i)F_i. \quad (14)$$

Activity A passively decays via term $-20A$. Term $\beta_A(10 - A)\sum_i f_S(S_i)F_i$

describes the sum of excitatory signals $f_S(S_i)$ from the i^{th} sensory representation to A ,

gated by the conditioned reinforcer adaptive weights F_i (Equation 15). This sum can

increase A until it reaches the saturation term 10 that is determined by term $(10 - A)$.

Adaptive weight F_i determines how well S_i can activate A , and thus the extent to which

the i^{th} CS has become a conditioned reinforcer through learning. Because F_i multiplies

$f_S(S_i)$, a large S_i will have a negligible effect on A if F_i is small, and a large effect on

A if F_i is large. The US LTM trace F_0 is fixed at a relatively large value to enable the

US to activate A via S_0 and to thereby drive conditioned reinforcer learning when a CS is also active. The CS LTM trace F_1 is initially set to one tenth of the US value to prevent the CS from significantly activating A before conditioning takes place.

Appendix A.4.2. Conditioned reinforcer learning.

Each adaptive weight F_1 obeys an outstar learning law:

$$\frac{d}{dt} F_1 = 0.5 f_s(S_i)(-F_1 + 0.2A). \quad (15)$$

Learning by F_1 is turned on and off by the sampling signal $0.5 f_s(S_i)$, whose size determines the rate at which F_1 time-averages $0.2A$. Activity F_1 can increase or decrease during learning, hence both long-term potentiation (LTP) and long-term depression (LTD) can occur. To represent the non-learned response to the US, F_0 is held constant at 0.5.

Appendix A.5. Hippocampus and adaptively timed learning.

Appendix A.5.1. Adaptively-timed hippocampal learning.

As noted in Section 3.5.1, the hippocampus delivers adaptively timed signals H to the orbitofrontal cortex that can maintain its activity for a duration that can span the trace interval; see Equation 6. The hippocampus hereby activates an adaptively-timed incentive motivational pathway in cases when the amygdala cannot, as described in Section 3.4.1. The spectral timing process embodies several processing steps.

Appendix A.5.2. Adaptively-timed hippocampal activity.

Activity H in the hippocampus obeys:

$$\frac{d}{dt}H = -15H + b_H(2 - H)(0.625R + 0.5B_H). \quad (16)$$

Term $-15H$ represents passive decay. The excitatory term is scaled by the excitatory gain β_H and bounded by 2, due to the shunting term $\beta_H(2 - H)$. The two sources of excitatory input are the adaptively timed input R (Equation 17) and the total BDNF input B_H (Equation 27), each with its own gain term.

Appendix A.5.3. Adaptively-timed population output signal.

The adaptively timed signal R is a population response:

$$R = \sum_{i,j} \dot{a}_{ij} h_{ij} \quad (17)$$

that sums over multiple individually timed signals

$$h_{ij} = 8f(x_{ij})y_{ij}z_{ij} \quad (18)$$

that are defined below. None of the signals h_{ij} individually can accurately time the ISI between a CS and US. The entire population response in (17) can do so using a “spectrum” of differently timed cells, leading to the term “spectral timing” for this kind of learning (Grossberg and Merrill, 1992, 1996; Grossberg and Schmajuk, 1989).

Appendix A.5.4. Activation spectrum.

Model simulations use the simplest embodiment of spectrally-timed learning. A more detailed biochemical model is given using Ca^{++} -modulated learning by a spectrum of metabotropic glutamate receptor (mGluR) cell sites in Fiala, Grossberg, & Bullock (1996), which shows how mGluR dynamics can span such long time intervals.

Spectrally timed learning can be initiated when an input signal $f_s(S_i)$ (Equation 4) from a sensory cortical representation (Equation 2) activates a population of hippocampal cell sites with activities x_{ij} that activate the next processing stage via sigmoidal signals:

$$f(x_{ij}) = \frac{x_{ij}^8}{0.01^8 + x_{ij}^8}. \quad (19)$$

Activities x_{ij} react at a spectrum of rates:

$$\frac{d}{dt}x_{ij} = r_j(-x_{ij} + (1 - x_{ij})f_s(S_i)), \quad (20)$$

with rates r_j ranging from 0.171 (fast) to 0.016 (slow) defined by:

$$r_j = 5.125 / (0.0125 + 15(j+1)), \quad (21)$$

for $j = 1$ to 20.

Appendix A.5.5. Habituated transmitter spectrum.

Each spectral activation signal $f(x_{ij})$ is gated by a habituated chemical transmitter, or postsynaptic response, y_{ij} that obeys:

$$\frac{d}{dt}y_{ij} = 0.5(1 - y_{ij}) - 10f(x_{ij})y_{ij}. \quad (22)$$

As in Equation 5, y_{ij} accumulates to 1 via term $(1 - y_{ij})$ at rate 0.5, and habituates, or inactivates, due to a mass action interaction with signal $f(x_{ij})$, via the gated release term $-10f(x_{ij})y_{ij}$. The different rates r_j that activate each x_{ij} cause the habituated transmitters y_{ij} to become habituated at different rates as well. The family of curves y_{ij} , $j = 1, 2, \dots, 20$, is called a habituation spectrum.

Appendix A.5.6. Gated signal spectrum and time cells.

Each signal $f(x_{ij})$ interacts with y_{ij} via mass action to generate a net output signal from its population of cell sites that obeys:

$$g_{ij} \circ [f(x_{ij})y_{ij} - 0.03]^+ \circ \max(f(x_{ij})y_{ij} - 0.03, 0). \quad (23)$$

Each gated signal g_{ij} has a different rate of growth and decay, thereby generating a unimodal function of time that achieves its maximum value M_{ij} at time T_{ij} , where T_{ij} is an increasing function of j , and M_{ij} is a decreasing function of j . Taken together, all the functions g_{ij} define the gated signal spectrum in Figure 11c. This timed spectrum is the basis of adaptively timed learning over an extended time interval that can range from hundreds of milliseconds to several seconds, with each g_{ij} acting as the sampling signal for its part of the adaptively timed spectrum.

Appendix A.5.7. Spectral learning law.

Each adaptive weight z_{ij} in the spectrum obeys an outstar learning law:

$$\frac{d}{dt} z_{ij} = 2g_{ij}(-z_{ij} + 2N). \quad (24)$$

In Equation 24, g_{ij} is a sampling signal that determines the rate with which z_{ij} samples a transient Now Print signal $2N$ (Equation 25) that is derived from amygdala activity A in Equation 14. Each z_{ij} changes by an amount that reflects the degree to which the curves g_{ij} and N have simultaneously large values through time. If g_{ij} is large when N is large,

then z_{ij} increases in size. If g_{ij} is large when N is small, then z_{ij} decreases in size. Since the different g_{ij} peak at different times, each z_{ij} responds to N to different degrees.

The Now Print signal N obeys:

$$N = [A - E - 0.04]^+ \circ \max(A - E - 0.04, 0), \quad (25)$$

where E is a feedforward inhibitory interneuron that obeys:

$$\frac{d}{dt}E = 40(-E + A). \quad (26)$$

The inhibitory interneuronal activity E in (26) time-averages the amygdala activity A at rate 40. Its activity hereby lags behind that of A . The difference $(A - E)$ in (25) may thus be activated by any sufficiently rapid increase in A . Either a US, or a CS that has become a conditioned reinforcer, can cause such a rapid increase, and thereby activate N , and thus learning of any adaptive weight z_{ij} whose sampling signal g_{ij} is sufficiently large at such a time.

An important property of N is that it increases in amplitude, but not significantly in duration, in response to larger inputs A . Thus learning can be faster in response to stronger rewards, but the timing of a conditioned response does not significantly change, as in the data and our simulations thereof (Figure 8).

Appendix A.5.8. Doubly-gated signal spectrum.

Each long-term memory trace z_{ij} learns to a different degree. Each z_{ij} also gate the signals g_{ij} in order to generate a twice-gated output signal h_{ij} (Equation 18) from each of the differently timed cell sites. Comparing the signals h_{ij} in Figure 11d with

the g_{ij} in Figure 11c shows how adaptively timed learning changes the relative strength of each spectral output. When all the h_{ij} are added together to generate the population output R in (17), accurate adaptively timing is achieved.

Appendix A.5.9. Hippocampal BDNF.

Production of hippocampal BDNF B_H is a time average of 25 times its adaptively timed population signal R (Equation 17), scaled by a reaction rate of 2:

$$\frac{d}{dt}B_H = 2(-B_H + 25R). \quad (27)$$

Hippocampal BDNF in the model extends hippocampal activation, and thus the incentive motivational support that it supplies to cortico-cortical learning during a memory consolidation period after the CS and US inputs terminate.

Appendix A.6. The Pontine Nuclei.

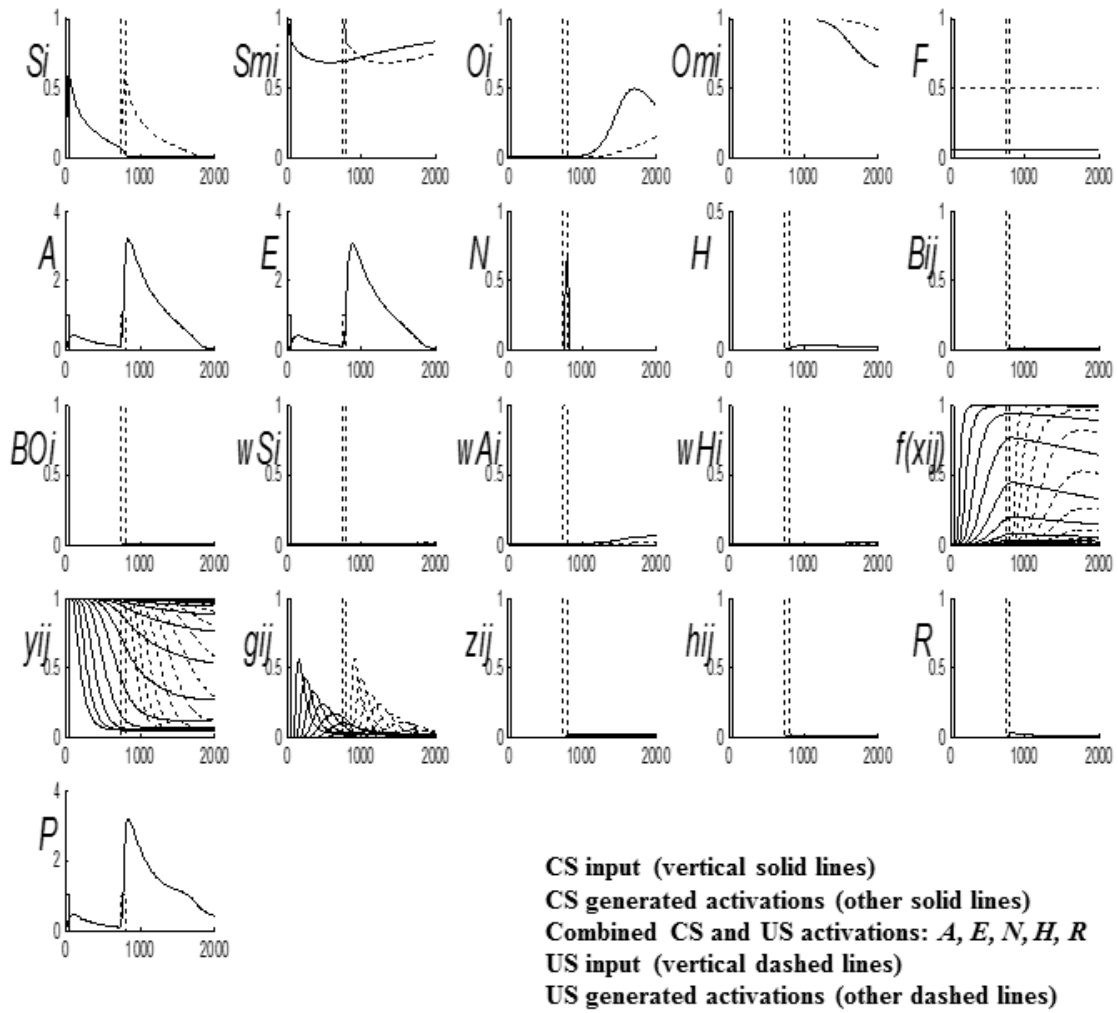
Appendix A.6.1. Final common path for conditioned output.

Output signals from the amygdala A (Equation 14) and the CS-activated orbitofrontal cortical representation O_1 (Equation 7) to the pons combine to form a common final path that is used in the model as a signal that generates a behavioral CR further downstream (see Section 3.6):

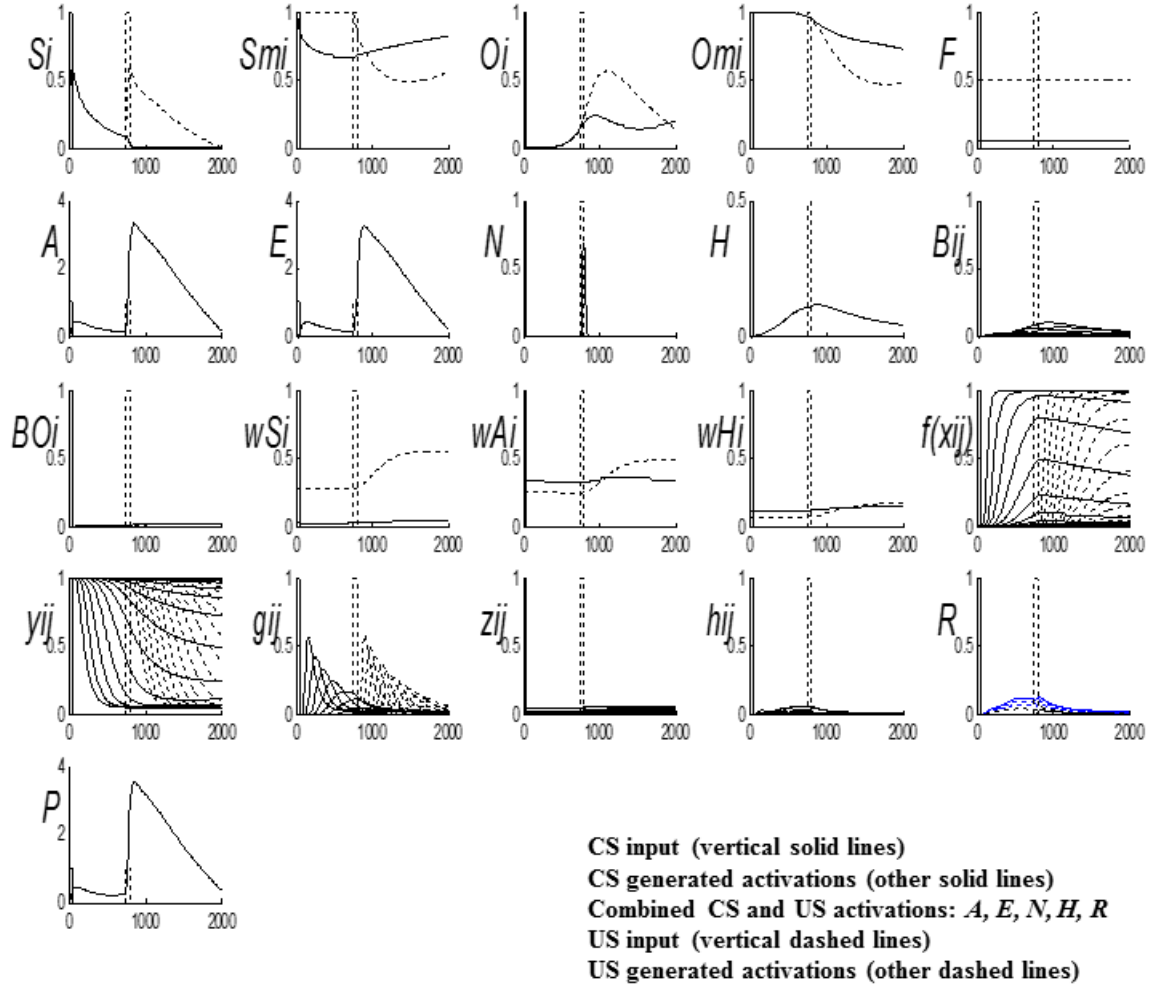
$$P = A + O_1. \quad (28)$$

APPENDIX B. Time Course of nSTART Variables during Trace Conditioning

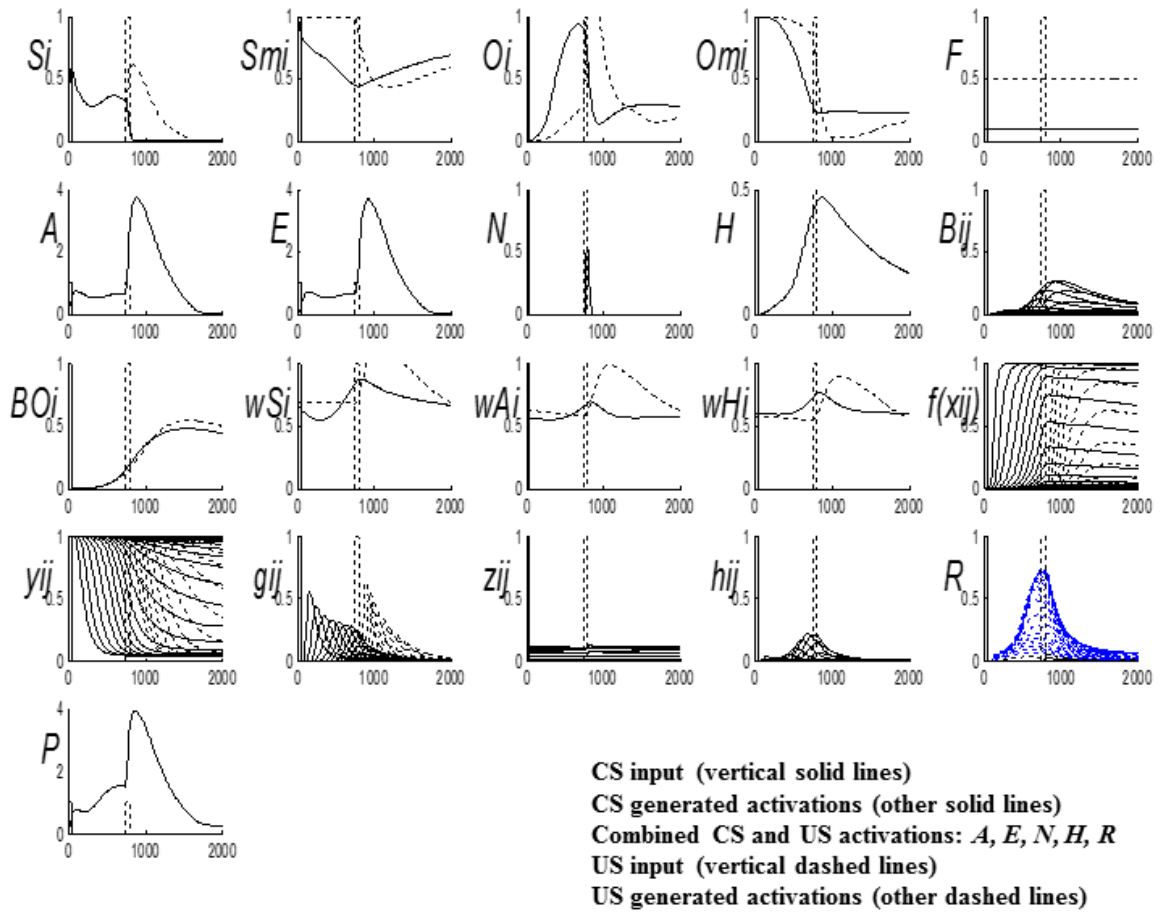
Appendix B.1. Trace conditioning during acquisition on 1st training trial



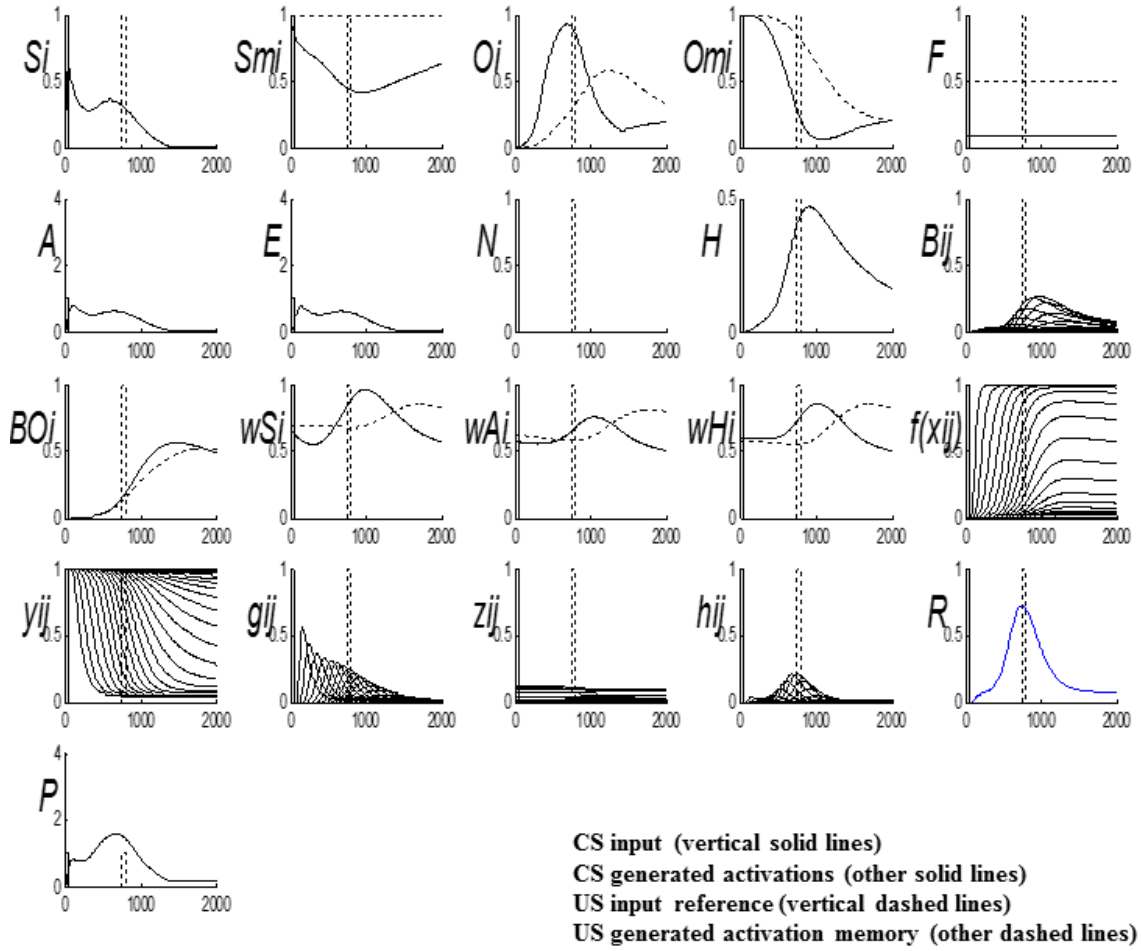
Appendix B.2. Trace conditioning during acquisition on 5th training trial



Appendix B.3. Trace conditioning during acquisition on 20th training trial



Appendix B.4. Trace conditioning during retention test after 20 training trials



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CURRICULUM VITAE

Daniel J. Franklin

20 Puritan Park Swampscott, MA 01907

Home: 781-598-4487 Mobile: 617-388-5989 E-mail: d.j.franklin@live.com

[linkedin.com/pub/dan-franklin/13/a87/b9](https://www.linkedin.com/pub/dan-franklin/13/a87/b9)

INTERESTS: Neural network models of perception, cognition, emotion and action. Data mining with neural networks. Application of neuroscience to education and business.

EDUCATION

Boston University, Boston, MA: PhD (Cognitive & Neural Systems).

Boston University, Boston, MA: MBA (Statistics and Organizational Design).

Harvard University, Cambridge, MA: MTS (History of Religion and Public Education).

Member: Committee on Academic Policy; Admissions Committee.

Williams College, Williamstown, MA: BA (Comparative Religion).

PROFESSIONAL SOCIETIES

American Statistical Association

American Educational Research Association

Learning & Brain Society

International Mind, Brain & Education Society

International Neural Network Society

National Council of Teachers of Mathematics

Project Management Institute

Society for Neuroscience

TEACHING EXPERIENCE

- | | |
|---------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Aug 2016 – present | Director of Mathematics, Everett Public Schools. Everett, MA.
Direct, supervise, and coordinate the math curriculum, instruction and assessment for 7,000+ urban students by data-driven teacher support and evaluation, research-based professional development, and program assessment and improvement. |
| Jan 2004 – present | Adjunct Faculty North Shore Community College, Danvers, MA
Courses: Introduction to Statistics; Mathematics for Elementary School Teachers. |
| Jun 2006 – Jul 2009 | Director, Boston University Boston, MA. NSF Summer Workshops for Teacher Professional Development |

Sep 2002 – May 2005 Teacher, Massachusetts Public Schools: Marblehead (2004-2005)
High School Mathematics. Advisor, Science Team. Revere (2002-2004) Middle School and High School Math.

GRANTS, AWARDS

Valedictorian, Revere High School, 1970
Phi Beta Kappa, Williams College, 1973
Boston University Deans Award, 2008, 2009
Research supported in part by CELEST, an NSF Science of Learning Center (NSF SBE-0354378).

SKILLS

Management by Continuous Process Improvement

Leadership through positive employee and organizational development; Collaborative innovation using data with Scrum/Agile management; Strategic planning, application portfolio management, and program oversight; Tactical project management, problem resolution, and risk management; Financial control and cost/benefit analysis; operations and development trade-offs; Design and implement metrics for delivery and performance of products/services; Benchmark, gap-analysis, and recommended action plans across diverse groups; Rollout new processes, technologies and business applications at multiple sites; Design and delivery of reusable software components; Design/deliver corporate training for programmers, and business management; Contract negotiation, vendor management, grant management

Technical

- Mainframe and client server application development and testing software
- SAS, MatLab, Predict (Neural Networks), Tableau
- ExamView, Angel, Blackboard, SCORM, Tin Can
- FileMaker Pro, Turning Technologies Audience Response Systems
- MS Office (Word, Excel, PowerPoint, Access, Project), Adobe CS4, SharePoint, Google tools, WebEx, Skype

PRESENTATIONS

Franklin, D.J. (2012). Games and activities based on whole-brain learning. National Council of Teachers of Mathematics (NCTM) Regional Meetings: Dallas, Hartford, and Chicago. October and November.

Franklin, D.J. (2011). The whole-Brain approach to mathematics learning for children. National Council of Teachers of Mathematics (NCTM) Regional Meetings: Albuquerque, Atlantic City, and St. Louis. October and November.

Franklin, D.J. (2011). The whole-brain approach to curriculum and pedagogy. Workshop. Annual Title I Conference. Marlborough, MA. March.

Franklin, D.J. (2009). Learning statistics through models of mind and brain. Workshop. 35th Annual Meeting of the New England Mathematical Association of Two Year Colleges. Southern New Hampshire University, Manchester, NH. April.

Franklin, D.J. (2009). Learning mathematics and science using models of mind and brain. Poster. Intensive Immersion Institute Conference in Mathematics and Science. Lowell, MA. March.

Franklin, D.J. (2009). Neural network modeling: Seeing principles and methods through models of vision. Second Annual iSLC Student/Postdoctoral Fellow Conference. Workshop. Seattle, Washington. February.

Franklin, D.J. (2007). Curriculum content and pedagogy based on models of mind and brain. International Mind, Brain, and Education Society (IMBES). Fort Worth, Texas, November.

Franklin, D.J., & Grossberg, S. (2005). A neural model of normal and amnesic learning and memory: Conditioning, adaptive timing, neurotrophins, and hippocampus. First Annual Conference on Computational Cognitive Neuroscience (CCN), Washington DC. November.

PUBLICATIONS

Franklin, D.J. (2012). The Way of the Game: A Case Study in the Use of Adaptive Interaction Design for Early Mathematics Online Curriculum. *Proceedings of the London International Conference on Education (LICE-2012), Curriculum, Research and Development*, 209-212. London, UK.

Franklin, D.J. (2008). Interactive Curriculum Based on Models of Mind & Brain. Brains, Minds, and Media, Vol.3, bmm1418, in: Lorenz S, and Egelhaaf M (Eds.): *Interactive Educational Media for the Neural and Cognitive Sciences*. Brains, Minds & Media.

Franklin, D.J. (2007). NSF Task Force on Educational Neuroscience. Invited participant. Arlington, Virginia. December. Results published in published in K. W. Fischer, U. Goswami and J. Geake (2010) The Future of Educational Neuroscience, *Mind, Brain and Education*, 4, 68-80.

Franklin, D.J. and Grossberg, S. (2008). Cognitive-emotional learning by neocortex, amygdala, and hippocampus: Timing, neurotrophins, amnesia, and consciousness. In

Proceedings of the twelfth international conference on cognitive and neural systems (ICCNS), Boston University, May.

OTHER ACTIVITIES

Educational Publishing & Technology

2005-present

Team Franklin Consulting, LLC, Swampscott, MA (2015-present). Consultant. Provide design, editorial, technology, and management support to various projects. Team Franklin is dedicated to developing high quality business and educational materials for students and professionals. We provide services for print and digital curricula including innovative games that support learning. Clients: Learning One to One Foundation; LearningMate Solutions.

Pearson Education, Boston, MA. (2013-2015) Editorial Director of Secondary Mathematics Product Development. Design, develop, and deliver multi-media secondary mathematics learning solutions to satisfied customers for deployment in print and on multiple digital devices via cloud. Coordinate plans with internal and external groups for visual and learning design, technology, production, materials management, data analytics, and research. Support Agile development based on data from formal prototype testing, mock classroom, field-test, and efficacy research. Structure interactive learning tasks based on research in neuroscience, computer science, mathematics education, and gaming. Design implementation and field-test of next generation assessment and adaptive learning support modules; support data analytics and algorithm testing. Worked with Global Curricula Standards and Scales Project team on international standards alignments and development asset reuse.

Six Red Marbles, Charlestown, MA. (2009-2013) Executive Director of Curriculum and Learning. Design, develop, and deliver scalable, award-winning, digital curriculum to meet state and national standards for K-12 mathematics. Interactive games included those for learning early mathematics, statistics and probability, and STEM (computer science). Design user interfaces and structure learning tasks based on research in neuroscience, computer science, mathematics education, and gaming. Develop authoring tool with automatic alerts to develop and test 200 competency-based, on-line courses for higher education and professional development in various disciplines on LMS. Manage local/remote internal/freelance staff. Provide leadership and hands-on support for instructional design, writing, editorial, development, and management on multiple digital and print projects on behalf of various clients. Prepare bids, grants, and patents.

Boston University, Boston MA. (2005-2009) Director of Curriculum Development, Center for Excellence in Education, Science and Technology, a National Science Foundation Science of Learning Center. Lead teams of graduate students and faculty to develop K-16 inquiry-based print and software materials to study models of mind,

brain and behavior within mainstream science and mathematics curricula. Incorporate research findings in mathematics education and gaming. Ensure compliance with content and process standards set by various professional and government agencies. Design and deliver curriculum development workshops to teachers at all levels; conduct content and program research to improve product. Grant preparation and project reporting.

Business

Fidelity Investments, Boston, MA

1984-2001

- Vice President, Workflow Systems, Fidelity Investments Systems Company
- Vice President of Development, Fidelity Investments & Brokerage Group
- Vice President, Software Engineering Technology, Fidelity Systems Company
- Manager & Director, Development Center, Fidelity Systems Company
- Sr. Programmer/Analyst, Software Development Company
- Programmer/Analyst, Fidelity Retail Systems

Professional Development

Mathematics Education, Teaching, Research

- Web Intelligence and Big Data (Gautam Sroff, TCS Innovation Labs, Dehli).
- Mathematical Thinking (Keith Devlin, Stanford University).
- Innovation By Design, Workshop, Cambridge.
- Responsible Conduct of Research Program/Boston University
- Leadership Program in Discrete Mathematics, Tufts/Rutgers
- Improving Mathematics Instruction (Institute of Teaching/Learning Mathematics)
- Linear Equations and Their Foundations, EduTron
- Research for Better Teaching
- Several courses at various area schools in mathematics and computer science.

Certifications

- Massachusetts Educator Licensure #228127: Primary Field: Secondary Mathematics; Supervisor/Director, Secondary Mathematics
- Project Management Professional